

February 20, 2018

Yong Chen, Changyong Cao and CrIS SDR Team

With contributions from NOAA/STAR, NASA/GSFC, Harris, UW/SSEC, UMBC, UMD/CICS, SDL/USU, MIT/LL, Logistikos, Raytheon







- Algorithm Cal/Val Team Members
- NOAA-20 CrIS SDR Specification
- CrIS SDR Performance
 - Noise NEdN
 - Radiometric Calibration Accuracy
 - Spectral Calibration Accuracy
 - Geolocation Accuracy
- Summary and Path Forward



Cal/Val Team Members

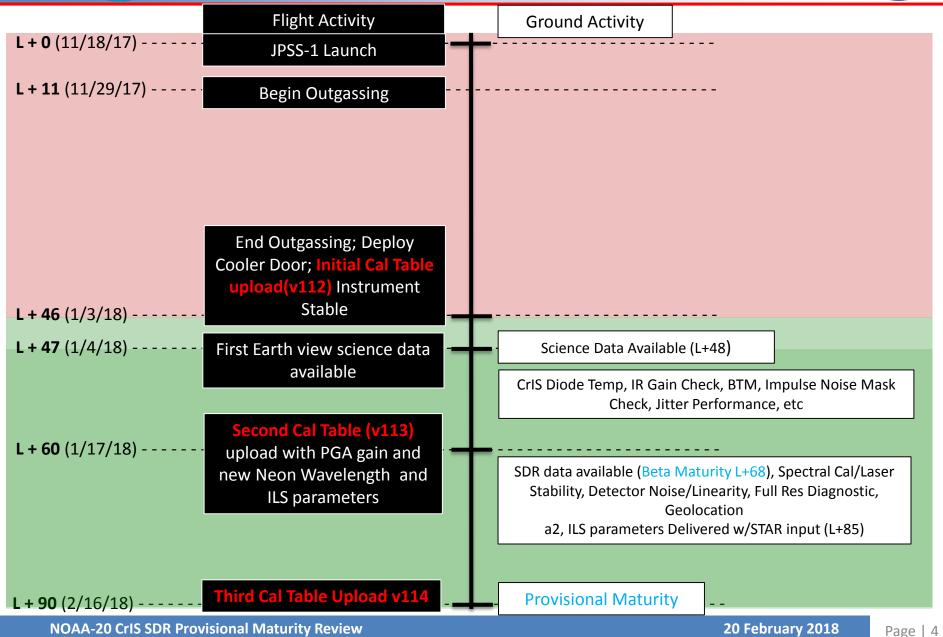


PI	Organization	Major Task		
Changyong Cao (acting)	NOAA/STAR	Project management, SDR team coordination and algorithm test in IDPS, calibration and geolocation science support, inter-comparison, CrIS SDR data quality and monitoring		
Dave Tobin	U. of Wisconsin (UW)	Radiometric calibration, non-linearity coefficients, polarization, inter-comparison, simulation		
Larrabee Strow	U. of Maryland Baltimore County (UMBC)	Spectral calibration, ILS parameters, inter-comparison, simulation		
Deron Scott	Space Dynamic Lab (SDL)	Noise characterization, bit trim and impulse noise mask, anomaly analysis		
Dan Mooney	MIT/LL	Correlated/uncorrelated noise characterization, residual analysis and ringing, simulation		
Dave Johnson	NASA Langley	NASA flight support, instrument science		
Lawrence Suwinski	Harris	PLT tests, on-orbit instrument performance		
Joe Predina	Logistikos	Optimal laser wavelength setting, noise, calibration algorithm		
Deirdre Bolen	JPSS/JAM	DR support		
Wael Ibrahim	Raytheon	IDPS support		

- Big thanks for the dedicated and hard work of each of the contributing organizations
- Team work has been and continues to be exceptional

NOAA-20 CrIS SDR Cal/Val Timeline

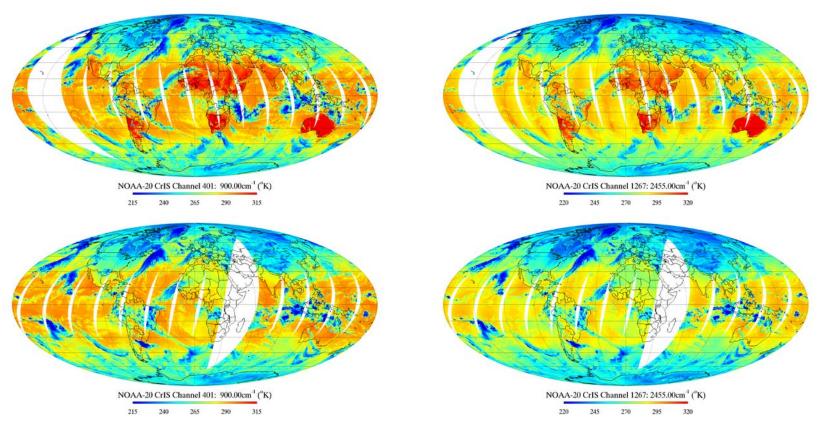






First Light Images on 1/5/2018





- Cooler door opened on 1/3
- First science data produced at 22:08 on 1/4; detectors still cooling
- IDPS immediately produced SDR products suitable for analysis
- End-to-end demonstration that system (Flight + Ground) is working



