

JPSS Risk Reduction: Uniform Multi-Sensor Clouds, Aerosols, and Cryosphere Algorithms for Consistent Products Algorithm Readiness Review Dec 15, 2015

Presented By: Walter Wolf¹, Andy Heidinger¹, Mike Pavolonis¹, Jeff Key¹, Shobha Kondragunta¹, Istvan Laszlo¹, Peter Romanov³, Andy Walther⁴, Pat Heck⁴, and Veena Jose⁵ ¹NOAA/NESDIS/STAR ²NOAA/NESDIS/OSPO ³CREST ⁴CIMSS ⁵IMSG



Review Agenda

- Introduction
- Risks & Actions
- Requirements
- Algorithm Readiness
 - » Clouds
 - » Aerosols
 - » Cryosphere
- Software Architecture
- Delivered Algorithm Package
- Risks Summary
- Summary and Conclusions

12:00 pm - 12:15 pm Wolf 12:15 pm - 12:30 pm Wolf 12:30 pm – 1:00 pm Wolf 1:00 pm – 3:00 pm Heidinger/ Pavolonis/ Heck/ Walther Laszlo/ Kondragunta/ **Pavolonis** Key/Yinghui/Xuanji/ Romanov 3:00 pm - 4:30 pm Jose 4:30 pm - 4:45 pm Wolf 4:45 pm - 4:55 pm Wolf 4:55 pm - 5:00 pm Wolf



Outline

- Introduction
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Introduction

Presented by

Walter Wolf



Contents

- Project Objectives
- Stakeholders
- Teams
- Project Plan
- Entry and Exit Criteria



Project Background

- NWS requests continuity of NOAA products between current and future NOAA operational satellites
- Demonstration of cost effective processing for NOAA JPSS products
- Demonstration of NOAA's goal of enterprise solutions by employing same algorithms for "POES" and "GOES"
- Supports NWS OS&T implementation strategy of multi-sensor algorithms and products



Project Background – NDE

- Disseminate JPSS/S-NPP Data Records to customers.
- Generate and disseminate tailored JPSS/S-NPP Data Records (versions of JPSS/S-NPP Data Records in previously agreed alternative formats and views).
- Generate and disseminate NOAA-unique products (augmented environmental products constructed from JPSS/S-NPP Data Records).
- Deliver NOAA-unique products, product processing elements, and associated metadata to CLASS for long-term archiving.
- Provide services to customers, including NDE product training, product enhancement, and implementation support across NOAA.
- Provide software for JPSS/S-NPP Data Record format translation and other data manipulations.



Project Objectives

- Modification of the NOAA Heritage Cloud, Cryosphere, Volcanic Ash, and Aerosol algorithms to work on VIIRS data
- This will bring scientific consistency between the current operational products, GOES-R products and VIIRS products
- Run the product system within NDE 2.0



Products Objectives Cloud Products

- Cloud Mask
- Cloud Top Phase
- Cloud Type
- Cloud Top Height
- Cloud Top Temperature
- Cloud Top Pressure
- Cloud Optical Depth
- Cloud Particle Size Distribution
- Cloud Liquid Water
- Cloud Ice Water Path



Products Objectives Aerosol Products

- Aerosol Detection Smoke & Dust
- Aerosol Optical Depth
- Aerosol Particle Size
- Volcanic Ash Mass Loading
- Volcanic Ash Height



Products Objectives Cryosphere Products

- Ice Concentration and Cover
- Ice Surface Temperature
- Ice Thickness/Age
- Snow Cover
- Fractional Snow Cover Reflectance based & NDSI



JPSS Risk Reduction Integrated Product Team

- IPT Lead: Walter Wolf (STAR)
- IPT Backup Lead: Shuang Qiu (OSPO)
- NESDIS team:
 - » STAR: Andy Heidinger, Jeff Key, Shobha Kondragunta, Istvan Laszlo, Mike Pavolonis, Lihang Zhou
 - » OSPO: A. K. Sharma, Hanjun Ding, Zhaohui Cheng, Chris Sisko, Donna McNamera
 - » OSGS: Tom Schott, Rick Vizbulis, Geof Goodrum
 - » NOAA JPSS: Mitch Goldberg, Arron Layns, Neal Baker
 - » NIC: Sean Helfrich, Pablo Clemente
 - » Data Center: Lei Shi (NCDC)
 - » Others: Peter Romanov (CREST), William Straka III, Ray Garcia, Andi Walther, Pat Heck (CIMSS), Shanna Sampson, John Lindeman, Tianxu Yu, Aiwu Li, Alexander Ken, Hua Xie, Michael Walters, Ruiyue Chen, Valerie Mikles, Veena Jose (IMSG)
- User team
 - » Lead: Kevin Schrab (NWS), Mike Johnson(NWS), John Derber (NWS/NCEP/EMC), Jeff Ator (NWS/NCEP/NCO), Sid Boukabara (JCSDA), Carven Scott (NWS), VAACs
 - » Others: International NWP users, NWP FOs, Climate Users
- POPs involved: EPOP, ICAPOP, CAL/NAVPOP, ACPOP, SURPOP



Project Stakeholders

- OSPO
- STAR
- OSGS
- NOAA National Weather Service
- Department of Defense
- National Ice Center
- Global NWP



Project Plan

- Design and Development (2012 2014)
 - » Develop Requirements Document
 - » Product leads to identify updates to the algorithms to work with VIIRS data
 - » Identify ancillary data for the algorithms
 - » Conduct CDR
 - » Algorithm development
 - » Implement algorithms within the Framework
 - » Conduct UTRR



Project Timeline Design and Development

ID	Task Name		_		2	013				2014				2015
		Qtr 2	Qtr 3	Qtr 4		Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1
1	JPSS Risk Reduction			<u> </u>										-
2	Development Phase			▲ 10/1										4
3	IPT Lead informed to begin product development		10/1	• IV/I										12/9
4	Algorithm Evaluation/Preliminary Development		10/1		1/0					:			-	12/9
5	Initial Archive Requirements identified		10/1		1/9									
6	Quality Monitoring Concept Defined		10/1		1									
7	Long-term Maintenance Concept Defined		10/1		1/16)								
8	Development processing system defined		10/1		1/9	-								
9	Evaluate the modifications required to create VIIRS products from the GC		10/1		12									
10	Initial Information Technology (IT) Security concept defined		10/1		1/16									
11	Requirements Review				1.1	2/10								
12	Preliminary development Aerosol, Cloud, Cryosphere and Volcanic Ash :		10/1			12/28								
13	Identify ancillary data inputs for all the algorithms			1/1 💳		1/23								
14	Preliminary development of infrastructure to implement the NetCDF4 rea		1	1/1 👝		2/13								
15	Critical Design Reviews for Cloud Mask, Phase, Height, and NCOMP al						4/5							
16	Critical Design Review for Cryosphere Ice and Snow Cover						4/18							
17	Critical Design Review for Aerosol, Volcanic Ash, and DCOMP algorith						4/30							
18	Critical Design Review for Fractional Snow Cover													12/9
19	Algorithm Development			1/2	_					1/29				
20	Development of Aerosol, Cloud, Cryosphere and Volcanic Ash algorithm			1/2	2 🗲				1	1/29				
21	Define Aerosol, Cloud, Cryosphere and Volcanic Ash output files			1/2	2 🧲				10/ 3	1				
22	Development of infrastructure to implement the NetCDF4 readers and w				2/1					1/29				
23	Algorithm Implementation/Testing/Demonstration								12/2 造					12/19
24	Begin documentation of the framework								12/2 1	2/2				
25	Implement Cloud Mask, Height, Phase and COMP algorithms into the fra								12/2 🧲	:		9	4	
26	Cloud Mask, Height, Phase and COMP test cases processed								12/2 🧲		4/18		+1	
27	Test Readiness Review for Cloud Mask, Height, Phase and COMP													1/12
28	Deliver preliminary Cloud DAP to NDE												10/	24
29	Implement Aerosol Detection and Aerosol Optical Depth algorithms into								12/2 🧲	:		8/1	$H \rightarrow 1$	
30	Aerosol Detection and Aerosol Optical Depth test case processed								12/2 🧲	:		6/27	╉ <u>┤</u> │	
31	Test Readiness Review for Aerosol Detection and Aerosol Optical Dep												1	1/14
32	Deliver preliminary Aerosol DAP to NDE												1 0/	24
33	Implement Cryosphere algorithms into the framework								12/2 🧲	:		9	45	
34	Cryosphere algorithm test case processed								12/2 🧲	:		8/8		
35	Test Readiness Review for Cryosphere(Ice only) algorithms												6 107	
36	Deliver preliminary Cryosphere(Ice only) DAP to NDE												🍒 10/2	20
37	Implement Snow Cover and Volcanic Ash algorithms into the framework								12/2 🧲	:			10 15	5
38	Snow Cover and Volcanic Ash test case processed								12/2 🧧			(12	
39	Deliver preliminary DAP for Snow Cover and Volcanic Ash Algorithms													12/19
40	Pre-operational Phase												<u>ام</u> ا	-
63	Operational Phase													



Project Plan

- Transition to Pre-Operations (2014 2016)
 - » Deliver initial DAP (Framework with pre-operational algorithms) to NDE
 - » Conduct Software Review
 - » Update algorithms
 - » Transition and test system within the NDE 2.0 environment
 - » Perform test data flows
 - » Conduct Algorithm Readiness Review
 - » Deliver final DAP to SADIE in Dec 2015
 - » Deliver updated DAP to NDE 2.0 in Apr 2016



Project Timeline Transition to Pre-Operations

				Sec. 13		100		- 100	100	11.202	$\sim \sim$		1.1	1.00	1.1			
ID	Task Name			2013				2014				2015				2016		
4	JPSS Risk Reduction	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3
			×															
2	Development Phase		·								<u> </u>	<u>)</u>						
40	Pre-operational Phase										42/24	1/21						
41	Transition Framework to the pre-operational system on the NDE hardware																	
42	NDE/OSPO Contractor Staff Training for the Framework											1/19						
43	Pre-operational product output evaluated & tested within the NDE environme										1/2	: -						
44	Aerosol, Cloud, Cryosphere, and Volcanic Ash algorithms are upgraded										12/22		3/19		-			
45	Software Review for Aerosol, Cloud, Cryosphere (Ice & Snow) and Volcani												0.000		° ∼ -11/	6		
46	Provide test products to the end users											2/23 🦢						
47	Prepare Documentation										12/29			29				
48	Developed Operational Products Implementation Plan										12/22			29				
49	Baseline products system										12/22	2/	27					
50	Evaluated and Modify Operational Documentation										12/22		4/30					
51	Validation and Verification of Operational Quality Assurance for Products										12/22		3/31					
52	Validation and Verification of Monitoring capability for Products										12/22		3/19					
53	All documentation is complete											8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	6/3 🦢			12/15		
54	Final DAP delivered to NDE														- `	12/18	_	
55	Prepare for Transition to Operations										12/22		4/24					
56	Conduct Algorithm Readiness Review for Aerosol, Cloud, Cryosphere and														- *	12/15	_	
57	Operational and backup processing capabilities in place										12/30					12/10		
58	Final IT Security Concept Defined										12/30				11/	11		
59	Deliver updated DAP to NDE2.0																4/2	5
60	Transition DAP to operations															4/	26 🃥	7/8
61	Brief SPSRB Oversight Panel(s) on product status																7/11	7/13
62	Brief SPSRB capability is ready to operational																7/1	4 7/18
63	Operational Phase																	۰. w
64	SPSRB manager and secretaries notified JPSS Risk Reduction NOAA Unic																	left 🔶 🔶
65	SPSRB Secretaries/manager update the SPSRB product metrics web page																7/1	9 🍵 8/1
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Project Plan Schedule

Schedule (Milestones)

- » Project begins 10/05/12
- » Requirements Review 12/27/12 (10/31/12)
- » Critical Design Review (10/31/12)
 - Cloud Mask, Phase, Height, NCOMP 04/05/13
 - Cryosphere Ice and Snow Cover 04/18/13
 - Aerosol, Volcanic Ash, DCOMP 04/30/13
 - Fractional Snow Cover 12/09/14

(cont.)



Project Plan Schedule

Schedule (Milestones) (Cont.)

- » Test Readiness Review 05/06/14 (10/31/13)
 - Ice 10/07/14
 - Clouds 11/12/14
 - Aerosols 11/14/14
- » Algorithm Readiness Review
 - Clouds, Aerosols, Cryosphere 12/15/15 (05/30/14)
- » Software Review 11/06/2015 (02/2014)
- » Operational Readiness Review 07/2016 (12/2015)



JPSS RR ARR Review Objectives

- Review the Project Goals, Stakeholders, Schedule
- Review the Risks and Actions
- Review the Requirements
- Review the Software Architecture
- Review the JPSS RR Product Validation
- Review the Delivered Algorithm Package



JPSS RR ARR Entry Criteria

- JPSS RR CDR Reports
 - » Updated CDR Reports for Cryosphere Snow and Volcanic Ash products
- JPSS RR UTRR Reports
 - » Updated UTRR Presentation for Clouds, Aerosols, and Cryosphere Ice products

JPSS RR Requirements Allocation Document

JPSS RR Review Item Disposition



JPSS RR ARR Exit Criteria

- Algorithm Readiness Review Report
 - » The ARR Report (ARRR), a standard artifact of the SPSRB Process will be compiled after the ARR
 - » The report will contain:
 - Review Item Disposition containing all risks, actions and comments
 - Updated ARR presentation of all RR products



Outline

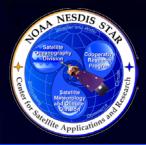
- Introduction
- Risks and Actions
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- Risks Summary
- Summary and Conclusions



Risks and Actions Presented by Walter Wolf



Pre-CDR Risks and Actions



Pre-CDR Risks and Actions

• None





CDR and UTRR Risks and Actions



- TRR Risk 1: The Framework for the VPW algorithm currently uses all M bands as inputs though the algorithms only use 5 of the bands
- Risk Assessment: Medium
- Mitigation:
 - » Update the Framework to only ingest the channels that it needs.
 - » Update the Gap Filling algorithm to only ingest the channels that it needs - Fixed to ingest only the required channels.
- Status: Closure Pending



- TRR Risk 2: Glint information is currently not included within the cloud mask outputs
- Risk Assessment: Medium
- Mitigation:
 - » Cloud Mask algorithm is updated to include Glint information.
- Status: Closure Pending



- TRR Risk 3: Cloud Shadow information is currently not included within the cloud mask outputs
- Risk Assessment: Medium
- Mitigation:
 - » Updated the Cloud height algorithm to include Cloud Shadow information
- Status: Closure Pending



- TRR Risk 4: Determine the hardware to be purchased for the Test and Operational environments – NDE 1.0 hardware vs. NDE 2.0 hardware
- Risk Assessment: High
- Mitigation:
 - » NDE has purchased and installed the NDE 2.0 hardware
- Status: Closure Pending



- TRR Risk 5: Schedule to go operational within NDE
- Risk Assessment: High
- Mitigation:
 - » Work with NDE to determine when the JPSS RR processing system will be transitioned to operations – Current delivery date is December 2015 with an operational date of July 2016 (due to the PDA delay)
- Status: Closure Pending



- TRR Risk 6: Product monitoring metadata variables not defined
- Risk Assessment: Medium
- Mitigation:
 - » Worked with the Product Monitoring and algorithm team to determine the product monitoring metadata that was added for each product
- Status: Closure Pending



- TRR Risk 7: The AOD and ADP algorithms can run but not validated with the Bayesian Cloud Mask
- Risk Assessment: Low
- Mitigation:
 - » Repeat validation efforts when the required Glint Mask and Fire mask bits are available in the Bayesian Cloud Mask -AOD and ADP algorithms are validated with Bayesian Cloud mask
- Status: Closure Pending



- TRR Risk 8: PFAAST is the RTM used for Cloud product validation
- Risk Assessment: Low
- Mitigation:
 - » Cloud Mask, Height, Phase, NCOMP and DCOMP products are validated using the CRTM
- Status: Closure Pending



- TRR Risk 9: NCOMP can run but not validated with the Bayesian Cloud Mask
- Risk Assessment: Low
- Mitigation:
 - » NCOMP is validated using Bayesian Cloud Mask
- Status: Closure Pending



- TRR Risk 10: NIC may request a requirement change for Ice Concentration to be output in percentage (0-100%)
- Risk Assessment: Low
- Mitigation:
 - » Ice Concentration is output in percentage as per the requirement update after TRR.
- Status: Closure Pending