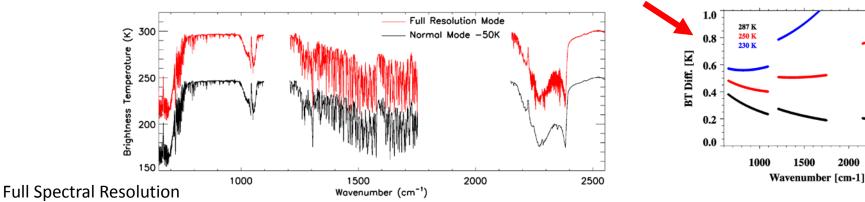
NOAA-20 SDR

Calibration Uncertainty Specifications



Normal Spectral Resolution

Band	Spectral range (cm ⁻¹)	N. of chan.	Resolution (cm ⁻¹)	FORs per Scan	FOVs per FOR	NEdN @287K BB mW/m²/sr/ cm ⁻¹	Radiometric Uncertainty @287K BB (%)	Spectral (chan center) uncertainty ppm	Geolocation uncertainty Km (Nadir)
LW	650-1095	713	0.625	30	9	0.14	0.45	10	1.5
MW	1210-1750	433	1.25	30	9	0.06	0.58	10	1.5
SW	2155-2550	159	2.5	30	9	0.007	0.77	10	1.5



Band	Spectral range (cm ⁻¹)	N. of chan.	Resolution (cm ⁻¹)	FORs per Scan	FOVs per FOR	NEdN @287K BB mW/m²/sr/ cm ⁻¹	Radiometric Uncertainty @287K BB (%)	Spectral (chan center) uncertainty ppm	Geolocation uncertainty Km (Nadir)
LW	650-1095	713	0.625	30	9	0.14	0.45	10	1.5
MW	1210-1750	865	0.625	30	9	0.084	0.58	10	1.5
SW	2155-2550	633	0.625	30	9	0.014	0.77	10	1.5

2000

2500





JPSS/GOES-R Data Product Validation Maturity Stages – COMMON DEFINITIONS (Nominal Mission)

1. <u>Beta</u>

- o Product is minimally validated, and may still contain significant identified and unidentified errors.
- Information/data from validation efforts can be used to make initial qualitative or very limited quantitative assessments regarding product fitness-for-purpose.
- Documentation of product performance and identified product performance anomalies, including recommended remediation strategies, exists.

2. Provisional

- Product performance has been demonstrated through analysis of a large, but still limited (i.e., not necessarily globally or seasonally representative) number of independent measurements obtained from selected locations, time periods, or field campaign efforts.
- o Product analyses are sufficient for qualitative, and limited quantitative, determination of product fitness-for-purpose.
- Documentation of product performance, testing involving product fixes, identified product performance anomalies, including recommended remediation strategies, exists.
- Product is recommended for potential operational use (user decision) and in scientific publications after consulting product status documents.

3. Validated

- Product performance has been demonstrated over a large and wide range of representative conditions (i.e., global, seasonal).
- Comprehensive documentation of product performance exists that includes all known product anomalies and their recommended remediation strategies for a full range of retrieval conditions and severity level.
- Product analyses are sufficient for full qualitative and quantitative determination of product fitness-for-purpose.
- o Product is ready for operational use based on documented validation findings and user feedback.
- Product validation, quality assurance, and algorithm stewardship continue through the lifetime of the instrument.



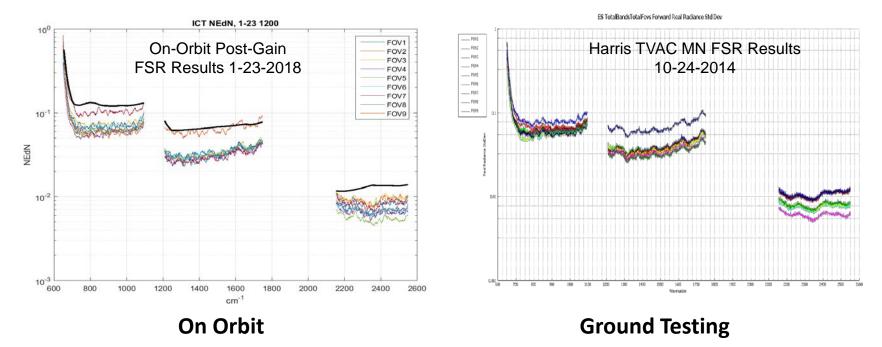


- Major NOAA-20 CrIS SDR performance from Beta Review:
 - NEdN: all FOVs and bands within the specification (except for MW FOV9), comparable well to S-NPP
 - Radiometric uncertainty: within the specification, all channels (except one) are with ±0.2 K with S-NPP (global averaged), showing very good agreement with VIIRS, AIRS, and IASI (less than 0.5 K)
 - Spectral uncertainty: within the specification, FOV 5 absolute spectral shift within 1 ppm, relative shift within 3 ppm for all bands after EngPkt v113
 - Geolocation uncertainty: within the specification, in-track geolocation having up to about 6% FOV size error
- Major CrIS SDR improvements after uploading EngPkt v114
 - Radiometric uncertainty: radiometric FOV2FOV consistency improved for LW and MW bands
 - Spectral uncertainty: spectral offsets for relative and absolute for all three bands are all within ±1ppm
 - Geolocation uncertainty: in-track geolocation accuracy significantly improved after updating mapping angles in v114 relative to VIIRS



NEdN Compares well to 287K ECT TVAC NEdN – Full Spectral Resolution





- Full resolution spectra compared against the NOAA full resolution SDR specification
- Spread in SW is a known result of the algorithm (SA correction) when applied to full resolution spectra
- Pre and Post launch NEdN are consistent
- MW9 NEdN elevated as expected from prelaunch TVAC measurements but within specification
- LW7 NEdN elevated (high noise had been seen once before during EMI test phase)