- TRR Risk 11: STAR does not have an agreement to receive JPSS RR products from PDA.
- Risk Assessment: Medium
- Mitigation:
 - » JPSS RR data is on the list of data for STAR to receive from PDA
- Status: Closure Pending



- TRR Risk 14: Suggest identifying ancillary data and primary input data requirements separately.
- Risk Assessment: Medium
- Mitigation:
 - » Added sub-bullets to identify the type of ancillary data.
- Status: Closure Pending



- TRR Risk 15: The Cloud algorithms Height, NCOMP and DCOMP- can run but not validated with the RR Cloud Phase algorithm
- Risk Assessment: Low
- Mitigation:
 - » The Height, NCOMP and DCOMP algorithms are validated with the RR Cloud Phase algorithm, for ARR product validation
- Status: Closure Pending



- TRR Risk 16: Uncertainty in aerosol model selection over land by the AOT algorithm results in large uncertainty in APSP retrieval over land
- Risk Assessment: High
- Mitigation:
 - » The requirements for APSP over land has been dropped; the JERD Vol. 2 says it is only over ocean
- Status: Closure Pending



- TRR Risk 17: The Planck functions used in Framework and CLAVR-x differ
- Risk Assessment: Low
- Mitigation:
 - » The difference has been Fixed with updated LUTs for VIIRS
- Status: Closure Pending



- CDR Risk 1: Algorithm has been developed and tested with the current VIIRS operational cloud mask. Algorithm will need tuning when the NOAA unique cloud mask is used
- Risk Assessment: Medium

• Mitigation:

- » Start testing and evaluating the new cloud mask as soon as it is available - Algorithm has been validated using the NOAA unique cloud mask
- Status: Closure Pending



- CDR Risk 2: Persistent cloud cover and false cloud detection in the polar regions
- Risk Assessment: Medium

• Mitigation:

- » Work closely with the cloud team to ensure accurate cloud classification
- » Use alternate source of snow/ice information (GFS, IMS, Global Snow & Ice Mapping System) to flag persistent clouds – Algorithm meets requirements, but will continue to work with the cloud mask team on issues with cloud detection in the polar regions
- Status: Closure Pending



- CDR Risk 3: Lack of truth data for ice concentration and cover validation
- Risk Assessment: Medium
- Mitigation:
 - » Sufficient "truth" data is now available in a robust collection of Landsat data. Also some very high resolution Digital Globe imagery to validate sea ice concentration
- Status: Closure Pending



- CDR Risk 7: In summer AMSR-E products not good to compare with
- Risk Assessment: Low
- Mitigation:
 - » Sufficient "truth" data is now available in a robust collection of Landsat data.
- Status: Closure Pending



- CDR Risk 8: Use SAR imagery to validate ice types and age
- Risk Assessment: Low
- Mitigation:
 - » Working on getting SAR imagery
 - » Algorithm does meet the requirements
 - » Will perform more validation when SAR data is acquired
- Status: Open



- CDR Risk 9: Add NIC and NCEP requirements for the ice products
- Risk Assessment: Medium
- Mitigation:
 - » Work with NIC and NCEP to establish user requirements. NIC is currently evaluating the JPSS L1RD requirements according to their expectations.
 - » NIC accepts the requirements as listed.
- Status: Closure Pending



- CDR Risk 10: UTRR will be skipped for Snow Fraction
- Risk Assessment: Medium
- Mitigation:
 - » Carried out extensive algorithm testing.
 - » Algorithm timing and accuracy information is provided in the ARR presentation
- Status: Closure Pending



- CDR Risk 11: Work toward the implementation of an Enterprise Fractional Snow Cover Algorithm
- Risk Assessment: High

• Mitigation:

- » Evaluate the three Fractional Snow Cover Algorithms (NDSI, Reflectance based, and MODSCAG) to determine an enterprise Fractional Snow Cover algorithm.
- » Work may have to wait until GOES-R is launched.
- » Resulting enterprise algorithm may be one of the three algorithms or a combination of the three.
- Status: Closure Pending -- Transferred to the Cryosphere Algorithm Team



- CDR Risk 12: Evaluate Fractional Snow Cover Requirement to maybe have requirement for a product under partially clear and partially cloudy conditions
- Risk Assessment: Medium
- Mitigation:
 - » Snow fraction retrievals in the optical spectral range are hardly possible under partially cloudy/partially cloudy conditions, so there is not much sense in performing these retrievals.
- Status: Closure Pending



Aerosols CDR Risks and Actions

- CDR Risk 1: Smoke detection over bright surface not optimized
- Risk Assessment: Medium
- Mitigation:
 - » Conduct additional testing and fine tune the algorithm as needed to smoke over land - Currently, flagging the bright pixels and allowing the aerosol detection to be of low quality.
- Status: Closure Pending



Aerosols CDR Risks and Actions

- CDR Risk 2: Dust detection over bright surface not optimized
- Risk Assessment: Medium
- Mitigation:
 - » Conduct additional testing and fine tune the algorithm as needed to smoke over land
 - » Conduct additional testing and fine tune the algorithm as needed to rescue detection of thick dust or smoke over sunglint region - Currently, flagging the bright pixels and allowing the aerosol detection to be of low quality.
- Status: Closure Pending



Aerosols CDR Risks and Actions

- CDR Risk 5: Aerosol model selection may be inadequate for episodic events
- Risk Assessment: Medium
- Mitigation:

» Identify episodic dust events using deep-blue channels, or input from dust detection, and force algorithm to use dust model - since we have implemented the first resolution, that is an initial version of internal tests for detecting heavy aerosol (dust). But this has not been thoroughly evaluated

• Status: Closure Pending



- CDR Risk 3: Will the data be CF compliant?
- Risk Assessment: Low
- Mitigation:
 - » Yes, the NetCDF4 files are CF compliant
- Status: Closure Pending



- CDR Risk 7: Are the SDRs terrain-corrected? Identify the team is responsible for terrain-corrected SDRs.
- Risk Assessment: High
- Mitigation:
 - » Will ensure that SDRs used are terrain-corrected. Will identify the team responsible for terrain-correction
 - » SDRs used are terrain corrected
 - » VIIRS SDR team is responsible for the terrain-corrected SDRs
- Status: Closure Pending



 CDR Review Item 8: Latency is defined as the interval from the last observation to when the product is available to users. The definition of latency is challenging in the scope of this review. Latency is measured at a system level and includes contributors outside of STAR control.

• Mitigation:

- » Latency has been redefined as processing time allocated to product generation. This plus NDE DHS and PDA system latency will not exceed required latency allocated to ESPC.
- Status: Closure Pending



- CDR Review Item 9: Source for Ground trim data
- Mitigation:
 - » Identify the source for ground trim data.
 - » VIIRS SDR team is the source of the ground trim data
- Status: Closure Pending



ARR Overall Risks and Actions

- ARR Risk 1: Address the mandatory code updates cited in OSPO Software Review, for Dec2015 DAP
- Risk Assessment: Low
- Mitigation:
 - » All 'mandatory updates' (color coded in Orange in the checklist) for Dec 2015 DAP are addressed.
- Status: Closure Pending



ARR Overall Risks and Actions

- ARR Risk 2: Address the recommended code updates for final DAP, as cited in OSPO Software Review
- Risk Assessment: Low
- Mitigation:
 - » Address remaining 'recommended updates' for final DAP in Apr 2016
- Status: Open



ARR Overall Risks and Actions

- ARR Risk 3: The product monitoring metadata variables for DCOMP algorithm will undergo revision.
- Risk Assessment: Medium
- Mitigation:
 - » Fine tune DCOMP metadata variables
 - » Update OSPO product monitoring team about the changes.
- Status: Open



Risk and Actions Summary

 There are currently 31 risks and 3 review items identified from the CDR

Three remain open



Outline

- Introduction
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Requirements for JPSS Risk Reduction: Uniform Multi-Sensor Algorithms for Consistent Products

Presented by Walter Wolf



JPSS Risk Reduction System Requirements

- All JPSS Risk Reduction System Project requirements are present in this section
- All JPSS Risk Reduction System Project requirements are documented in a single RAD and are part of the CDR documentation suite
- Basic requirements are shown in all yellow text on a single slide
- Requirement changes since TRR are marked in orange



JPSS Risk Reduction Requirements Information

- The JPSS Risk Reduction Products are addressing L1RD Supplement requirements
- The JPSS Risk Reduction Products are addressing SPSRB requirements
- The Products created from this project will at least meet the associated product requirements within the L1RD Supplement
- The RAD traces the Risk Reduction products to the L1RD Supplement requirements

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- JPSS-PS-R 0.0: The JPSS Risk Reduction Product System (JPSS RRPS) development project shall adopt the standard practices of the Satellite Product and Services Review Board (SPSRB).
 - » Driver: STAR Enterprise Product Lifecycle (EPL). The SPSRB process has been updated by incorporating aspects of the STAR EPL Process.



- JPSS-PS-R 0.1: The JPSS RRPS development project practices shall be tailored from the SPSRB process.
 - » This requirement should be met by following the SPSRB process, as long as the tailoring does not introduce an incompatibility.



- JPSS-PS-R 1.0: The JPSS RRPS shall generate Global Cloud products.
 - » **Driver:** SPSRB requirements:
 - 1107-0011: Gridded Cloud Products for NWP Verification
 - 0909-0018: CLAVR-x and GSIP cloud product composites over Alaska



• JPSS-PS-R 1.1: The Cloud products shall include Cloud Mask Product.

» Current operational products, with upgraded capabilities.

Current operational products, with upgraded capabilities



- JPSS-PS-R 1.1.1: The Cloud Mask Product shall have JPSS 3 priority.
- JPSS-PS-R 1.1.2: The Cloud Mask Product shall have global coverage.
- JPSS-PS-R 1.1.3: The Cloud Mask Product shall have Vertical Reporting Interval of N/A.
- JPSS-PS-R 1.1.4: The Cloud Mask Product shall have Horizontal Cell Size of 0.75 km.
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 1.1.5: The Cloud Mask Product shall have Mapping Uncertainty, 3 Sigma: threshold - 4 km; objective - 1 km.
- JPSS-PS-R 1.1.6: The Cloud Mask Product shall have Measurement Range of Cloudy/Not Cloudy.





- JPSS-PS-R 1.1.7: The Cloud Mask Product shall have Measurement Accuracy of 90% 87% correct detection, globally.
 - » Ocean, Day 92%
 - » Ocean, Night 90%
 - » Snow-free Land, Day 90%
 - » Snow-free Land, Night 88%
 - » Desert, Day/Night 85%
 - » Snow –covered Land, Day 88%
 - » Snow –covered Land, Night 85%
 - » Sea-ice, Day 82%
 - » Sea-ice, Night 72%
 - » Antarctica & Greenland, Day 80%
 - » Antarctica & Greenland, Night 70%
- Current operational products, with upgraded capabilities



- JPSS-PS-R 1.1.8: The Cloud Mask Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average)
 - » Objective 4 hrs
- JPSS-PS-R 1.1.9: The Cloud Mask Product False Alarm Rate shall be:
 - » <u>1. Ocean, Day, COT>1.0-5</u>%
 - * 2. Land, Day, ToC NDVI < 0.2 or ToC NDVI > 0.4,
 - <u>or Desert, COT > 1.0 7%</u>
 - » 3. Land, Ocean, Night, COT>1.0-8%
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 1.1.10: The Cloud Mask Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.
- JPSS-PS-R 1.1.11: The Cloud Mask Product shall have timeliness of ≤ 3 hours.



- JPSS-PS-R 1.1.12: The applicable conditions for Cloud Mask Product shall be: whenever detectable clouds are present.
- JPSS-PS-R 1.1.13: The Cloud Mask Product shall be computed and reported for the total cloud cover.





- JPSS-PS-R 1.1.14: The JPSS RR Cloud Mask shall use the VIIRS calibrated and navigated brightness temperature and radiances in bands M12, M13, M14, M15, M16 and reflectance in bands M5, M7, M9, M10 with solar and satellite view angles as an input data set.
 Primary Input
- JPSS-PS-R 1.1.15: The JPSS RR Cloud Mask shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 Static Ancillary input
- JPSS-PS-R 1.1.16: The JPSS RR Cloud Mask shall use Digital Surface Elevation at 1km resolution as an input data set.
 Static Ancillary input



• JPSS-PS-R 1.1.17: The JPSS RR Cloud Mask shall use Snow Mask by the Interactive Multi-sensor Snow and Ice Mapping System as an input data set.

Dynamic Ancillary Input

JPSS-PS-R 1.1.18: The JPSS RR Cloud Mask shall use calculated Desert Mask as an input data set.
 Ancillary Input – framework internal computation

 JPSS-PS-R 1.1.19: The JPSS RR Cloud Mask shall use Coast Mask as an input data set.
 Static Ancillary Input



• JPSS-PS-R 1.1.20: The JPSS RR Cloud Mask shall use MODIS monthly mean IR Land Surface Emissivity for channel M7 as an input data set.

Static Ancillary input

• JPSS-PS-R 1.1.21: The JPSS RR Cloud Mask shall use CRTM Clear sky radiance/BT for bands M7, M14 and blackbody radiance for channel M14 and atmospheric transmittance profiles for channel M7 as an input data set.

Dynamic Ancillary input – framework internal computation

 JPSS-PS-R 1.1.22: The JPSS RR Cloud Mask shall use Surface, Tropopause Level and Surface Temperature from GFS model as an input data set.
 Oynamic Ancillary Input



• JPSS-PS-R 1.2: The Cloud products shall include Cloud Top Phase Product.



- JPSS-PS-R 1.2.1: The Cloud Top Phase Product shall have global coverage.
- JPSS-PS-R 1.2.2: The Cloud Top Phase Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.2.3: The Cloud Top Phase Product shall have Measurement Accuracy of 80% Correct Classification (7 phases).



- JPSS-PS-R 1.2.4: The Cloud Top Phase Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average);
 - » Objective 4 hrs;



- JPSS-PS-R 1.2.5: The Cloud Top Phase Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.
- JPSS-PS-R 1.2.6: The Cloud Top Phase Product shall have timeliness of ≤ 3 hours.



- JPSS-PS-R 1.2.7: The JPSS RR Cloud Top Phase shall use the VIIRS calibrated and navigated brightness temperature in bands M14, M15, M16 as an input data set.
 - » Primary Input data
- JPSS-PS-R 1.2.8: The JPSS RR Cloud Top Phase shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.2.9: The JPSS RR Cloud Top Phase shall use Digital Surface Elevation at 1km resolution as an input data set.
 » Static Ancillary Input



- JPSS-PS-R 1.2.10: The JPSS RR Cloud Top Phase shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.2.11: The JPSS RR Cloud Top Phase shall use calculated Coast Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.2.12: The JPSS RR Cloud Top Phase shall use CRTM Clear sky radiance and transmittance for bands 14, 15, 16 TOA radiance bands 14, 15, 16 as an input data set.
 - » Dynamic Ancillary Input framework internal computation



- JPSS-PS-R 1.2.13: The JPSS RR Cloud Top Phase shall use Temperature, Pressure, Height profiles, Surface Level, Tropopause Level, and Surface Temperature from GFS model as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.2.14: The JPSS RR Cloud Top Phase shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » RR VIIRS Derived Product Input



• JPSS-PS-R 1.3: The Cloud products shall include Cloud Type Product.



JPSS-PS-R 1.3.1: The Cloud Type Product shall have global coverage.

• JPSS-PS-R 1.3.2: The Cloud Type Product shall have Horizontal Cell Size of 0.75 km.

• JPSS-PS-R 1.3.3: The Cloud Type Product shall have Measurement Accuracy of 60%.



- JPSS-PS-R 1.3.4: The Cloud Type Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average)
 - » Objective 4 hrs



- JPSS-PS-R 1.3.5: The Cloud Type Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as processing time allocated to product generation. Current capability is 60 minutes.
- JPSS-PS-R 1.3.6: The Cloud Type Product shall have timeliness of ≤ 3 hours.



- JPSS-PS-R 1.3.7: The JPSS RR Cloud Type shall use the VIIRS calibrated and navigated brightness temperature in bands M14, M15, M16 as an input data set.
 - » Primary Input data
- JPSS-PS-R 1.3.8: The JPSS RR Cloud Type shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 » Static Ancillary Input
- JPSS-PS-R 1.3.9: The JPSS RR Cloud Type shall use Digital Surface Elevation at 1km resolution as an input data set.
 » Static Ancillary Input



- JPSS-PS-R 1.3.10: The JPSS RR Cloud Type shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.3.11: The JPSS RR Cloud Type shall use Coast Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.3.12: The JPSS RR Cloud Type shall use CRTM Clear sky radiance and transmittance for bands 14, 15, 16 TOA radiance bands 14, 15, 16 as an input data set.