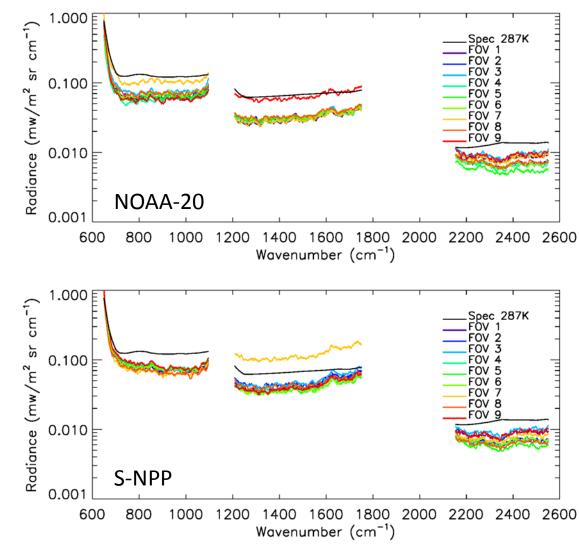


ICT NEdN on

01/21/2018

NOAA-20 NEdN Comparable to S-NPP

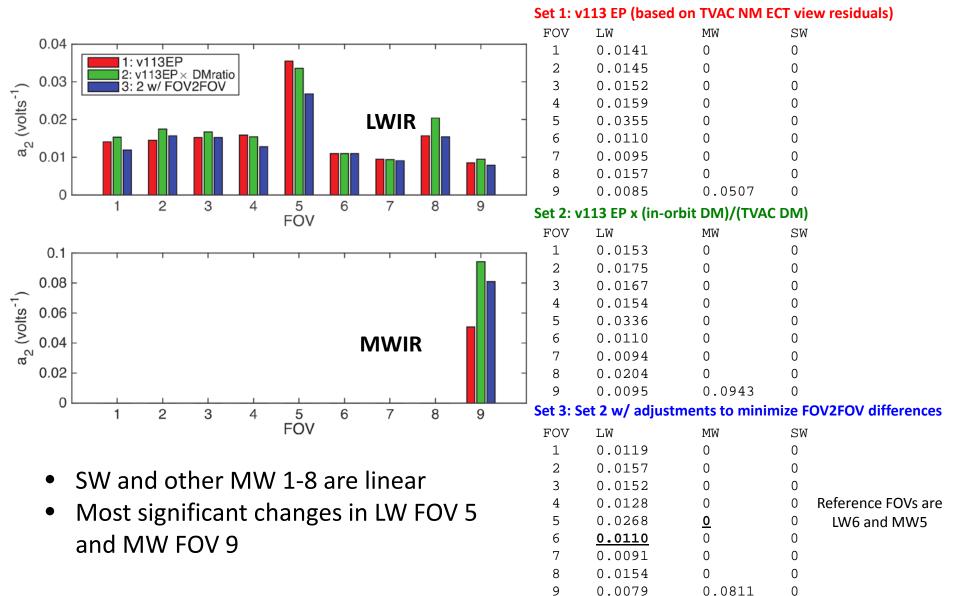




NOAA-20 MW NEdN are better than S-NPP for FOVs 1-8

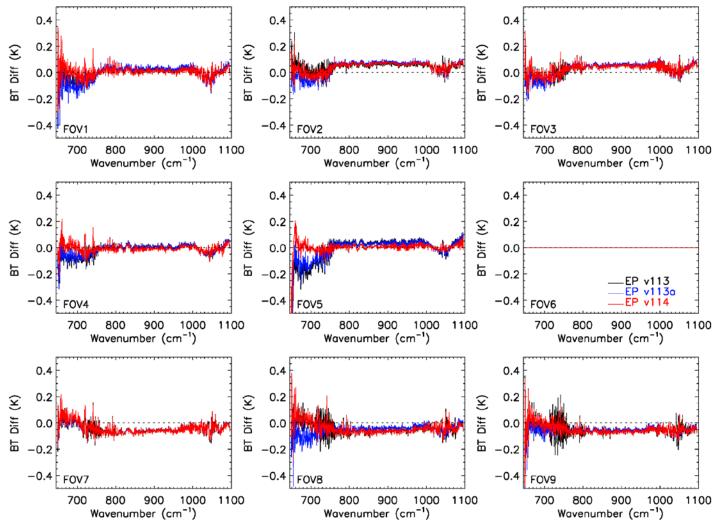
Non-Linearity Coefficients Adjustment





Radiometric FOV2FOV Comparison (LWIR)



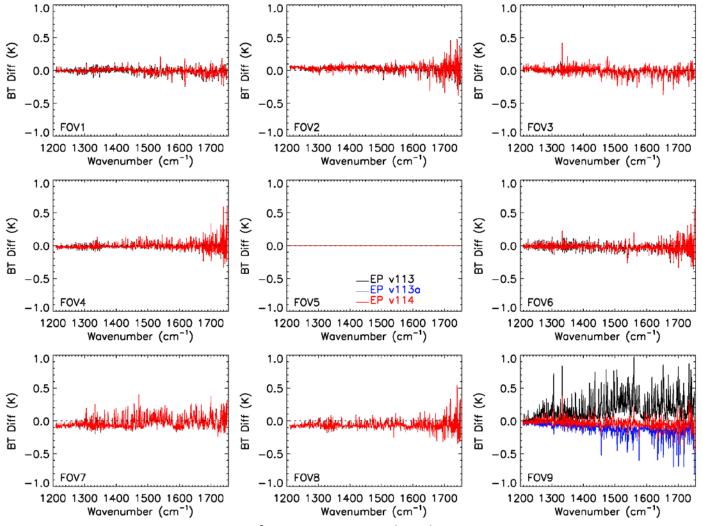


- Using LW FOV 6 as a reference, unapodized mean spectra
- FOV2FOV consistency significantly improved after non-linearity coefficients adjustment in EP v114

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Radiometric FOV2FOV Comparison (MWIR)





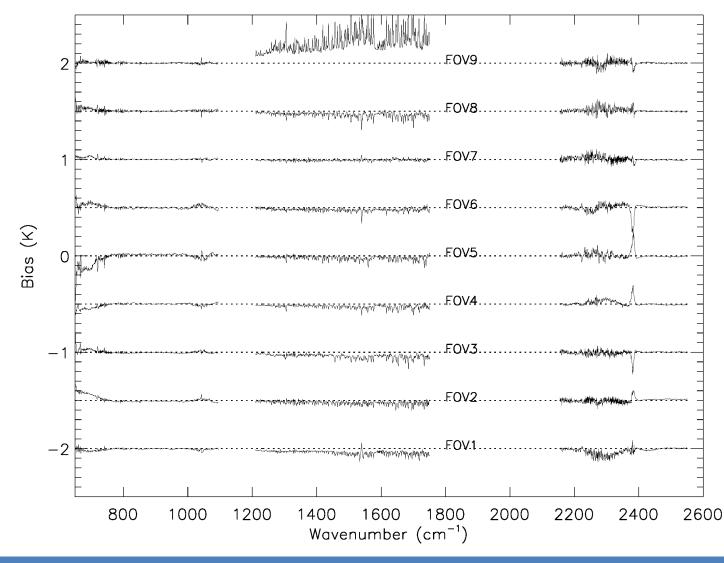
- Using MW FOV 5 as a reference, unapodized mean spectra
- MW FOV 9 non-linearity significantly improved after non-linearity coefficients adjustment in EP v114

NOAA-20 CrIS SDR Provisional Maturity Review

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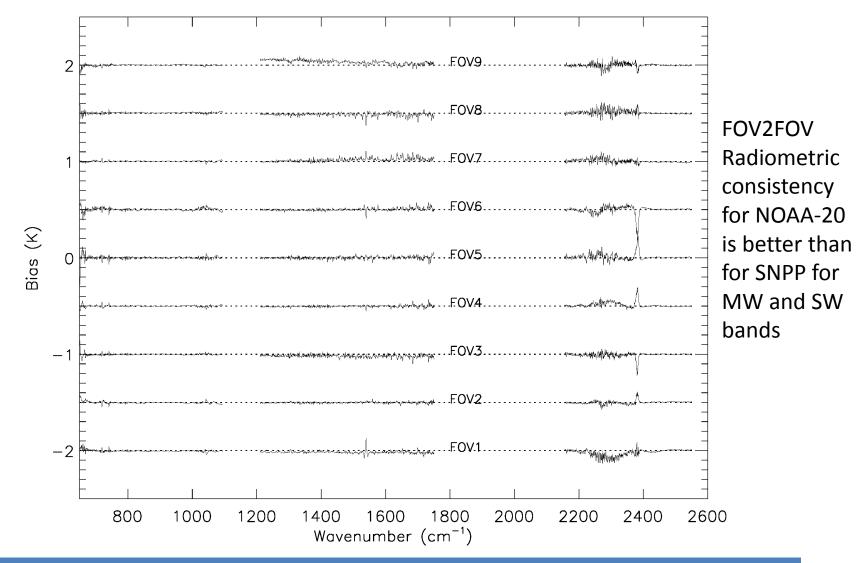