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» Dynamic Ancillary Input – framework internal computation



- JPSS-PS-R 1.3.13: The JPSS RR Cloud Type shall use Temperature, Pressure, Height profiles, Surface Level, Tropopause Level, and Surface Temperature from GFS model as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.3.14: The JPSS RR Cloud Type shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » RR VIIRS Derived Product as Input



• JPSS-PS-R 1.4: The Cloud products shall include Cloud Top Height Product.





- JPSS-PS-R 1.4.1: The Cloud Top Height Product shall have priority of JPSS 3.
- JPSS-PS-R 1.4.2: The Cloud Top Height Product shall have global coverage.
- JPSS-PS-R 1.4.3: The Cloud Top Height Product shall have Vertical Reporting Interval:
 - » Threshold Tops of up to three cloud layers (1); applicable to single layered clouds only
 - » Objective Tops of all distinct cloud layers
 - » Threshold Tops of highest cloud in column
 - » Objective Tops of multiple clouds in column
 - Current operational products, with upgraded capabilities



• JPSS-PS-R 1.4.4: The Cloud Top Height Product shall have Horizontal Cell Size of 0.75 km.

 JPSS-PS-R 1.4.5: The Cloud Top Height Product shall have Mapping Uncertainty, 3 Sigma:

- » Threshold 4 km
- » Objective 1 km.

 JPSS-PS-R 1.4.6: The Cloud Top Height Product shall have Measurement Accuracy of 500m for Clouds with emissivity > 0.8.
 » Threshold: 1 km for COT ≥ 1 and 2 km for COT < 1
 » Objective: 0.3 km for COT ≥ 1 and 0.3 km for COT < 1



- JPSS-PS-R 1.4.7: The Cloud Top Height Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average)
 - » Objective 4 hrs
- JPSS-PS-R 1.4.8: The Cloud Top Height Product Measurement Precision shall be:
 - » Threshold 1. COT ≥1 1.0 km; 2. COT < 1 2.0 km;
 - » Objective –1. COT ≥ 1 0.15 km; 2. COT < 1 0.15 km;



- JPSS-PS-R 1.4.9: The Cloud Top Height Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

• JPSS-PS-R 1.4.10: The Cloud Top Height Product shall have timeliness of ≤ 3 hours.



• JPSS-PS-R 1.4.11: The requirements for the Cloud Top Height Product shall apply whenever detectable clouds are present.





• JPSS-PS-R 1.4.12: The JPSS RR Cloud Top Height shall use the VIIRS calibrated and navigated brightness temperature and radiance in bands M14, M15, M16 with solar and satellite view angles as an input data set.

» Primary Input Data

 JPSS-PS-R 1.4.13: The JPSS RR Cloud Top Height shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 » Static Ancillary Input

• JPSS-PS-R 1.4.14: The JPSS RR Cloud Top Height shall use Digital Surface Elevation at 1km resolution as an input data set.

» Static Ancillary Input



- JPSS-PS-R 1.4.15: The JPSS RR Cloud Top Height shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.4.16: The JPSS RR Cloud Top Height shall use CRTM Clear sky radiance and transmittance for channels 14, 15, 16 and radiance profiles for channels 14, 15, 16 as an input data set.
 » Dynamic Ancillary Input – framework internal computation



- JPSS-PS-R 1.4.17: The JPSS RR Cloud Top Height shall use Temperature, Pressure, Height profiles, Surface Level and Tropopause Temperature from GFS model as an input data set.
 » Dynamic Ancillary Input
- JPSS-PS-R 1.4.18: The JPSS RR Cloud Top Height shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS Derived RR Product Input
- JPSS-PS-R 1.4.19: The JPSS RR Cloud Top Height shall use Cloud type produced by JPSS RR cloud type algorithm as an input data set.
 - » VIIRS Derived RR Product Input



JPSS-PS-R 1.5: The Cloud products shall include Cloud Cover/Layers Products.



• JPSS-PS-R 1.5.1: The Cloud Cover/Layers Products shall have priority of JPSS 3.

JPSS-PS-R 1.5.2: The Cloud Cover/Layers Products shall have global coverage.

 JPSS-PS-R 1.5.3: The Cloud Cover/Layers Products shall have Vertical Reporting Interval:
 » Threshold -Up to three cloud layers
 » Objective - 0.1 km



 JPSS-PS-R 1.5.4: The Cloud Cover/Layers Products shall have Horizontal Cell Size of 0.75 km.

• JPSS-PS-R 1.5.5: The Cloud Cover/Layers Products shall have Mapping Uncertainty, 3 Sigma:

» Threshold - 4 km

» Objective - 1 km

 JPSS-PS-R 1.5.6: The Cloud Cover/Layers Products shall have Measurement Range (Applies only to total cloud cover; Not applicable — to layers):

» Threshold - 0 to 1.0 HCS Area; Objective - 0 to 1.0



JPSS-PS-R 1.5.7: The Cloud Cover/Layers Products shall have Measurement Accuracy of 80% Correct Classification (Low, Mid, High).

JPSS-PS-R 1.5.8: The Cloud Cover/Layers Products Refresh

- Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average)
 - » Objective 4 hrs



 JPSS-PS-R 1.5.9: The Cloud Cover/Layers Products shall have latency of 30 minutes after granule data is available.

» Latency is defined as processing time allocated to product generation. Current capability is 60 minutes.

 JPSS-PS-R 1.5.10: The Cloud Cover/Layers Products shall have timeliness of ≤ 3 hours.



JPSS-PS-R 1.5.11: The requirements for the Cloud Cover/Layers
 Products shall apply whenever detectable clouds are present.

 JPSS-PS-R 1.5.12: The Cloud Cover Product shall be computed and reported at each separate, distinct layer, as well as for the total cloud cover.



 JPSS-PS-R 1.5.13: The JPSS RR Cloud Cover/Layers shall use the VIIRS calibrated and navigated brightness temperature and radiance in bands M14, M15, M16 with solar and satellite view angles as an input data set.

 JPSS-PS-R 1.5.14: The JPSS RR Cloud Cover/Layers shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.

 JPSS-PS-R 1.5.15: The JPSS RR Cloud Cover/Layers shall use Digital Surface Elevation at 1km resolution as an input data set.

 JPSS-PS-R 1.5.16: The JPSS RR Cloud Cover/Layers shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.



 JPSS-PS-R 1.5.17: The JPSS RR Cloud Cover/Layers shall use CRTM Clear sky radiance and transmittance for channels 14, 15, 16 and radiance profiles for channels 14, 15, 16 as an input data set.

 JPSS-PS-R 1.5.18: The JPSS RR Cloud Cover/Layers shall use Temperature, Pressure, Height profiles, Surface Level and Tropopause Temperature from GFS model as an input data set.

 JPSS-PS-R 1.5.19: The JPSS RR Cloud Cover/Layers shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.

 JPSS-PS-R 1.5.20: The JPSS RR Cloud Cover/Layers shall use Cloud type produced by JPSS RR cloud type algorithm as an input data set.



• JPSS-PS-R 1.6: The Cloud products shall include Cloud Top Temperature Product.

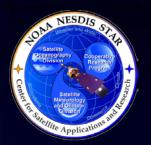


- JPSS-PS-R 1.6.1: The Cloud Top Temperature Product shall have priority of JPSS 3.
- JPSS-PS-R 1.6.2: The Cloud Top Temperature Product shall have global coverage.
- JPSS-PS-R 1.6.3: The Cloud Top Temperature Product shall have Vertical Reporting Interval:
 - » Threshold Tops of up to three cloud layers; applicable to single layered clouds only
 - » Objective Tops of all distinct cloud layers
 - » Threshold Tops of highest cloud in column
 - » Objective Tops of multiple clouds in column
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 1.6.4: The Cloud Top Temperature Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.6.5: The Cloud Top Temperature Product shall have Mapping Uncertainty, 3 Sigma:
 - » Threshold 4 km
 - » Objective 1 km.

 JPSS-PS-R 1.6.6: The Cloud Top Temperature Product shall have Measurement Accuracy of 3 K for clouds with emissivity > 0.8.
 » Threshold: 6 K for COT ≥ 1 and 12 K for COT < 1
 » Objective: 1.5 K for COT ≥ 1 and 2 K for COT < 1



- JPSS-PS-R 1.6.7: The Cloud Top Temperature Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average);
 - » Objective 4 hrs;
- JPSS-PS-R 1.6.8: The Cloud Top Temperature Product Measurement Precision shall be:
 - » Threshold –1. Optical thickness ≥ 1 3K; 2. Optical Thickness < 1 – 6K;</p>
 - » Objective N/A
 - » Threshold: 6 K for $COT \ge 1$ and 12 K for COT < 1
 - » Objective: 1.5 K for $COT \ge 1$ and 2 K for COT < 1



- JPSS-PS-R 1.6.9: The Cloud Top Temperature Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

 JPSS-PS-R 1.6.10: The Cloud Top Temperature Product shall have timeliness of ≤ 3 hours.



 JPSS-PS-R 1.6.11: The requirements for the Cloud Top Temperature Product shall apply whenever detectable clouds are present.





- JPSS-PS-R 1.6.12: The JPSS RR Cloud Top Temperature shall use the VIIRS calibrated and navigated brightness temperature and radiance in bands M14, M15, M16 with solar and satellite view angles as an input data set.
 - » Primary Input Data
- JPSS-PS-R 1.6.13: The JPSS RR Cloud Top Temperature shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.6.14: The JPSS RR Cloud Top Temperature s shall use Digital Surface Elevation at 1km resolution as an input data set.
 - » Static Ancillary Input



- JPSS-PS-R 1.6.15: The JPSS RR Cloud Top Temperature shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.6.16: The JPSS RR Cloud Top Temperature shall use CRTM Clear sky radiance and transmittance for channels 14, 15, 16 and radiance profiles for channels 14, 15, 16 as an input data set.
 » Dynamic Ancillary Input – framework internal computation
- JPSS-PS-R 1.6.17: The JPSS RR Cloud Top Temperature shall use Temperature, Pressure, Height profiles, Surface Level and Tropopause Temperature from GFS model as an input data set.
 » Dynamic Ancillary Input



- JPSS-PS-R 1.6.18: The JPSS RR Cloud Top Temperature shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR Product as Input
- JPSS-PS-R 1.6.19: The JPSS RR Cloud Top Temperature shall use Cloud type produced by JPSS RR cloud type algorithm as an input data set.
 - » VIIRS derived RR Product as Input



• JPSS-PS-R 1.7: The Cloud products shall include Cloud Top Pressure Product.





- JPSS-PS-R 1.7.1: The Cloud Top Pressure Product shall have priority of JPSS 3.
- JPSS-PS-R 1.7.2: The Cloud Top Pressure Product shall have global coverage.
- JPSS-PS-R 1.7.3: The Cloud Top Pressure Product shall have Vertical Reporting Interval:
 - » Threshold Tops of up to three cloud layers; applicable to single layered clouds only
 - » Threshold Tops of highest cloud in column
 - » Objective Tops of multiple clouds in column
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 1.7.4: The Cloud Top Pressure Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.7.5: The Cloud Top Pressure Product shall have Mapping Uncertainty, 3 Sigma: threshold 4 km; objective 1 km.
- JPSS-PS-R 1.7.6: The Cloud Top Pressure Product shall have Measurement Range of:
 - » Cloudy/Not Cloudy.

 JPSS-PS-R 1.7.7: The Cloud Top Pressure Product shall have Measurement Accuracy of 50 mb for clouds with emissivity > 0.8.

- » Threshold: 100 hPa for COT ≥ 1 and 200 hPa for COT < 1
- » Objective: 50 hPa for COT ≥ 1 and 100 hPa for COT < 1



- JPSS-PS-R 1.7.8: The Cloud Top Pressure Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average); Objective – 4 hrs

• JPSS-PS-R 1.7.9: The Cloud Top Pressure Product

Measurement Precision shall be:

- » Threshold COT ≥ 1:
- <u>1. Surface to 3km 100mb</u>
- <u> 3. → 7km 50mb</u>
- » Objective -
 - -1. Surface to 3km 10mb
 - -2. 3 to 7 7 mb
- » Threshold: 100 hPa for COT ≥ 1 and 200 hPa for COT < 1
- » Objective: 50 hPa for $COT \ge 1$ and 100 hPa for COT < 1



- JPSS-PS-R 1.7.10: The Cloud Top Pressure Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

• JPSS-PS-R 1.7.11: The Cloud Top Pressure Product shall have timeliness of ≤ 3 hours.



• JPSS-PS-R 1.7.12: The requirements for the Cloud Top Pressure Product shall apply whenever detectable clouds are present.



- JPSS-PS-R 1.7.13: The JPSS RR Cloud Top Pressure shall use the VIIRS calibrated and navigated brightness temperature and radiance in bands M14, M15, M16 with solar and satellite view angles as an input data set.
 - » Primary Input data
- JPSS-PS-R 1.7.14: The JPSS RR Cloud Top Pressure shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.7.15: The JPSS RR Cloud Top Pressure shall use Digital Surface Elevation at 1km resolution as an input data set.
 - » Static Ancillary Input



- JPSS-PS-R 1.7.16: The JPSS RR Cloud Top Pressure shall use Snow Mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.7.17: The JPSS RR Cloud Top Pressure shall use CRTM Clear sky radiance and transmittance for channels 14, 15, 16 and radiance profiles for channels 14, 15, 16 as an input data set.
 - » Dynamic Ancillary Input framework internal computation
- JPSS-PS-R 1.7.18: The JPSS RR Cloud Top Pressure shall use Temperature, Pressure, Height profiles, Surface Level and Tropopause Temperature from GFS model as an input data set.
 » Dynamic Ancillary Input



- JPSS-PS-R 1.7.19: The JPSS RR Cloud Top Pressure shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR Product as Input
- JPSS-PS-R 1.7.20: The JPSS RR Cloud Top Pressure shall use Cloud type produced by JPSS RR cloud type algorithm as an input data set.
 - » VIIRS derived RR Product as Input



- JPSS-PS-R 1.8: The Cloud products shall include Cloud Optical Properties Products (Daytime and Nighttime).
- JPSS-PS-R 1.8.1: The Cloud Optical Properties products shall include Cloud Optical Thickness Product.





- JPSS-PS-R 1.8.1.1: The Cloud Optical Thickness Product shall have priority of JPSS 3.
- JPSS-PS-R 1.8.1.2: The Cloud Optical Thickness Product shall have global coverage.
- JPSS-PS-R 1.8.1.3: The Cloud Optical Thickness Product shall have Vertical Reporting Interval:
 - » Threshold up to three cloud layers;
 - » Objective 3 layers;
 - » Threshold N/A;
 - » Objective N/A;
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 1.8.1.4: The Cloud Optical Thickness Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.8.1.5: The Cloud Optical Thickness Product shall have Mapping Uncertainty, 3 Sigma:
 - » Threshold 4km
 - » Objective 1 km.

• JPSS-PS-R 1.8.1.6: The Cloud Optical Thickness Product shall have Measurement Range of:

- » 1.0 50 (day)
- » 1.0 5.0 (night)



- JPSS-PS-R 1.8.1.7: The Cloud Optical Thickness Product shall have Measurement Accuracy of:
 - » Liquid phase: 20% error (Day), 20% (Night);
 - » Ice phase: 20% Day), 30% (Night)
 - » Liquid phase: 20% (Day), 30% (Night);
 - » Ice phase: 20% (Day), 30% (Night)
- JPSS-PS-R 1.8.1.8: The Cloud Optical Thickness Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average);
 - » Objective 4 hrs;



- JPSS-PS-R 1.8.1.9: The Cloud Optical Thickness Product
 - Measurement Precision shall be:
 - * Threshold Greater of 33 % or 1 Tau
 - »—Objective—2%
 - » Greater of 30% error or 3.0 Tau (Day);
 - » Greater of 30% or 0.8 Tau (Night)

• JPSS-PS-R 1.8.1.10: The Cloud Optical Thickness Product shall have latency of 30 minutes after granule data is available.

» Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

 JPSS-PS-R 1.8.1.11: The Cloud Optical Thickness Product shall have timeliness of ≤ 3 hours.



 JPSS-PS-R 1.8.1.12: The requirements for the Cloud Optical Thickness Product shall apply whenever detectable clouds are present.





• JPSS-PS-R 1.8.2: The Cloud Optical Properties products shall include Cloud Effective Particle Size Product.





- JPSS-PS-R 1.8.2.1: The Cloud Effective Particle Size Product shall have priority of JPSS 3.
- JPSS-PS-R 1.8.2.2: The Cloud Effective Particle Size Product shall have global coverage.
- JPSS-PS-R 1.8.2.3: The Cloud Effective Particle Size Product shall have Vertical Reporting Interval:
 - * Threshold up to three cloud layers
 - » Objective 0.3 km;
 - » N/A



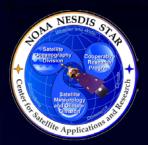
- JPSS-PS-R 1.8.2.4: The Cloud Effective Particle Size Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.8.2.5: The Cloud Effective Particle Size Product shall have Mapping Uncertainty, 3 Sigma:
 - » Threshold 4 km ;
 - » Objective 1 km.

• JPSS-PS-R 1.8.2.6: The Cloud Effective Particle Size Product

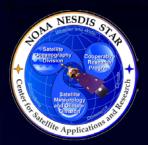
- shall have Measurement Range of:
 - » Threshold 0 to 50 μm;
 - » Objective N/S
 - » 2 50 um (day);
 - » 2 32 um for water (night)
 - » 2 50 um for ice (night)



- JPSS-PS-R 1.8.2.7: The Cloud Effective Particle Size Product shall have Measurement Accuracy of:
 - » greater of 4 µm or 30% for liquid phase
 - » 10 µm for ice phase
- JPSS-PS-R 1.8.2.8: The Cloud Effective Particle Size Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average);
 - » Objective 4 hrs;



- JPSS-PS-R 1.8.2.9: The Cloud Effective Particle Size
 - Product Measurement Precision shall be:
 - »—Threshold Greater of 22% or 1 μm for water; Greater of 28% or _1μm for ice
 - »—Objective—2%
 - » Threshold:
 - greater of 4 µm or 25% for liquid phase
 - greater of 10 µm or 25% for ice phase
 - » Objective: 10%



• JPSS-PS-R 1.8.2.10: The Cloud Effective Particle Size Product shall have latency of 30 minutes after granule data is available.

» Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

 JPSS-PS-R 1.8.2.11: The Cloud Effective Particle Size Product shall have timeliness of ≤ 3 hours.

• JPSS-PS-R 1.8.2.12: The requirements for the Cloud Effective Particle Size Product shall apply both day and night and whenever detectable clouds are present.



• JPSS-PS-R 1.8.3: The Cloud Optical Properties products shall include Cloud Liquid Water Product.





- JPSS-PS-R 1.8.3.1: The Cloud Liquid Water Product shall be have priority of JPSS 3.
- JPSS-PS-R 1.8.3.2: The Cloud Liquid Water Product shall have global coverage.
- JPSS-PS-R 1.8.3.3: The Cloud Liquid Water Product shall have Vertical Reporting Interval: N/A



- JPSS-PS-R 1.8.3.4: The Cloud Liquid Water Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.8.3.5: The Cloud Liquid Water Product shall have Mapping Uncertainty N/A
- JPSS-PS-R 1.8.3.6: The Cloud Liquid Water Product shall have Measurement Accuracy of:
 - » Greater of 25 g/m2 or 15% error (Night)
 - » 50 g/m2 (Day)



- JPSS-PS-R 1.8.3.7: The Cloud Liquid Water Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average)
 - » Objective 4 hrs

• JPSS-PS-R 1.8.3.8: The Cloud Liquid Water Product Measurement Precision shall be:

- » Greater of 25 g/m2 or 40% (Night)
- » 30 % (Day)



- JPSS-PS-R 1.8.3.9: The Cloud Liquid Water Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.
- JPSS-PS-R 1.8.3.10: The Cloud Liquid Water Product shall have timeliness of ≤ 3 hours.





• JPSS-PS-R 1.8.4: The Cloud Optical Properties products shall include Cloud Ice Water Path Product.





- JPSS-PS-R 1.8.4.1: The Cloud Ice Water Path Product shall have global coverage.
- JPSS-PS-R 1.8.4.2: The Cloud Ice Water Path Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 1.8.4.3: The Cloud Ice Water Path Product shall have Measurement Accuracy of:
 - » Greater of 25g/m2 or 30% error.
 - » 100 g/m2 (day)



- JPSS-PS-R 1.8.4.4: The Cloud Ice Water Path Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours (monthly average);
 - » Objective 4 hrs;



- JPSS-PS-R 1.8.4.5: The Cloud Ice Water Path Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.

 JPSS-PS-R 1.8.4.6: The Cloud Ice Water Path Product shall have timeliness of ≤ 3 hours.



- JPSS-PS-R 1.8.5: The JPSS RR Daytime Cloud Optical Properties shall use VIIRS calibrated and navigated brightness temperature in band 12 and reflectance in bands 5, 7, 10, and 11 with solar and satellite view angles as an input data set.
 - » Primary Input Data
- JPSS-PS-R 1.8.6: The JPSS RR Daytime Cloud Optical Properties shall use Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.8.7: The JPSS RR Daytime Cloud Optical Properties shall use UW Baseline Fit Emissivity for band 7 as an input data set.
 - » Static Ancillary Input



- JPSS-PS-R 1.8.8: The JPSS RR Daytime Cloud Optical Properties shall use Temperature and Water Vapor profiles from GFS model as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.8.9: The JPSS RR Daytime Cloud Optical Properties shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR Product as Input

 JPSS-PS-R 1.8.10: The JPSS RR Daytime Cloud Optical Properties shall use Cloud height produced by JPSS RR cloud height algorithm as an input data set.

» VIIRS derived RR Product as Input



- JPSS-PS-R 1.8.11: The JPSS RR Daytime Cloud Optical Properties shall use Cloud type produced by JPSS RR cloud type algorithm as an input data set.
 - » VIIRS derived RR Product as Input
- JPSS-PS-R 1.8.12: The JPSS RR Daytime Cloud Optical Properties shall be validated for Solar Zenith angle <= 70 deg and verified between 70 deg and 82 deg.
- JPSS-PS-R 1.8.13: The JPSS RR Nighttime Cloud Optical Properties shall use VIIRS calibrated and navigated brightness temperature in bands M12, M15, M16 with solar and satellite view angles as an input data set.
 - » Primary Input Data



- JPSS-PS-R 1.8.14: The JPSS RR Nighttime Cloud Optical Properties shall use Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.8.15: The JPSS RR Nighttime Cloud Optical Properties shall use UW Baseline Fit Surface Emissivity for band 7 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 1.8.16: The JPSS RR Nighttime Cloud Optical Properties shall use Clear sky radiance and transmittance for bands 12, 15, 16 TOA radiance for a black cloud bands 12, 15, 16 from CRTM model as an input data set.
 - Dynamic Ancillary Input framework internal computation



- JPSS-PS-R 1.8.17: The JPSS RR Nighttime Cloud Optical Properties shall use Temperature, Pressure, Height profiles from GFS model as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 1.8.18: The JPSS RR Nighttime Cloud Optical Properties shall use Cloud mask produced by JPSS RR cloud mask algorithm and Cloud Type used by JPSS RR Cloud Type algorithm as an input data sets.
 - » VIIRS derived RR products as input
- JPSS-PS-R 1.8.19: The JPSS RR Nighttime Cloud Optical Properties shall be validated for Solar Zenith angle >= 90 deg and verified between 82 and 90 deg.



- JPSS-PS-R 1.9: The Cloud Products shall include quality information.
 - » QC flags will be specified in the External Users Manual.
- JPSS-PS-R 1.10: The JPSS RRPS shall write Cloud Products files in NetCDF4 formats.
 - » SPSRB requirement



- JPSS-PS-R 1.11: The JPSS RRPS system shall perform validation and verification of the Cloud Products.
 - » Validation tools will be based upon the GOES-R validation tools and/or the heritage validation tools
- JPSS-PS-R 1.11.1: The JPSS RRPS system shall plot datasets for verification of the Cloud Products.



- JPSS-PS-R 1.11.2: The JPSS RRPS system shall verify that Cloud Products files are generated correctly.
 - » Will be included in the unit tests described in the UTR and the system test described in the ARR.
- JPSS-PS-R 1.11.3: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the input data.
 - » Anomalous values will be flagged. These checks will be included in the code and described in the ARR.



- JPSS-PS-R 1.11.4: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the Cloud Products.
 - » Out-of-range values will be flagged. These checks will be included in the code. UTR will address.
- JPSS-PS-R 1.11.5: The JPSS RRPS system shall generate matchup datasets between Cloud Products retrievals and in situ measurements.
 - » In situ data obtained from NCEP & ECMWF analysis, SURFRAD measurements, and CALIPSO data.



• JPSS-PS-R 2.0: The JPSS RRPS shall generate Aerosol Products.

Driver: SPSRB requirements:

 1009-0016: Dust Aerosol Concentration Product
 0707-0014: Support satellite-based verification of the National Air Quality Forecast Capability



- JPSS-PS-R 2.1: The Aerosol Products shall include Aerosol Optical Depth.
- JPSS-PS-R 2.1.1: The Aerosol Optical Depth Product priority shall be JPSS 4.
- JPSS-PS-R 2.1.2: The Aerosol Optical Depth Product shall have global coverage.



• JPSS-PS-R 2.1.3: The Aerosol Optical Depth Product shall have Horizontal Cell Size of 0.75 km (nadir).

• JPSS-PS-R 2.1.4: The Aerosol Optical Depth Product shall have Vertical Reporting Interval of:

- » Threshold Total column;
- » Objective Total column



- JPSS-PS-R 2.1.5: The Aerosol Optical Depth Product shall have Mapping Uncertainty, 3 Sigma, of:
 - » Threshold 4 km
 - » Objective 1 km

JPSS-PS-R 2.1.6: The Aerosol Optical Depth Product shall have

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Measurement Range of:

- * Threshold 0 to 2
- » Objective 0 to 10
- » Threshold 0.05 to 5
- » Objective 0 to 10



- JPSS-PS-R 2.1.7: The Aerosol Optical Depth Product shall have
 - measurement accuracy based on Aerosol Optical Depth ranges:
 - »—Over land:
 - <u>< 0.04: 0.06; 0.04 0.80: 0.04; > 0.80: 0.12</u>
 - » Over water:
 - < 0.40: 0.02; > 0.40: 0.10
 - Threshold:
 - » Over land:
 - -0.06 (Tau < 0.1); 0.05 (0.1 \leq Tau \leq 0.8); 0.2 (Tau > 0.8)
 - » Over water:

– 0.08 (Tau < 0.3); 0.15 (Tau ≥ 0.3)</p>
Objective : 1 %



- JPSS-PS-R 2.1.8: The Aerosol Optical Depth Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours 24 hours (monthly average)
 - » Objective 4 hrs

• JPSS-PS-R 2.1.9: The Aerosol Optical Depth Products shall have latency of 30 minutes after granule data is available.

 JPSS-PS-R 2.1.10: The Aerosol Optical Depth Products shall have timeliness of ≤ 3 hours.



 JPSS-PS-R 2.1.11: The Aerosol Optical Depth Products shall have Measurement Precision of:

Threshold –

- » Over Ocean 0.15 (Tau < 0.3); 0.35 (Tau ≥ 0.3) (1,2,4);
- » Over Land 0.15 (Tau < 0.1); 0.25 (0.1 ≤ Tau ≤ 0.8); 0.45 (Tau > 0.8); Objective –
- » Over Ocean –0.01; Over Land –0.01;
- » Threshold
 - Over land:
 - 0.15 (Tau < 0.1); 0.25 (0.1 ≤Tau ≤ 0.8); 0.45 (Tau > 0.8)
 Over water:
 - 0.15 (Tau < 0.3); 0.35 (Tau ≥ 0.3);</p>
- » Objective: 0.01
- Current operational products, with upgraded capabilities



 JPSS-PS-R 2.1.12: Applicable Conditions for Aerosol Optical Depth shall be:

- 1. Clear, daytime only
- 2. Zenith angles less than or equal to 80 degrees.



- JPSS-PS-R 2.1.13: The JPSS RR Aerosol Optical Depth shall use the VIIRS calibrated and navigated reflectance in bands M1, M2, M3, M4, M5, M8 and M11 over land and M4, M5, M7, M8, M10, M11 over Water with solar and satellite view angles as an input data set.
 » Primary Input data
- JPSS-PS-R 2.1.14: The JPSS RR Aerosol Optical Depth shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 2.1.15: The JPSS RR Aerosol Optical Depth shall use Digital Surface Elevation at 1km resolution as an input data set.
 » Static Ancillary Input



- JPSS-PS-R 2.1.16: The JPSS RR Aerosol Optical Depth shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR product input
- JPSS-PS-R 2.1.17: The JPSS RR Aerosol Optical Depth shall use Location of areas covered by snow or ice as an input data set.
 » Ancillary input
- JPSS-PS-R 2.1.18: The JPSS RR Aerosol Optical Depth shall use Fire Mask as an input data set.
 - » Ancillary Input

• JPSS-PS-R 2.1.19: The JPSS RR Aerosol Optical Depth shall use Heavy Aerosol Mask as an input data set.

» Ancillary input



• JPSS-PS-R 2.1.20: The JPSS RR Aerosol Optical Depth shall use Lookup tables of atmospheric optical functions (reflectance, transmittance, and spherical albedo) calculated from 6S radiative transfer model as an input data set.

» Algorithm Ancillary input

 JPSS-PS-R 2.1.21: The JPSS RR Aerosol Optical Depth shall use Water surface sunglint directional-hemispherical reflectance calculated from 6S radiative transfer model as an input data set.
 » Algorithm Ancillary input

• JPSS-PS-R 2.1.22: The JPSS RR Aerosol Optical Depth shall use Surface wind speed and direction (clockwise from local north) as an input data set.

» Dynamic Ancillary input



- JPSS-PS-R 2.1.23: The JPSS RR Aerosol Optical Depth shall use NCEP model predicted surface pressure and corresponding surface height as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 2.1.24: The JPSS RR Aerosol Optical Depth shall use NCEP total precipitable water grids that bracket the satellite data as an input data set.
 » Dynamic Ancillary Input
- JPSS-PS-R 2.1.25: The JPSS RR Aerosol Optical Depth shall use NCEP surface height grids as an input data set.
 » Dynamic Ancillary Input
- JPSS-PS-R 2.1.26: The JPSS RR Aerosol Optical Depth shall use NCEP Ozone data as an input data set.
 - » Dynamic Ancillary Input



- JPSS-PS-R 2.2: The Aerosol Products shall include Aerosol Detection.
- JPSS-PS-R 2.2.1: The Aerosol Detection Product priority shall be JPSS 3.
- JPSS-PS-R 2.2.2: The Aerosol Detection Product shall have global coverage.



- JPSS-PS-R 2.2.3: The Aerosol Detection Product shall have Horizontal Cell Size of 0.75 km.
- JPSS-PS-R 2.2.4: The Aerosol Detection Product shall have Vertical Reporting Interval of:
 » Threshold: Total Column
 » Objective: 0.2 km



 JPSS-PS-R 2.2.5: The Aerosol Detection Product shall have Mapping Uncertainty, 3 Sigma, of:

- » Threshold: 3 km
- » Objective: 0.1 km

 JPSS-PS-R 2.2.6: The Aerosol Detection Product shall have Measurement Range of:
 » Smoke: 0 to 200 microg/m3



 JPSS-PS-R 2.2.7: The Aerosol Detection Product shall have measurement accuracy of:

- » Dust: 80% correct detection over land and ocean
- » Smoke: 80% 70% Correct detection over land and ocean

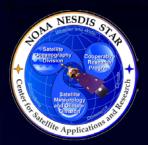
» 70% correct detection over ocean



- JPSS-PS-R 2.2.8: The Aerosol Detection Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours 24 hours (monthly average);
 - » Objective 4 hrs;
- JPSS-PS-R 2.2.9: The Aerosol Detection Products shall have latency of 30 minutes after granule data is available.
- JPSS-PS-R 2.2.10: The Aerosol Detection Products shall have timeliness of ≤ 3 hours.
 - Current operational products, with upgraded capabilities



- JPSS-PS-R 2.2.11: The JPSS RR Aerosol Detection shall use the VIIRS calibrated and navigated reflectance in bands M1, M2, M5, M6, M7, M8, M10 and M11 with solar and satellite view angles as an input data set.
 - » Primary input Data
- JPSS-PS-R 2.2.12: The JPSS RR Aerosol Detection shall use the MODIS Collection 5 1km resolution Land/Water Mask as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 2.2.13: The JPSS RR Aerosol Detection shall use Digital Surface Elevation at 1km resolution as an input data set.
 » Static Ancillary Input
- JPSS-PS-R 2.2.14: The JPSS RR Aerosol Detection shall use Cloud mask produced by cloud mask algorithm as an input data set.
 » VIIRS derived RR Product as Input



- JPSS-PS-R 2.2.15: The JPSS RR Aerosol Detection shall use Location of areas covered by snow or ice as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 2.2.16: The JPSS RR Aerosol Detection shall use Location of areas covered by sun glint as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 2.2.17: The JPSS RR Aerosol Detection shall use Day/Night Mask Defined by VIIRS pixel observation time as an input data set.
 - » Dynamic Ancillary Input



- JPSS-PS-R 2.3: The Aerosol Products shall include Aerosol Particle Size Parameter Product.
- JPSS-PS-R 2.3.1: The Aerosol Particle Size Parameter Product priority shall be JPSS 4.
- JPSS-PS-R 2.3.2: The Aerosol Particle Size Parameter Product shall have global coverage.