NOAA-20 with EP v113, apodized mean spectra, and removed O-B bias for each FOV



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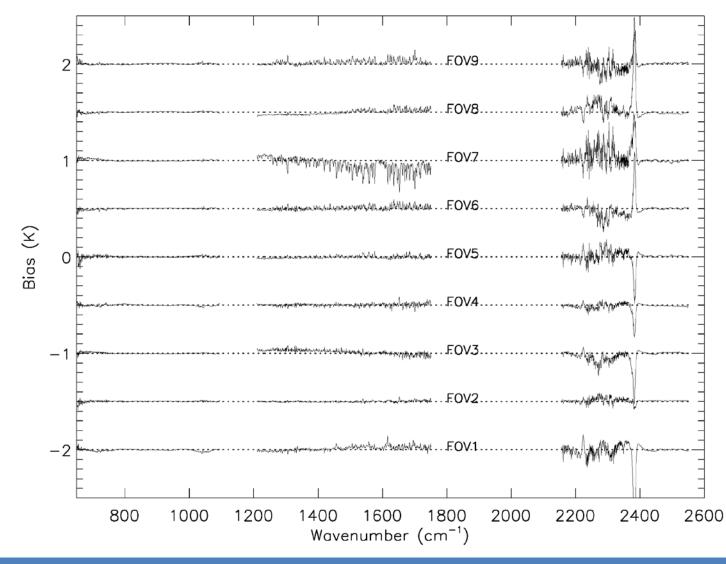
NOAA-20 with EP v114, apodized mean spectra, and removed O-B bias for each FOV



FOV2FOV Radiometric Consistency



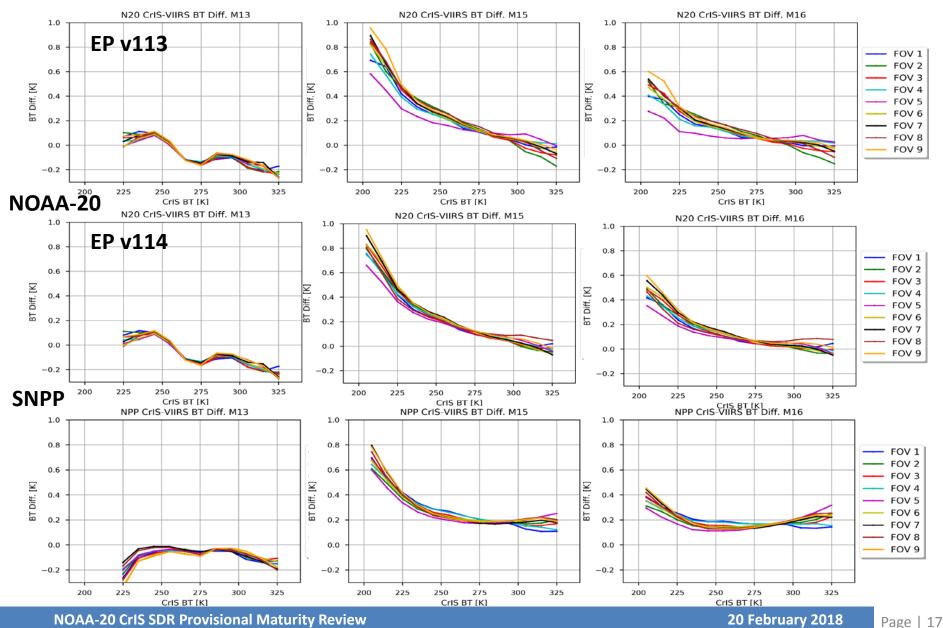
S-NPP, apodized mean spectra, and removed O-B bias for each FOV