- JPSS-PS-R 2.3.3: The Aerosol Particle Size Parameter Product shall have Horizontal Cell Size of 0.75 km (nadir) and 1.6 km (EOS).
- JPSS-PS-R 2.3.4: The Aerosol Particle Size Parameter Product shall have Vertical Coverage of:
 * Threshold - Surface to 30 km
 * Objective - Surface to 50 km

• JPSS-PS-R 2.3.5: The Aerosol Particle Size Parameter Product

- shall have Vertical Cell Size of:
 - » Threshold Total Column;
 - » Objective 0.25 km;



- JPSS-PS-R 2.3.6: The Aerosol Particle Size Parameter Product shall have Mapping Uncertainty, 3 Sigma, of:
 - » Threshold 4 km
 - » Objective 1 km

• JPSS-PS-R 2.3.7: The Aerosol Particle Size Parameter Product shall have Measurement Range of:

- » Threshold Operational
- » -1 to +3 alpha units
- » Objective -2 to +4 alpha units



- JPSS-PS-R 2.3.8: The Aerosol Particle Size Parameter Product shall have measurement accuracy of:
 - » Fine/Coarse Angstrom exponent: 0.3 over ocean and land





- JPSS-PS-R 2.3.9: The Aerosol Particle Size Parameter Product Refresh Rate shall be:
 - » Threshold At least 90% coverage of the globe every 12 hours 24 hours (monthly average);
 - » Objective 4 hrs;

• JPSS-PS-R 2.3.10: The Aerosol Particle Size Parameter Products shall have latency of 30 minutes after granule data is available.



- JPSS-PS-R 2.3.11: The Aerosol Particle Size Parameter Products shall have timeliness of ≤ 3 hours.
- JPSS-PS-R 2.3.12: The Aerosol Particle Size Parameter Products shall have Measurement Precision of:
 - Operational over Ocean
 - » Threshold 0.3 alpha units
 - » Objective 0.1 alpha units
 - » Threshold 0.6 alpha units
 - » Objective 0.1 alpha units



 JPSS-PS-R 2.3.13: Applicable Conditions for Aerosol Particle Size Parameter Product shall be:

» Clear, daytime only



- JPSS-PS-R 2.3.14: The JPSS RR Aerosol Particle Size Parameter shall use the VIIRS calibrated and navigated reflectance in bands <u>M1, M2, M3, M4, M5, M8 and M11 over land and</u> M4, M5, M7, M8, M10, M11 over Water with solar and satellite view angles as an input data set.
 - » Primary Input Data

• JPSS-PS-R 2.3.15: The JPSS RR Aerosol Particle Size

Parameter shall use the MODIS Collection 5 1km resolution Land Mask as an input data set.

» Static Ancillary Input

• JPSS-PS-R 2.3.16: The JPSS RR Aerosol Particle Size

Parameter shall use Digital Surface Elevation at 1km resolution as an input data set.

» Static Ancillary Input



 JPSS-PS-R 2.3.17: The JPSS RR Aerosol Particle Size Parameter shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.

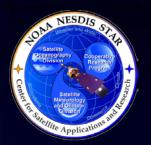
» VIIRS derived RR Product input

• JPSS-PS-R 2.3.18: The JPSS RR Aerosol Particle Size Parameter shall use Location of areas covered by snow or ice as an

input data set.

» Dynamic Ancillary Input

- JPSS-PS-R 2.3.19: The JPSS RR Aerosol Particle Size Parameter shall use Fire Mask as an input data set.
 » Dynamic Ancillary Input
- JPSS-PS-R 2.3.20: The JPSS RR Aerosol Particle Size Parameter shall use Heavy Aerosol Mask as an input data set.
 » Dynamic Ancillary input



- JPSS-PS-R 2.3.21: The JPSS RR Aerosol Particle Size Parameter shall use Lookup tables of atmospheric optical functions (reflectance, transmittance, and spherical albedo) calculated from 6S
 - radiative transfer model as an input data set.
 - » Algorithm Ancillary Input

• JPSS-PS-R 2.3.22: The JPSS RR Aerosol Particle Size

Parameter shall use Water surface sunglint directional-hemispherical reflectance calculated from 6S radiative transfer model as an input data set.

» Algorithm Ancillary Input

• JPSS-PS-R 2.3.23: The JPSS RR Aerosol Particle Size Parameter shall use Surface wind speed and direction (clockwise from local north) as an input data set.

» Dynamic Ancillary Input



- JPSS-PS-R 2.3.24: The JPSS RR Aerosol Particle Size Parameter shall use NCEP model predicted surface pressure and corresponding surface height as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 2.3.25: The JPSS RR Aerosol Particle Size Parameter shall use NCEP total precipitable water grids that bracket the satellite data as an input data set.
 - » Dynamic Ancillary Input
- JPSS-PS-R 2.3.26: The JPSS RR Aerosol Particle Size Parameter shall use NCEP surface height grids as an input data set.
 » Dynamic Ancillary Input
- JPSS-PS-R 2.3.27: The JPSS RR Aerosol Particle Size Parameter shall use NCEP Ozone data as an input data set.
 » Dynamic Ancillary Input



- JPSS-PS-R 2.4: The Aerosol Products shall include quality information.
 - » QC flags will be specified in the External Users Manual.

• JPSS-PS-R 2.5: The JPSS RRPS shall write Aerosol Products files in NetCDF4 formats.

» SPSRB requirement



- JPSS-PS-R 2.6: Aerosol Products shall be validated and verified.
 - » Validation tools will be based upon the GOES-R validation tools

• JPSS-PS-R 2.6.1: The JPSS RRPS system shall plot datasets for verification of the Aerosol Products.



- JPSS-PS-R 2.6.2: The JPSS RRPS system shall verify that Aerosol Products files are generated correctly.
 - » Will be included in the unit tests described in the UTR and the system test described in the ARR.
- JPSS-PS-R 2.6.3: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the input data.
 - » Anomalous values will be flagged. These checks will be included in the codeand described in the ARR.



- JPSS-PS-R 2.6.4: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the Aerosol Products.
 - » Out-of-range values will be flagged. These checks will be included in the code. UTR will address.

• JPSS-PS-R 2.6.5: The JPSS RRPS system shall generate matchup datasets between Aerosol Products retrievals and in situ measurements.

» In situ data obtained from AERONET Measurements



• JPSS-PS-R 3.0: The JPSS RRPS shall generate Volcanic Ash Products.

Driver: SPSRB requirements:

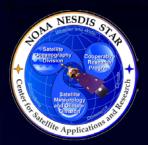
 0507-05: Polar/Geostationary Volcanic Ash Detection and Height on CLAVR-X



- JPSS-PS-R 3.1: The Volcanic Ash Products shall include Volcanic Ash Detection (Mass Loading) and Height.
- JPSS-PS-R 3.1.1: The Volcanic Ash Detection (Mass Loading) and Height Product shall have priority of JPSS 3.
- JPSS-PS-R 3.1.2: The Volcanic Ash Detection (Mass Loading) and Height Product shall have Horizontal Cell Size of 0.75 km.



- JPSS-PS-R 3.1.3: The Volcanic Ash Detection (Mass Loading) and Height Products shall have global coverage.
- JPSS-PS-R 3.1.4: The Volcanic Ash Detection (Mass Loading) and Height Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 3.1.5: The Volcanic Ash Detection (Mass Loading) and Height Product shall have Product Refresh Rate of at least 90% coverage of the globe every 12 hours (monthly average).
- JPSS-PS-R 3.1.6: The Volcanic Ash Detection (Mass Loading) and Height Product shall have timeliness of ≤ 3 hours.

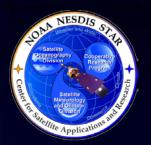




- JPSS-PS-R 3.1.7: The Volcanic Ash Detection (Mass Loading) and Height Product shall have Mapping Uncertainty, 3 Sigma of:
 - » Threshold 3 km
 - » Objective 0.1 km
- JPSS-PS-R 3.1.8: The Volcanic Ash Detection (Mass Loading) and Height Product shall have Measurement Precision of:
 - » 2.5 tons/km2



- JPSS-PS-R 3.1.9: The Volcanic Ash Detection (Mass Loading) and Height Product shall have Measurement Accuracy of:
 2 tons/km2 3 km height
 - » 2 tons/km2, 3 km height.
- JPSS-PS-R 3.1.10: The Applicable Conditions for Volcanic Ash Detection (Mass Loading) and Height Product shall be:
 - » Clear, for AOD greater than 0.15, daytime only.



- JPSS-PS-R 3.1.11: The JPSS RR Volcanic Ash <u>Detection</u> (Mass Loading) and Height shall use the VIIRS calibrated and navigated reflectance in band M5 and brightness temperature & radiances in bands 12, 14, 15 and 16 with solar & satellite view angles as an input data set.
 - » Primary Input Data
- JPSS-PS-R 3.1.12: The JPSS RR Volcanic Ash <u>Detection</u> (<u>Mass Loading</u>) and Height shall use the Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - Static Input Data
- JPSS-PS-R 3.1.13: The JPSS RR Volcanic Ash <u>Detection</u> (<u>Mass Loading</u>) and Height shall use Temperature, Pressure, Height profiles, Surface Temperature Level, Tropopause Level, and Surface Temperature as an input data sets.
 - Dynamic Input Data



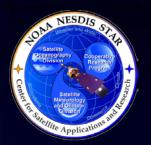
- JPSS-PS-R 3.1.14: The JPSS RR Volcanic Ash <u>Detection (Mass</u> <u>Loading)</u> and Height shall use Clear sky radiance and transmittance for bands 14, 15 and 16 TOA radiance for a black cloud bands 14, 15 and 16 from CRTM model as an input data sets.
 - » Dynamic Input Data framework internal computation
- JPSS-PS-R 3.1.15: The JPSS RR Volcanic Ash <u>Detection (Mass</u> <u>Loading)</u> and Height shall use Snow mask by the Interactive Multisensor Snow and Ice Mapping System as an input data set.
 - Dynamic Input data



- JPSS-PS-R 3.2: The Volcanic Ash Detection (Mass Loading) and Height Product shall include quality information.
 - » QC flags will be specified in the External Users Manual.
- JPSS-PS-R 3.3: The JPSS RRPS shall write Volcanic Ash Detection (Mass Loading) and Height Product files in NetCDF4 formats.
 - » SPSRB requirement.



- JPSS-PS-R 3.4: The JPSS RRPS system shall perform validation and verification of the Volcanic Ash Detection (Mass Loading) and Height Product.
 » Validation tools will be based upon the GOES-R validation tools
- JPSS-PS-R 3.4.1: The JPSS RRPS system shall plot datasets for verification of the Volcanic Ash Detection (Mass Loading) and Height Products.



- JPSS-PS-R 3.4.2: The JPSS RRPS system shall verify that Volcanic Ash Detection (Mass Loading) and Height Products files are generated correctly.
 - » Will be included in the unit tests described in the UTR and the system test described in the ARR.
- JPSS-PS-R 3.4.3: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the input data.
 - » Anomalous values will be flagged. These checks will be included in the code And described in the ARR.



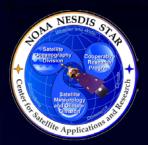
- JPSS-PS-R 3.4.4: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the Volcanic Ash Detection (Mass Loading) and Height Products.
 - » Out-of-range values will be flagged. These checks will be included in the code. UTR will address.

• JPSS-PS-R 3.4.5: The JPSS RRPS system shall generate matchup datasets between Volcanic Ash Detection (Mass Loading) and Height Products retrievals and in situ measurements.

» In situ data obtained from CALIPSO data.



- JPSS-PS-R 4.0: The JPSS RRPS shall generate Cryosphere Products.
 - » Driver: SPSRB requirements: SPSRB 0707-0018 "Add 4 new capabilities to IMS snow cover analysis"



- JPSS-RRPS-R 4.1: The Cryosphere Products shall include Snow Cover Product and a Fractional Snow Cover Product.
- JPSS-PS-R 4.1.1: The Snow Cover Product shall have priority of JPSS 3.
- JPSS-PS-R 4.1.2: The Snow Cover Product shall have Horizontal Cell Size of 0.375 km 1.6 km EOS.



JPSS-PS-R 4.1.3: The Snow Cover Product shall have global coverage.

• JPSS-PS-R 4.1.4: The Snow Cover Product shall have latency of 30 minutes after granule data is available.

» Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 4.1.5: The Snow Cover Product shall have Product Refresh Rate of:
 - » Threshold at least 90% coverage of the globe every 12 hours 24 hours (monthly average).
 - » Objective 3 hrs;

• JPSS-PS-R 4.1.6: The Snow Cover Product shall have timeliness of ≤ 3 hours.



 JPSS-PS-R 4.1.7: The Snow Cover Product shall have Mapping Uncertainty, 3 Sigma of:

- » Threshold
 - Clear 3km;
 - Cloudy N/S
- » Objective
 - Clear 1 km; Cloudy – 1km;

 JPSS-PS-R 4.1.8: The Snow Cover Product shall have Measurement Range of :

» 0 or 1 BSC mask



• JPSS-PS-R 4.1.9: The Snow Cover Product shall have Measurement Accuracy of 90% correct classification.

 JPSS-PS-R 4.1.10: The Snow Cover Product shall have Sensing Depth of:

- » Threshold N/S
- » Objective 1.0 m

 JPSS-PS-R 4.1.11: The Applicable Conditions for Snow Cover Product shall be:

» Clear Daytime, only



- JPSS-PS-R 4.1.12: The JPSS RR Snow Cover shall use the VIIRS calibrated and navigated reflectance in bands 11, 12, and 13 along with solar and satellite view angles as an input data set.
 - » Primary Input Data

 JPSS-PS-R 4.1.13: The JPSS RR Snow Cover shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 » VIIRS derived RR product as input

 JPSS-PS-R 4.1.14: The JPSS RR Snow Cover shall use Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.

» Static Ancillary Input



• JPSS-PS-R 4.1.15: The JPSS RR Snow Cover shall use Digital surface elevation at 1km resolution as an input data set.

» Static Ancillary Input

• JPSS-PS-R 4.1.16: The JPSS RR Snow Cover shall use Weekly maps of snow cover frequency of occurrence on 1/3 degree global lat/lon grid as an input data set.

» Static Ancillary Input

• JPSS-PS-R 4.1.17: The JPSS RR Snow Cover shall use Monthly mean land surface temperature as an input data set.

» Static Ancillary Input



- JPSS-RRPS-R 4.1.18: The Cryosphere Products shall include Fractional Snow Cover Product.
- JPSS-PS-R 4.1.19: The Fractional Snow Cover Product shall have priority of JPSS 3.
- JPSS-PS-R 4.1.20: The Fractional Snow Cover Product shall have Horizontal Cell Size of 0.375 km.



- JPSS-PS-R 4.1.21: The Fractional Snow Cover Product shall have global coverage.
- JPSS-PS-R 4.1.22: The Fractional Snow Cover Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 4.1.23: The Fractional Snow Cover Product shall have Product Refresh Rate of:
 - » Threshold at least 90% coverage of the globe every 12 hours 24 hours (monthly average).
 - » Objective 3 hrs

 JPSS-PS-R 4.1.24: The Fractional Snow Cover Product shall have timeliness of ≤ 3 hours.