FOV2FOV Dependence Relative to VIIRS

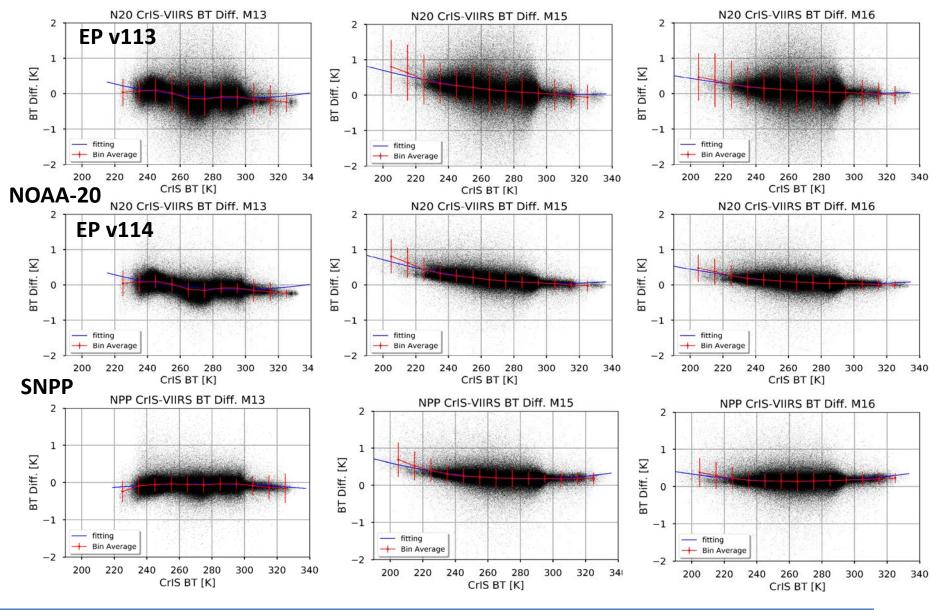
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CrIS-VIIRS BT Difference VS Scene Temperature

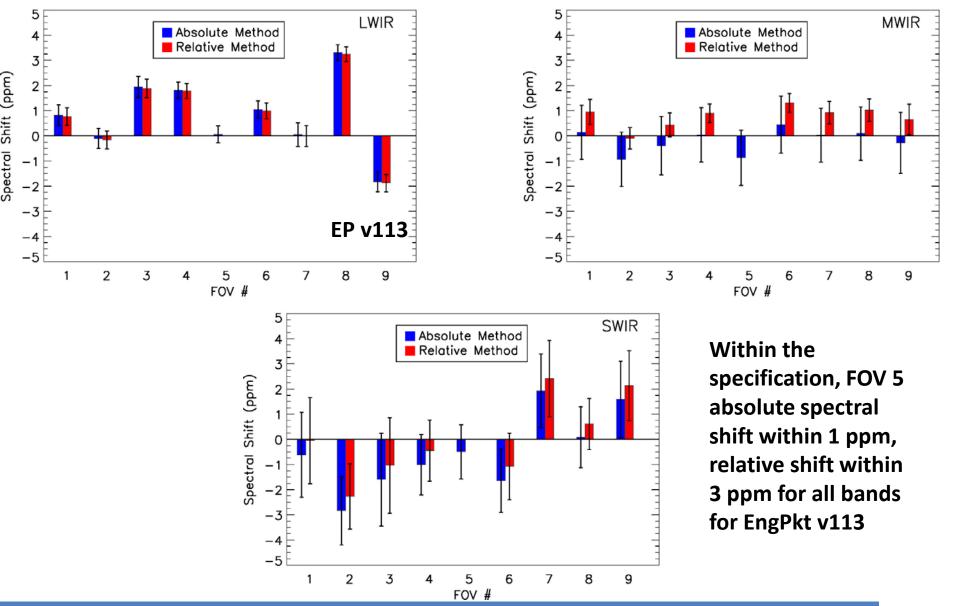




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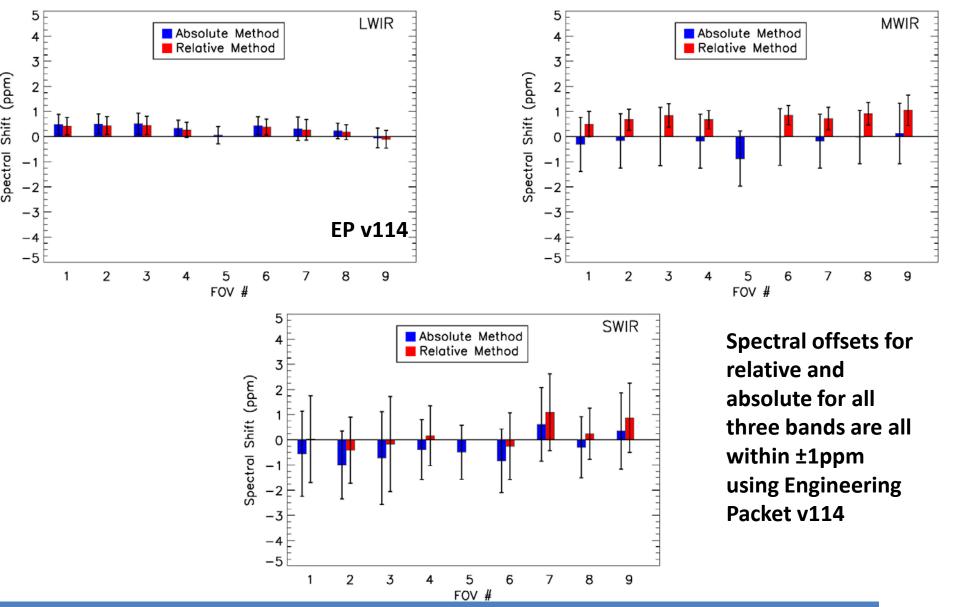
Spectral Accuracy: Relative and Absolute





Spectral Accuracy: Relative and Absolute

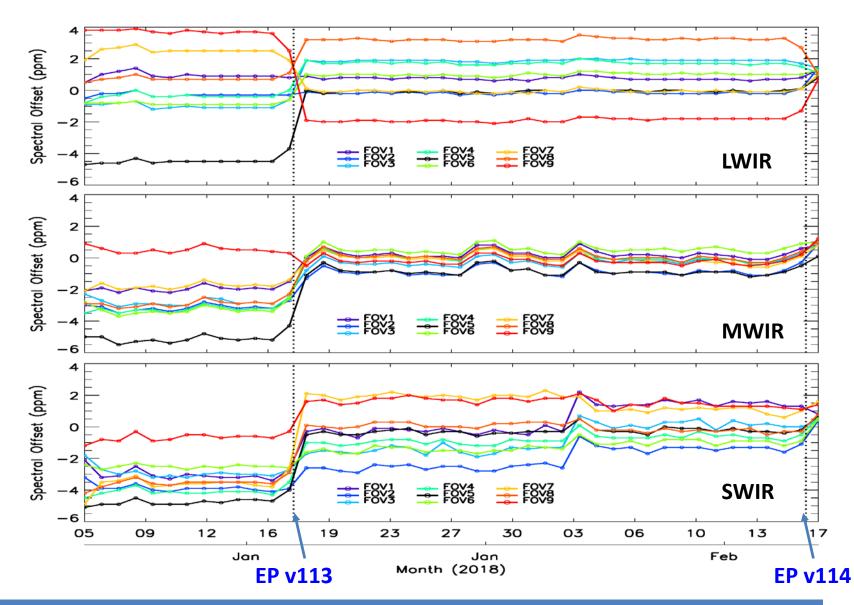






Spectral Accuracy Trending

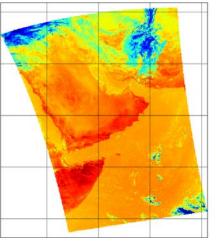


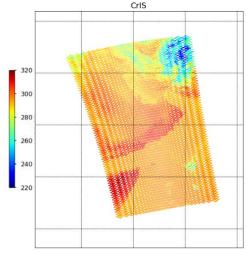


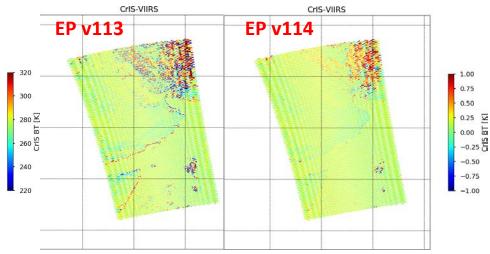


Geolocation Accuracy

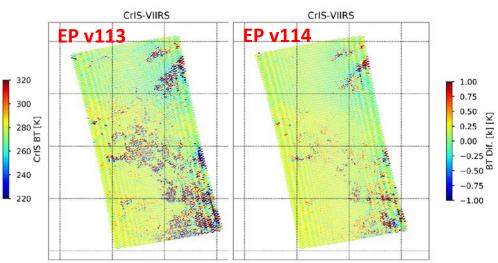




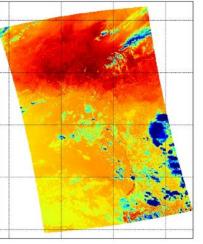


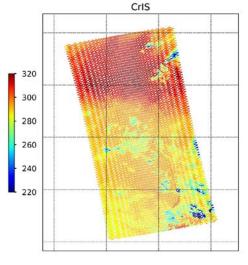


CrIS VIIRS BT Differences for Coastline Case



CrIS VIIRS BT Differences for Cloud Case



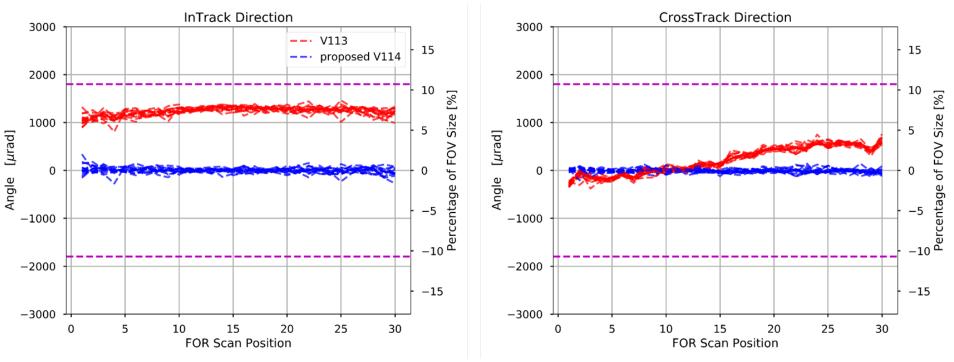


CrIS at 900.0 cm⁻¹

VIIRS M15

In-track and Cross-track Bias





Overall performance for CrIS geolocation for all FOV positions: requirement is 1.5 km at nadir, 11% of FOV diameter for all scan positions:

• EP v113 based on prelaunch characterization, v114 includes launch shifts and postlaunch comparison with VIIRS

nna

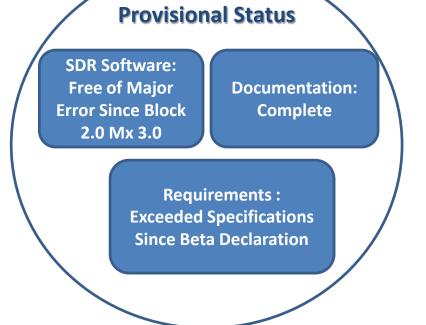
CrIS SDR Reached Provisional Maturity Level



- Requirements
 - Instrument & SDR performances exceeded requirements since Beta status declaration 1/17/2018
- SDR software
 - Stable & free of errors that can impact data quality since 7/28/2017 (Block 2.0 Mx 3.0)
- Documentation
 - 5 presentations in this meeting
 - Peer reviewed Journal papers for S-NPP
 - SDR ATBD
 - SDR User Guide
 - ReadMe for Data Product Users
 - Algorithm Calibration/Validation Plan



Band	NEdN @287K BB mW/m²/sr/cm ⁻¹	Radiometric Uncertainty @287K BB (%)*	Frequency Uncertainty (ppm)	Geolocation Uncertainty (km)
LW	0.10 (0.14)	0.12 (0.45)	2 (10)	0.3 (1.5)
MW	0.04 (0.084)	0.15 (0.58)	2 (10)	0.3 (1.5)
SW	0.01 (0.014)	0.2 (0.77)	<mark>2</mark> (10)	0.3 (1.5)



* Using SNPP radiometric uncertainty here, expect that NOAA-20 has very similar radiometric uncertainty, will provide the uncertainty at the Validated Status

NOAA-20 CrIS SDR Provisional Maturity Review



Summary



- NOAA-20 CrIS SDR data well meet the Provisional Maturity: The CrIS SDR team recommends the NOAA-20 CrIS SDR data for operational use (user decision)
- Major NOAA-20 CrIS SDR performance and improvements after Beta Maturity:
 - NEdN: all FOVs and bands within the specification (except for MW FOV9), comparable well to S-NPP
 - Radiometric uncertainty: radiometric FOV2FOV consistency improved for LW and MW bands (within 0.1 K)
 - Spectral uncertainty: spectral offsets for relative and absolute for all three bands are all within ±1ppm
 - Geolocation uncertainty: in-track geolocation accuracy significantly improved after updating mapping angles in v114 relative to VIIRS
- NOAA-20 CrIS SDR products have been reliably produced by IDPS since detectors first went cold on 01/04/2018. No DR submitted during this period



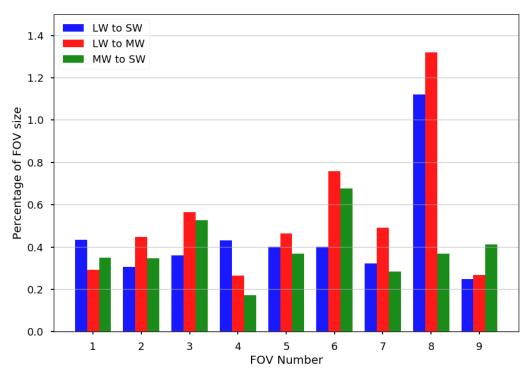


- The CrIS SDR team will continue performing the cal/val tasks with NOAA-20 CrIS towards Validated status milestone by August, 2018
 - Radiometric uncertainty: on-orbit error budget analysis, polarization correction, and inter-comparison with other sensors
 - Spectral uncertainty: only very minor adjustment if demanded
 - Geolocation uncertainty: mapping angles may need to be adjusted depending on the VIIRS geolocation updates
 - SDR algorithm improvements to address the potential issues (e.g. polarization effect correction, lunar intrusion detection)
 - Continuation of SDR software improvements to address the remaining and future issues





- While additional minor tuning will take place during the extended validation campaign, there are no open issues
- One science waiver at launch: MA-04—07
 Chipped LW FOV 8 singlet results in minor outage for band-to-band centroid coregistration and shape matching



Band-to-band performance for EP v114, meets requirement (1.4%)