 JPSS-PS-R 4.1.25: The Fractional Snow Cover Product shall have Mapping Uncertainty, 3 Sigma of:

- » Threshold
 - Clear 3km;
 - Cloudy N/S
- » Objective
 - Clear 1 km; Cloudy – 1km;

 JPSS-PS-R 4.1.26: The Fractional Snow Cover Product shall have Measurement Range of :

» 0 or 100% HSC area fraction



• JPSS-PS-R 4.1.27: The Fractional Snow Cover Product shall have Measurement Uncertainty of 10% of FSC area.

• JPSS-PS-R 4.1.28: The Fractional Snow Cover Product shall have Sensing Depth of:

- » Threshold N/S
- » Objective 1.0 m

 JPSS-PS-R 4.1.29: The Applicable Conditions for Fractional Snow Cover Product shall be:

» Clear Daytime, only



- JPSS-PS-R 4.1.30: The JPSS RR Fractional Snow Cover shall use the VIIRS calibrated and navigated reflectance in bands I1, I2, I3, I4 and I5 along with solar and satellite view angles as an input data set.
 - » Primary Input Data
- JPSS-PS-R 4.1.31: The JPSS RR Fractional Snow Cover shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR product as input
- JPSS-PS-R 4.1.32: The JPSS RR Fractional Snow Cover shall use Binary Snow mask produced by JPSS RR Snow Cover algorithm as an input data set.
 - » VIIRS derived RR product as input



- JPSS-PS-R 4.1.33: The JPSS RR Fractional Snow Cover shall use Digital surface elevation at 1km resolution as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 4.1.34: The JPSS RR Fractional Snow Cover shall use Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 4.1.35: The JPSS RR Fractional Snow Cover shall use Global 250 m land/water mask used for MODIS collection 6 as an input data set.
 - **»** Static Ancillary Input



- JPSS-RRPS-R 4.2: The Cryosphere Products shall include Sea Ice Concentration Product.
- JPSS-PS-R 4.2.1: The Sea Ice Concentration Product shall have priority of JPSS 3.
- JPSS-PS-R 4.2.2: The Sea Ice Concentration Product shall have Horizontal Cell Size of 0.75 km.



- JPSS-PS-R 4.2.3: The Sea Ice Concentration Product shall have global coverage.
- JPSS-PS-R 4.2.4: The Sea Ice Concentration Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 4.2.5: The Sea Ice Concentration Product shall have timeliness of ≤ 3 hours.
- JPSS-PS-R 4.2.6: The Sea Ice Concentration Product shall have Product Refresh Rate of:
 - » Threshold at least 90% coverage of the globe every 12 hours 24 hours (monthly average).
 - » Objective 6 hrs

 JPSS-PS-R 4.2.7: The Sea Ice Concentration Product shall have vertical coverage of Ice Surface.



• JPSS-PS-R 4.2.8: The Sea Ice Concentration Product shall have Mapping Uncertainty, 3 Sigma of:

» Threshold

Clear - 1km @ nadir Cloudy -No capability

» Objective

Clear – 0.5 km Cloudy - 1 km

 JPSS-PS-R 4.2.9: The Sea Ice Concentration Product shall have Measurement Range of 0/10 to 10/10 0 – 100%.



Basic Requirement 4.0

- JPSS-PS-R 4.2.10: The Sea Ice Concentration Product shall have Measurement Uncertainty of 10% 25%.
- JPSS-PS-R 4.2.11: The Sea Ice Concentration Product shall have Cloud Leakage Rate of:
 » Ocean, Day, COT>1.0, outside Sun Glint region – 1%;
 » Day, Land, COT>1.0 – 3%;
 » Land, Ocean, Night, COT>1.0 – 5%



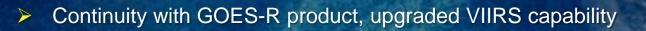
• JPSS-PS-R 4.2.12: The JPSS RR Sea Ice Concentration shall use VIIRS calibrated and navigated Brightness Temperature in Channel M5, M7, M10, M15 and M16 along with solar and satellite view angles as an input data set.

» Primary Input Data

- JPSS-PS-R 4.2.13: The JPSS RR Sea Ice Concentration shall use global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 4.2.13: The JPSS RR Sea Ice Concentration shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS derived RR product as input



- JPSS-RRPS-R 4.3: The Cryosphere Products shall include Ice Age Product.
- JPSS-PS-R 4.3.1: The Ice Age Product shall have priority of JPSS 3.
- JPSS-PS-R 4.3.2: The Ice Age Product shall have Horizontal Cell Size of 0.75 km.





- JPSS-PS-R 4.3.3: The Ice Age Product shall have global coverage.
- JPSS-PS-R 4.3.4: The Ice Age Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 4.3.5: The Ice Age Product shall have timeliness of ≤ 3 hours.
- JPSS-PS-R 4.3.6: The Ice Age Product shall have Product Refresh Rate of:
 - » Threshold at least 90% coverage of the globe every 12 hours 24 hours (monthly average).
 - » Objective 6 hrs

 JPSS-PS-R 4.3.7: The Ice Age Product shall have vertical coverage of Ice Surface.



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Basic Requirement 4.0

• JPSS-PS-R 4.3.8: The Ice Age Product shall have Mapping Uncertainty, 3 Sigma of:

- » Threshold Clear - 1km @ nadir Cloudy -No capability
- » Objective

Clear – 0.5 km Cloudy - 1 km



• JPSS-PS-R 4.3.9: The Ice Age Product shall have Measurement Range of:

» Threshold

Ice free, New/Young Ice, all other ice

» Objective

Ice Free, Nilas, Grey White, Grey, White, First Year Medium, First Year Thick, Second Year, and Multiyear; Smooth and Deformed Ice



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Basic Requirement 4.0

- JPSS-PS-R 4.3.10: The Ice Age Product shall have Measurement Uncertainty of :
 - » 80% correct classification (Ice free areas, First year ice, Older ice)
 - » 70% correct classification



- JPSS-PS-R 4.3.11: The JPSS RR Ice Age shall use VIIRS solar and satellite view angles as an input data set.
 - » Primary Input data
- JPSS-PS-R 4.3.12: The JPSS RR Ice Age shall use Global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input
- JPSS-PS-R 4.3.13: The JPSS RR Ice Age shall use NWP Derived surface air temperature, surface air pressure, surface air moisture, surface wind speed, snow cover, and snow depth as an input data set.
 » Dynamic Ancillary Input



- JPSS-PS-R 4.3.14: The JPSS RR Ice Age shall use Ice concentration and Ice cover produced by JPSS RR ice concentration/cover algorithm as an input data set.
 - » VIIRS derived RR product as input
- JPSS-PS-R 4.3.15: The JPSS RR Ice Age shall use Ice surface skin temperature produced by JPSS RR ice surface temperature algorithm as an input data set.
 - » VIIRS derived RR product as input

 JPSS-PS-R 4.3.16: The JPSS RR Ice Age shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 » VIIRS derived RR product as input



- JPSS-PS-R 4.3.17: The JPSS RR Ice Age shall use Parameterization File to represent the VIIRS Surface Solar Radiation as an input data set.
 - » Algorithm Ancillary Input
- JPSS-PS-R 4.3.18: The JPSS RR Ice Age shall use Parameterization File to represent the VIIRS Surface Thermal Radiation as an input data set.
 - » Algorithm Ancillary Input
- JPSS-PS-R 4.3.19: The JPSS RR Ice Age shall use Parameterization File to represent the VIIRS Surface Broadband Albedo as an input data set.
 - » Algorithm Ancillary Input



- JPSS-RRPS-R 4.4: The Cryosphere Products shall include Ice Surface Temperature Product.
- JPSS-PS-R 4.4.1: The Ice Surface Temperature Product shall have priority of JPSS 4.
- JPSS-PS-R 4.4.2: The Ice Surface Temperature Product shall have Horizontal Cell Size of 0.75 km 1.6 km.



- JPSS-PS-R 4.4.3: The Ice Surface Temperature Product shall have global coverage.
- JPSS-PS-R 4.4.4: The Ice Surface Temperature Product shall have latency of 30 minutes after granule data is available.
 - » Latency is defined as the processing time allocated to product generation. Current capability is 60 minutes.



- JPSS-PS-R 4.4.5: The Ice Surface Temperature Product shall have timeliness of ≤ 3 hours.
- JPSS-PS-R 4.4.6: The Ice Surface Temperature Product shall have Product Refresh Rate of:
 - » Threshold at least 90% coverage of the globe every 12 hours 24 hours (monthly average).
 - » Objective 12 hrs;

 JPSS-PS-R 4.4.7: The Ice Surface Temperature Product shall have Sensing Depth of Ice Surface.



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Basic Requirement 4.0

- JPSS-PS-R 4.4.8: The Ice Surface Temperature Product shall have Mapping Uncertainty, 3 Sigma of:
 - » Threshold
 - 1. Nadir 1km
 - 2. Worst Case 1.6 km
 - » Objective
 - 1. Nadir 0.1km
 - 2. Worst Case 0.1 km



- JPSS-PS-R 4.4.9: The Ice Surface Temperature Product shall have Measurement Range of:
 - » Threshold 213 - 275 K
 - » Objective-213 - 293 K (2 m above ice)

• JPSS-PS-R 4.4.10: The Ice Surface Temperature Product shall have Measurement Uncertainty of 1K.



- JPSS-PS-R 4.4.11: The JPSS RR Ice Surface Temperature shall use VIIRS calibrated and navigated Brightness Temperature in Channels M15 and M16 with solar and satellite view angles as an input data set.
 » Primary Input data
- JPSS-PS-R 4.4.12: The JPSS RR Ice Surface Temperature shall use global 1 km land/water & coast mask used for MODIS collection 5 as an input data set.
 - » Static Ancillary Input



- JPSS-PS-R 4.4.13: The JPSS RR Ice Surface Temperature shall use Cloud mask produced by JPSS RR cloud mask algorithm as an input data set.
 - » VIIRS generated RR product as input

• JPSS-PS-R 4.4.14: The JPSS RR Ice Surface Temperature shall use Ice concentration and Ice cover produced by JPSS RR ice concentration/cover algorithm as an input data set.

» VIIRS generated RR product as input



• JPSS-RRPS-R 4.5: The Cryosphere Products shall include quality information.

» QC flags will be specified in the External Users Manual.

 JPSS-RRPS-R 4.6: The JPSS RRPS shall write Cryosphere Products files in NetCDF4 formats.

» SPSRB requirement.



- JPSS-RRPS-R 4.7: The JPSS RRPS system shall perform validation and verification of the Cryosphere Products.
 » Validation tools will be based upon the GOES-R validation tools
- JPSS-RRPS-R 4.7.1: The JPSS RRPS system shall plot datasets for verification of the Cryosphere Products.



- JPSS-RRPS-R 4.7.2: The JPSS RRPS system shall verify that Cryosphere Products files are generated correctly.
 - » Will be included in the unit tests described in the UTR and the system test described in the ARR

• JPSS-RRPS-R 4.7.3: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the input data.

» Anomalous values will be flagged. These checks will be included in the codeand described in the ARR.



- JPSS-PS-R .4.7.4: The JPSS RRPS system shall perform routine data range checks to flag anomalous values in the Cryosphere Products.
 - » Out-of-range values will be flagged. These checks will be included in the code. UTR will address
- JPSS-RRPS-R 4.7.5: The JPSS PS system shall generate matchup datasets between Cryosphere Products retrievals and in situ measurements.
 - » In situ data obtained from NCEP & ECMWF analysis, AMSR-E products, Upward Looking Sonar data, Canadian Ice Service measurements and Buoy data.



- JPSS-RRPS-R 5.0: The JPSS PS system shall have data ingestion capability.
 - » Driver:
 - This basic requirement is traced to algorithm input needs, as documented in the Algorithm Theoretical Basis Documents (ATBDs).



- JPSS-RRPS-R 5.1: The JPSS PS system shall ingest NPP VIIRS L1 data.
 - » Required algorithm input. Ingest from the IDPS. Data link for development is established by NDE.



- JPSS-RRPS-R 6.0: The GOES-R algorithms to generate a retrieval of Cloud Products, Aerosol Products, Volcanic Ash Products, and Cryosphere Products shall be modified.
 - » Driver:
 - This basic requirement is traced to user needs for Cloud, Aerosol, Volcanic Ash, and Cryosphere products.



- JPSS-RRPS-R 6.1: The JPSS RRPS Algorithms shall be implemented by processing codes written in C, C++ and Fortran 90.
 - » Adaptation of current algorithm/framework code.
- JPSS-RRPS-R 6.1.1: The JPSS RRPS processing code shall be able to run in the STAR Development Environment (Linux with 12 dual core 3.2 GHz CPUs.
 - » S/W: Intel and GNU Compilers (C/C++/Fortran) and IDL for Validation
 - » Storage: 100 TB)
 - » C code, C++ code, and Fortran code can run in this environment



- JPSS-RRPS-R 6.1.2: The JPSS RRPS processing code shall be able to run in the NDE 2.0 Test Environment (Linux machine with 6 quad core 3.2 GHz CPUs
 - » S/W: Intel and GNU Compilers (C/C++/Fortran) and IDL for Validation
 - » Storage: 30 TB
 - » C code, C++ code, and Fortran code can run in this environment

• JPSS-RRPS-R 6.1.3: The JPSS RRPS processing code shall be able to run in the OSPO Operations Environment: (Linux machine with 6 quad core 3.2 GHz CPUs

- » S/W: Intel and GNU Compilers (C/C++/Fortran) and IDL for Validation
- » Storage: 30 TB
- » C code, C++ code, and Fortran code can run in this environment



- JPSS-RRPS-R 7.0: The JPSS RRPS system shall generate metadata for each retrieved product.
 - » Driver:

– Metadata will be used by the Product Monitoring Project



- JPSS-RRPS-R 7.1: The JPSS RRPS system shall write metadata into the NetCDF4 files associated with the retrieved products.
 - » Coordinate with the Product Monitoring Project.
- JPSS-RRPS-R 7.1.1: The metadata shall include overall quality and summary level metadata.
 - » Coordinate with the Product Monitoring Project.



- JPSS-RRPS-R 7.1.2: The metadata shall include Granule metadata.
 - » Coordinate with the Product Monitoring Project.

• JPSS-RRPS-R 7.1.3: The metadata shall include product specific metadata.

» Coordinate with the Product Monitoring Project.



- JPSS-RRPS-R 8.0: The JPSS RRPS system shall have QC monitoring capability.
 - » Driver:

This basic requirement is traced to an OSPO need for QC monitoring.



- JPSS-RRPS-R 8.1: The JPSS RRPS Product files shall include overall quality control flags and quality summary level metadata.
 - » Needed for distribution, quality control and post-processing. JPSS PS code will generate metadata for this purpose.
- JPSS-RRPS-R 8.2: The JPSS RRPS system shall be capable of monitoring input data latency and overall quality.
 » Need to import metadata from input file and create code for generating metadata.



 JPSS-RRPS-R 8.3: The JPSS RRPS system shall be capable of monitoring product latency.
 » Run status file will include processing time.

 JPSS-RRPS-R 8.4: The JPSS RRPS system shall produce real-time imagery for visual inspection of output files.
 Will be done with IDL.



- JPSS-RRPS-R 8.5: The JPSS RRPS system shall be capable of monitoring product distribution status to ensure that the data/products are successfully available for transfer to the user community.
 - » A run status file will be produced. Work with OSPO to determine needs.
- JPSS-RRPS-R 8.5.1: Each run status file shall include all runtime error messages.
 - » Error messages will include system messages and error conditions written by the code.



- JPSS-RRPS-R 8.5.2: Each run status file shall indicate whether or not the run was completed without error.
 - » Code will write this message. This indication will be the last message in the file, so that operators can find it easily.
- JPSS-RRPS-R 8.6: The JPSS PS system shall write a log file for each production run.
 - » Used by OSPO for QC monitoring and troubleshooting.



- JPSS-RRPS-R 9.0: The JPSS PS shall produce a fully functional pre-operational system in the STAR Development Environment.
 - » Driver:

 This basic requirement is traced to an NDE need for a unit-tested, fully functional system delivered to its Test Environment.



- JPSS-RRPS-R 9.1: The STAR Development Environment shall be capable of hosting the conversion of JPSS RRPS science code to JPSS RRPS pre-operational code.
 - » See derived requirements 9.1.x.
- JPSS-RRPS-R 9.1.1: The STAR Development Environment shall include the INTEL FORTRAN 90/95 compiler and GNU FORTRAN 90/95 compiler.
 - » Needed for the Framework FORTRAN code. Development Environment servers have this.



- JPSS-RRPS-R 9.1.2: The STAR Development Environment shall include the INTEL C compiler and the GNU C compiler.
 - » Needed for the Framework C code. Development Environment servers have this.
- JPSS-RRPS-R 9.1.3: The STAR Development Environment shall include the INTEL C++ compiler and the GNU C++ compiler.
 - » Needed for the Framework C++ code. Development Environment servers have this.



- JPSS-RRPS-R 9.1.4: The STAR Development Environment shall include Linux machine with 100TB of disk storage.
 » Development Environment servers have this.
- JPSS-RRPS-R 9.2: The STAR Development Environment shall be capable of hosting unit tests and a system test.
 - » Unit tests and system test required prior to delivery of pre-operational system to OSPO.



- JPSS-RRPS-R 9.2.1: The STAR Development Environment shall have access to the OSPO DDS/PDA server.
 » For ingest of JPSS VIIRS RR products.
- JPSS-RRPS-R 9.2.2: The STAR Development Environment shall have access to the GRAVITE server.
 » For ingest of JPSS VIIRS SDR data.



- JPSS-RRPS-R 9.3: The STAR Development Environment shall host the pre-operational system.
 - » For development and unit testing. Complete unit test of the pre-operational system is expected before delivery to NDE.
- JPSS-RRPS-R 9.3.1: The pre-operational system shall include all processing code and ancillary files needed to conduct unit tests.
 - » Complete unit test of the pre-operational system is expected before delivery to NDE. The UTRR will provide a detailed description of the source code units and ancillary files.



- JPSS-RRPS-R 9.3.2: The pre-operational system shall include all input test data needed to conduct unit tests.
 - » Complete unit test of the pre-operational system is expected before delivery to NDE. The UTRR will provide a detailed description of the unit test data.
- JPSS-RRPS-R 9.3.3: The JPSS RRPS pre-operational system baseline shall be established and maintained with the Clear Case CM tool.
 - » CM of the pre-operational system is expected throughout its development.



• JPSS-RRPS-R 10.0: The JPSS RRPS integrated preoperational system shall be transitioned from the STAR Development Environment to the NDE 2.0 Test Environment.

» Driver:

 This basic requirement is traced to an NDE need for a systemtested, integrated pre-operational system delivered to its Test Environment.



- JPSS-RRPS-R 10.1: The STAR Development Environment shall host the JPSS RRPS integrated pre-operational system.
 - » For system testing. A complete system test of the integrated pre-operational system is expected before delivery to NDE.
- JPSS-RRPS-R 10.1.1: The integrated pre-operational system shall include all processing code and ancillary files needed to conduct the system test.
 - » Complete system test of the integrated pre-operational system is expected. The ARR will provide a description of the processing software system and ancillary files.



- JPSS-RRPS-R 10.1.2: The integrated pre-operational system shall include all input data needed to conduct a system test.
 - » Complete system test of the integrated pre-operational system is expected. The ARR will provide a description of the system test data.
- JPSS-RRPS-R 10.1.3: The integrated pre-operational system shall include all output data produced by the system test.
 - » Needed by NDE to verify the system test in its Test Environment. Comparison of outputs from system test in STAR and NDE 2.0 environments will be part of the NDE system test. Specific items will be listed in the ARR.



- JPSS-RRPS-R 10.1.4: The JPSS RRPS integrated preoperational system baseline shall be established and maintained with the Clear Case CM tool.
 - » CM of the integrated pre-operational system is expected throughout its development.



- JPSS-RRPS-R 10.2: The integrated pre-operational system shall be delivered to NDE via SADIE as a preliminary Delivered Algorithm Package (DAP).
 - » NDE needs to reproduce the system test in its Test Environment.
- JPSS-RRPS-R 10.2.1: The JPSS RRPS development team shall ensure that the NDE PAL has the information needed to acquire the preliminary JPSS RRPS DAP from SADIE.
 » Use of SADIE ensures this.



• JPSS-RRPS-R 11.0: STAR shall deliver a JPSS RRPS document package to OSPO.

» <u>Driver:</u>

 This basic requirement is traced to an OSPO need for documentation to support operations, maintenance, and distribution.



- JPSS-RRPS-R 11.1: The JPSS RRPS document package shall include a README text file.
- JPSS-RRPS-R 11.1.1: The README file shall list each item in the final pre-operational system baseline, including code, test data, and documentation.
 - » All required deliverable items must be correctly identified



- JPSS-RRPS-R 11.2: The JPSS RRPS document package shall include a Review Item Disposition (RID) document.
- JPSS-RRPS-R 11.2.1: The RID shall describe the final status of all development project tasks, work products, and risks.
 - » Supports the final Algorithm Readiness Review Report (ARRR)



- JPSS-RRPS-R 11.3: The JPSS RRPS document package shall include an Algorithm Theoretical Basis Document (ATBD).
 - » The ATBD will follow SPSRB Version 2 document standards
- JPSS-RRPS-R 11.4: The JPSS RRPS document package include a Requirements Allocation Document (RAD).
 - » The RAD will follow document standards stated in EPL v3 process asset DG-6.2



- JPSS-RRPS-R 11.5: The JPSS RRPS document package shall include a System Maintenance Manual (SMM).
 - » The SMM will follow SPSRB Version 2 document standards.
- JPSS-RRPS-R 11.6: The JPSS RRPS document package shall include an External Users Manual (EUM).
 » The EUM will follow SPSRB Version 2 document standards.



 JPSS-RRPS-R 11.7: The JPSS RRPS document package shall include an Internal Users Manual (IUM).

The IUM will follow SPSRB Version 2 document standards.

• JPSS-RRPS-R 11.8: The JPSS RRPS document package shall include a Critical Design Document (CDD).

» The CDD will follow STAR EPL document standards in DG-8.2 and DG-8.2.A.



- JPSS-RRPS-R 11.9: The JPSS RRPS document package shall include a Code Test Document (CTD).
 - » The CTD will follow STAR EPL document standards in DG-10.3 and DG-10.3.A.
- JPSS-RRPS-R 11.10: The JPSS RRPS document package shall include a System Readiness Document (SRD).
 - » The SRD will follow STAR EPL document standards in DG-11.5 and DG-11.5.A.



- JPSS-RRPS-R 11.11: The JPSS RRPS document package shall include a Algorithm Readiness Review Report (ARRR).
 - » The ARRR will follow document standards stated in EPL v3 process asset DG-11.6
- JPSS-RRPS-R 11.11.1: The ARRR shall document the approved readiness of the JPSS RR PS system for transition to operations.
 - » This is an ARR exit criteria item



- JPSS-RRPS-R 12.0: The JPSS RRPS system shall undergo an OSPO Code Review Security for security compliance
 - » <u>Driver:</u>
 - OSPO Security





- JPSS-RRPS-R 12.1: The JPSS RRPS system shall comply with OSPO data integrity check list.
 - » OSPO data integrity check list is part of the OSPO Code Review Security check lists.
- JPSS-RRPS-R 12.2: The JPSS RRPS system shall comply with OSPO development security check list.
 - » OSPO development security check list is part of the OSPO Code Review Security check lists.



- JPSS-RRPS-R 12.3: The JPSS RRPS system shall comply with OSPO code check list.
 - » OSPO code check list is part of the OSPO Code Review Security check lists.



• JPSS-RRPS-R 13.0: The IT resource needs for operations shall be specified.

» Driver:

- OSPO IT Capacity Planning





- JPSS-RRPS-R 13.1: The JPSS RRPS system shall run on Redhat Linux.
 - » Servers are available.
- JPSS-RRPS-R 13.2: Operational server shall have 30 TB of disk space.
 - » Available servers have this capability.
- JPSS-RRPS-R 13.3: Each operational server shall have 8 GB of RAM for each core.
 - » Available servers have this capability.



JPSS RR Requirements shown with the JPSS L1RD Supplement Requirements



Cloud Mask

JPSS RRPS Cloud Mask Supplement Requirements Table

User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	400 m
Cloud Mask Horizontal Reporting Interval	Cloud Mask HCS	NS
Mapping Uncertainty, 3 Sigma	4 km	1 km
Cloud Mask Measurement Range	Cloudy/Not Cloudy	NS
Cloud Mask Probability of Correct Typing	 Global - 87% Ocean, Day – 92% Ocean, Night – 90% Snow-free Land, Day – 90% Snow-free Land, Night – 88% Desert, Day – 85% Desert, Night – 85% Snow-covered Land, Day – 88% Snow-covered Land, Night – 85% Sea-Ice, Day – 82% Sea-Ice, Night – 72% Antarctica and Greenland, Day – 80% Antarctica and Greenland, Night – 70% 	N/S
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	205
Timeliness	≤ 3hours	283



Cloud Mask

Cloud Mask Applicable Conditions:

- 1. Requirements apply whenever detectable clouds are present.
- 2. Cloud Mask shall be computed and reported for the total cloud cover.



Cloud Top Phase

JPSS RRPS Cloud Phase Supplement Requirements Table

Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	400 m
Vertical Reporting Interval	N/S	N/S
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Accuracy	80% correct classification	
Measurement Precision	N/S	N/S
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Type

JPSS RRPS Cloud Type Supplement Requirements Table

Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	400 m
Vertical Reporting Interval	N/S	N/S
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Accuracy	60% correct classification	
Measurement Precision	N/S	N/S
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Top Height

JPSS RRPS Cloud Top Height Supplement Requirements Table		
User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	Top of highest Cloud in column	Top of multiple cloud layers in column
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Precision	COT ≥ 1 – 1.0 km COT < 1 – 2.0 km	COT ≥ 1 – 0.15 km COT < 1 – 0.15 km
Measurement Accuracy	COT ≥ 1 – 1.0 km COT < 1 – 2.0 km	COT ≥ 1 – 0.30 km COT < 1 – 0.30 km
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Top Height (CTH)

CTH Applicable Conditions:

 1. Requirements apply whenever detectable clouds are present.





Cloud Top Temperature

JPSS RRPS Cloud To	p Temperature	Supplement Re	quirements Table
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User & Priority	JPSS4	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	Top of highest Cloud in column	Top of multiple clouds in column
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Precision	COT ≥ 1 – 6 K COT < 1 – 12 K	COT ≥ 1 – 1.5 K COT < 1 – 2 K
Measurement Accuracy	COT ≥ 1 – 6 K COT < 1 – 12 K	COT ≥ 1 – 1.5 K COT < 1 – 2 K
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Top Temperature (CTT)

CTT Applicable Conditions:

 1. Requirements apply whenever detectable clouds are present.





Cloud Top Pressure

JPSS RRPS Cloud Top Pressure Supplement Requirements Table

User & Priority	JPSS4	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	Top of highest Cloud in column	Top of multiple clouds in column
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Precision	COT ≥ 1 – 100 hPa COT < 1 – 200 hPa	COT ≥1 – 50 mb COT <1 – 100 mb
Measurement Accuracy	COT ≥ 1 – 100 hPa COT < 1 – 200 hPa	COT ≥1 – 50 mb COT <1 – 100 mb
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Top Pressure (CTP)

CTP Applicable Conditions:

 1. Requirements apply whenever detectable clouds are present.



Cloud Optical Depth

JPSS RRPS Cloud Optical Depth Supplement Requirements Table

User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	N/A	N/A
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	1.0 – 50.0 (Day) 1.0 – 5.0 (Night)	N/A
Measurement Precision	Greater of 30 % or 3.0 Tau (Day) Greater of 30 % or 0.8 Tau (Night)	10 %
Measurement Accuracy	Liquid phase: 20% (Day), 30% (Night); Ice phase: 20% (Day), 30% (Night)	N/A
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Optical Thickness (COD)

COD (COT) Applicable Conditions:

 1. Requirements apply whenever detectable clouds are present.



Cloud Effective Particle Size

JPSS RRPS Cloud Effective particle Size Supplement Requirements Table

User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	N/A	N/A
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	2 to 50 μm(day); 2 to 32 μm for water (night); 2 to 50 μm for ice (night)	NS
Measurement Precision	Greater of 4 μm or 25% for water; Greater of 10 μm or 25% for ice	10 %
Measurement Accuracy	Greater of 4 μm or 30% for water; 10 μm for ice	
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Effective Particle Size (CEPS)

CEPS Applicable Conditions:

 1. Requirements apply both day and night and whenever detectable clouds are present.



Cloud Liquid Water

JPSS RRPS Cloud Liquid Water Supplement Requirements Table

User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	N/A	N/A
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	25 – 100 g/m2	NS
Measurement Precision	30% (Day) Greater of 25 g/m2 or 40% (Night)	
Measurement Accuracy	50 g/m2 (Day) Greater of 25 g/m2 or 15% (Night)	
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Cloud Ice Water Path

JPSS RRPS Cloud Ice Water Supplement Requirements Table

User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Reporting Interval	N/A	N/A
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	25 – 175 g/m2	NS
Measurement Precision	40% (Day) Greater of 25 g/m2 or 40% (Night)	
Measurement Accuracy	100 g/m2 (Day) Greater of 25 g/m2 or 30% (Night)	
Product Refresh Rate	At least 90% coverage of the globe every 12hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Aerosol Detection

JPSS RRPS Aerosol Detection S	Supplement Requirements Table
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User & Priority	JPSS3	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Cell Size	Total Column	0.2 km
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	Dust/sand and Smoke.	Dust/Sand, Ash, sea salt
Probability of correct typing	Smoke: 70 % Dust: 80%	Smoke: 100 % Dust: 100%
Product Refresh Rate	At least 90% coverage of the globe every 24hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Aerosol Detection

Aerosol Detection Applicable Conditions:Clear, for AOT > 0.15, daytime only



Aerosol Optical Depth

JPSS RRPS AOD Supplement Requirements Table

User & Priority	JPSS4	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	0.4 km
Vertical Cell Size	Total Column	0.2 km
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	-0.05 to 5	0 to 10
Measurement Precision	Over Ocean: 0.15 (Tau < 0.3) 0.35 (Tau ≥ 0.3) Over land: 0.15 (Tau < 0.1); 0.25 (0.1 ≤ Tau ≤ 0.8); 0.45 (Tau > 0.8)	0.01
Measurement Accuracy	Over Ocean: 0.08 (Tau < 0.3) 0.15 (Tau ≥ 0.3) Over land: 0.06 (Tau < 0.1); 0.05 (0.1 ≤ Tau ≤ 0.8); 0.2 (Tau > 0.8)	1%
Product Refresh Rate	At least 90% coverage of the globe every 24hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Aerosol Optical Depth (AOD)

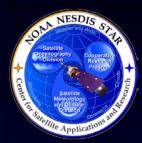
AOD Applicable Conditions:

- Clear, daytime only
- Zenith angles less than or equal to 80 degrees.



Aerosol Particle Size Parameter

JPSS RRPS APSP Supplement Requirements Table		
User & Priority	JPSS4	
Attribute	Threshold	Objective
Geographic Coverage	Global coverage	
Horizontal Cell Size	0.8 km at Nadir	
Vertical Cell Size	Total Column	0.25 km
Mapping Uncertainty, 3 Sigma	4 km	1 km
Measurement Range	-1 to +3 alpha units	-2 to +4 alpha units
Measurement Precision	Operational Over Ocean: 0.6 alpha units	Operational Over Ocean: 0.6 alpha units
Measurement Uncertainty	Operational Over Ocean: 0.3 alpha units	Operational Over Ocean: 0.1 alpha units
Product Refresh Rate	At least 90% coverage of the globe every 24hours (monthly average)	4 hrs
Latency	30 minutes after granule data is available	
Timeliness	≤ 3hours	



Aerosol Particle Size Parameter (APSP)

APSP Applicable Conditions:1. Clear, daytime, Ocean only





Volcanic Ash and Height

JPSS RRPS Volcanic Ash Detection and Height Supplement Requirements Table

User & Priority	JPSS4		
Attribute	Threshold	Objective	
Geographic Coverage	Global coverage		
Horizontal Cell Size	0.8 km at Nadir		
Vertical Cell Size	Total Column	0.2 km	
Mapping Uncertainty, 3 Sigma	4 km	1 km	
Measurement Accuracy	2 tons/km2, 3 km height		
Measurement Precision	2.5 tons/km2		
Product Refresh Rate	At least 90% coverage of the globe every 12 hours (monthly average)	4 hrs	
Latency	30 minutes after granule data is available		
Timeliness	≤ 3hours		



Volcanic Ash

Applicable Conditions:

• 1. Clear, for AOD greater than 0.15.



Snow Cover

JPSS RRPS Snow Cover Supplement Requirements Table

User & Priority	JPSS3		
Attribute	Threshold	Objective	
Geographic Coverage	Global coverage		
Horizontal Cell Size	1.6 km EOS	1 km	
Measurement Range	0 or 1 binary mask		
Mapping Uncertainty, 3 Sigma	4 km Cloudy: Not Applicable	Clear/Cloudy: 1 km	
Probability of correct classification	Clear: 90% Cloudy: Not Applicable		
Product Refresh Rate	At least 90% coverage of the globe every 24 hours (monthly average)	3 hrs	
Latency	30 minutes after granule data is available		
Timeliness	≤ 3hours		



Fractional Snow Cover

JPSS RRPS Fractional Snow Cover Supplement Requirements Table

User & Priority	JPSS3		
Attribute	Threshold	Objective	
Geographic Coverage	Global coverage		
Horizontal Cell Size	1.6 km EOS	1 km	
Measurement Range	0 – 100% area fraction		
Mapping Uncertainty, 3 Sigma	4 km Cloudy: Not Applicable	Clear/Cloudy: 1 km	
Probability of correct detection	Clear: 20% Cloudy: Not Applicable	Clear: 10% Cloudy: Not Applicable	
Product Refresh Rate	At least 90% coverage of the globe every 24 hours (monthly average)	3 hrs	
Latency	30 minutes after granule data is available		
Timeliness	≤ 3hours		



Snow Cover

Snow Cover Applicable Conditions:Clear Daytime, only



Sea Ice Concentration

JPSS RRPS Sea Ice Concentration Supplement Requirements Table

User & Priority	JPSS3		
Attribute	Threshold	Objective	
Geographic Coverage	All ice-covered regions of the global ocean		
Vertical Coverage	Ice Surface	Ice Surface	
Horizontal Cell Size	Clear: 1.0 km All weather: no capability	Clear: 0.5 km All weather: 1 km	
Measurement Range	0 – 100%		
Mapping Uncertainty, 3 Sigma	Clear: 1 km at nadir Cloudy: No capability	Clear: 0.5 km Cloudy: 1 km	
Measurement Accuracy	10%		
Measurement Uncertainty	25%		
Product Refresh Rate	At least 90% coverage of the globe every 24 hours (monthly average)	6 hrs	
Latency	30 minutes after granule data is available		
Timeliness	≤ 3hours		



Ice Age/Thickness

JPSS RRPS Ice Age/Thicknes	s Supplement Requirements Table
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User & Priority	JPSS3			
Attribute	Threshold	Objective		
Geographic Coverage	All ice-covered regions of the global ocean			
Vertical Coverage	Ice Surface	Ice Surface		
Horizontal Cell Size	Clear: 1.0 km All weather: no capability	Clear: 0.5 km All weather: 1 km		
Measurement Range	Ice free, New/Young Ice, all other ice	Ice Free, Nilas, Grey White, Grey, White, First Year Medium, First Year Thick, Second Year, and Multiyear; Smooth and Deformed Ice		
Mapping Uncertainty, 3 Sigma	Clear: 1 km at nadir Cloudy: No capability	Clear: 0.5 km Cloudy: 1 km		
Measurement Uncertainty, Probability of correct Typing of ice classes	New/Young Ice – 70% Other Ice – 70%	New/Young Ice – 90% Other Ice – 90%		
Product Refresh Rate	At least 90% coverage of the globe every 24 hours (monthly average)	6 hrs		
Latency	30 minutes after granule data is available			
Timeliness	≤ 3hours			



Ice Surface Temperature

JPSS RRPS Ice Surface Temperature Supplement Requirements Table

User & Priority	JPSS4			
Attribute	Threshold	Objective		
Geographic Coverage	All ice-covered regions of the global ocean			
Sensing Depth	Ice Surface	Ice Surface		
Horizontal Cell Size Nadir - 1km Worst Case –1.6 km		Nadir - 0.1km Worst Case – 0.1 km		
Measurement Range	213 - 275 K	213 - 293 K (2 m above ice)		
Mapping Uncertainty, 3 Sigma	Clear: 1 km at nadir Cloudy: No capability	Clear: 0.5 km Cloudy: 1 km		
Measurement Uncertainty	1 K	1 K		
Product Refresh Rate	At least 90% coverage of the globe every 24 hours (monthly average)	6 hrs		
Latency	30 minutes after granule data is available			
Timeliness	≤ 3hours			



Sea Ice Characterization

Sea Ice Characterization Applicable Conditions:Clear sky conditions only.



JPSS RRPS System Requirements – Summary

- The JPSS Risk Reduction System Requirements have been established.
- The Requirements have been documented in the Requirements Allocation Document (RAD).
- The Requirements are traceable to drivers (customer needs or expectations) and other requirements.



Outline

- Introduction
- Risks and Actions
- Requirements
- Algorithm Readiness
- Software Architecture
- Delivered Algorithm Package
- Risks Summary
- Summary and Conclusions

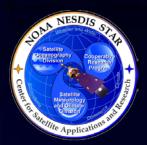


Algorithm Readiness Review (ARR) VIIRS Clear Sky Mask

Presented by

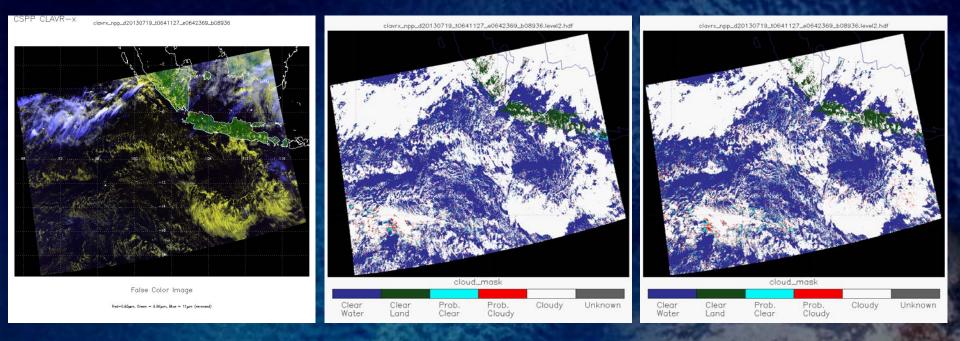
Andrew Heidinger NOAA/NESDIS/STAR

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Algorithm Output: Example 4-level Mask

Example Output of the RGB (left), CLAVR-x Cloud Mask (center), and Framework Cloud Mask (right) July 19, 2013 from 06:38:21 to 06:42:36 UTC



RGB

Cloud Mask CLAVR-x Cloud Mask Framework





- The equivalence of one day's worth of data (≈1000 granules) processed through Cloud Mask implemented in the Framework/SAPF.
- These granules are chosen to be co-located with CALIPSO, and spread over the whole 2013 year.
- CALIPSO and VIIRS validation tools run on these data to demonstrate compliance with the L1RD requirements.



CDR Requirements Clear Sky Masks

Name	Vertical Resolution	Horizontal Resolution	Mapping Accuracy	Measurement Range	Measurement Accuracy	Temporal Coverage Qualifiers	Cloud Cover Conditions Qualifier	Product Statistics Qualifier
Clear Sky Mask	N/A	0.75 km		0 – 1 Binary (0 – 3 for 4- Level Mask)	13% probability of incorrect detection	Day and night	Clear conditions associated with threshold accuracy	Over specified geographic area

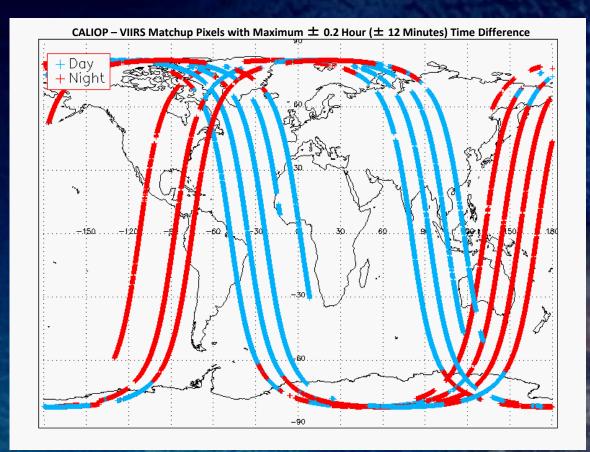


Performance Estimates: Calculation of Metrics

- The Probability of Incorrect Detection (POID) is 13% (threshold)
- POD = (number of correctly identified clear pixels + number of correctly identified cloudy pixels) / (number of cloudy CALIPSO pixels and number of clear CALIPSO pixels)
- Leakage or Missed Cloud = number of pixels with cloud mask = CLEAR or PROBABLY CLEAR when collocated CALIPSO views within a VIIRS pixel were cloudy.
- False Alarm = number of pixels with cloud mask = CLOUDY or PROBABLY CLOUDY when no collocated CALIPSO views within VIIRS pixel were cloudy.
- •For this computation, the 4-level mask was converted to a binary mask



CALIPSO Collocation Pixels

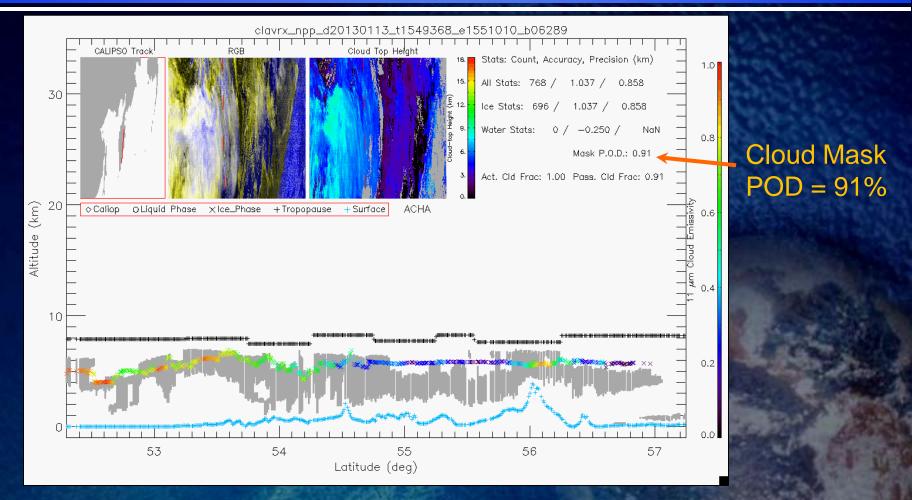


~1000 granules collocation from 2013 Processed by Framework

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VIIRS Cloud Mask with CALIPSO/CALIOP



Collocation tools are applied to VIIRS Cloud Mask for CALIPSO based Cloud Layer Products.



CALIPSO Collocation Stats

~1000 granules collocation from 2013 Processed by Frame Work

Sample		Cloud f	raction		Probability of			
Size	Active	Passive	Prob. Clear	Prob. Cloudy	Detection	False Detect.	Leakage	
	90N – 90S (Global), Ocean / Land, Day / Night, No Snow / Snow / Ice							
453935	0.727	0.692	0.075	0.089	0.888	0.038	0.074	
		60N – 60S	, Ocean / Land, I	Day / Night, No S	Snow / No Ice			
283271	0.698	0.651	0.034	0.046	0.933	0.010	0.057	
	60N – 60S, Ocean, Day, No Snow / No Ice							
122078	0.688	0.661	0.016	0.021	0.951	0.011	0.038	
60N – 60S, Ocean, Night, No Snow / No Ice								
84021	0.803	0.721	0.056	0.088	0.908	0.005	0.087	
		60	N – 60S, Land, E	Day, No Snow / N	lo Ice			
33193	0.571	0.551	0.017	0.015	0.952	0.014	0.034	
		106	I – 60S, Land, N	ight, No Snow / I	No Ice			
24534	0.568	0.492	0.072	0.054	0.906	0.009	0.085	
		90N – 60N (Arcti	ic), Ocean / Lanc	l, Day / Night, No	Snow / Snow /	lce		
55222	0.707	0.654	0.180	0.155	0.725	0.111	0.164	
	9	0S – 60S (Antaro	ctic), Ocean / Lar	nd, Day / Night, N	lo Snow / Snow	/ Ice		
55184	0.642	0.701	0.209	0.269	0.766	0.146	0.088	

POD exceeds 87% threshold for all but Polar Regions. Overall global POD = 88.8%.

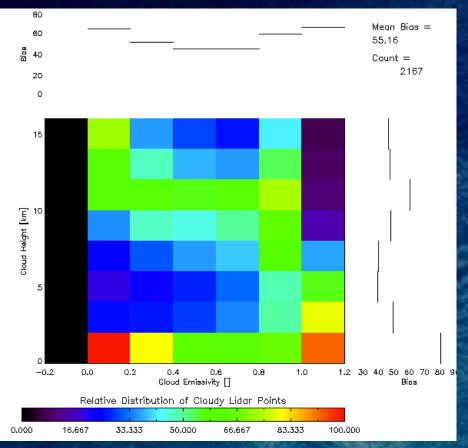
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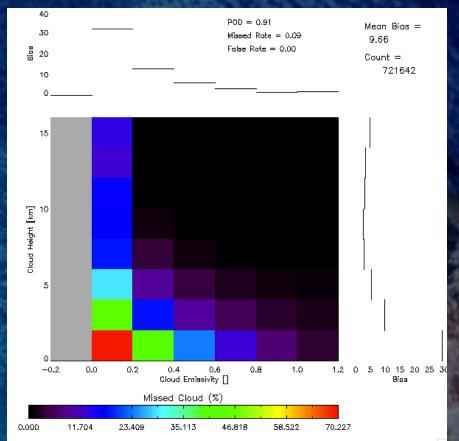
CALIPSO – VIIRS Analysis

Given the quantity of VIIRS/CALIPSO matchups. Here are results for ~1000 granules of 2013 for all regions.

Height/Emissivity distribution of Cloudy CALIPSO values



Height/Emissivity distribution of missed pixels



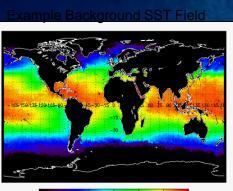


Performance Estimates: SST Bias Monitoring

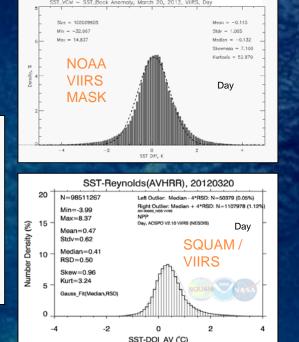
 We have worked closely with STAR SST Team on the GOES-R AWG and JPSS CAL/VAL programs.

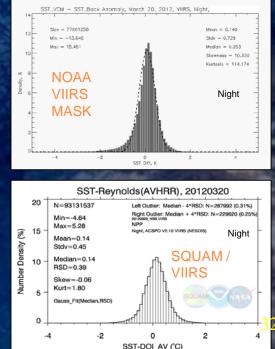
• We have developed tools to match the SQUAM (SST Quality Monitoring Analysis) results and will use these to monitor our cloud mask's performance.

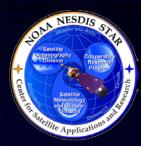
•SST Team will always do additional filtering that is not appropriate for a multi-purpose cloud mask.



275.0 280.0 285.0 290.0 295.0 300.0 305.0







Summary of Validation Results

 ~1000 granules of VIIRS where processed and validated against CALIOP cloud product;

 VIIRS Clear Sky Mask performance is within requirements, but improvement is possible and should be executed.



References

- Heidinger, Andrew K.; Evan, Amato T.; Foster, Michael J. and Walther, Andi. A naive Bayesian cloud-detection scheme derived from CALIPSO and applied within PATMOSx. Journal of Applied Meteorology and Climatology, Volume 51, Issue 6, 2012, 1129–1144
- Schreiner, Anthony J.; Ackerman, Steven A.; Baum, Bryan A. and Heidinger, Andrew K. A multispectral technique for detecting low-level cloudiness near sunrise. Journal of Atmospheric and Oceanic Technology, Volume 24, Issue 10, 2007, pp.1800-1810.
- Thomas, Sarah M.; Heidinger, Andrew K. and Pavolonis, Michael J.. Comparison of NOAA's operational AVHRR-derived cloud amount to other satellite-derived cloud climatologies. Journal of Climate, Volume 17, Issue 24, 2004, pp.4805-4822.
- Heidinger, Andrew K.; Frey, Richard and Pavolonis, Michael. Relative merits of the 1.6 and 3.75 micron channels of the AVHRR/3 for cloud detection. Canadian Journal of Remote Sensing, Volume 30, Issue 2, 2004, pp.182-194.



VIRS Cloud Phase/Type Algorithm Readiness Presented by Mike Pavolonis

NOAA/NESDIS/STAR





- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

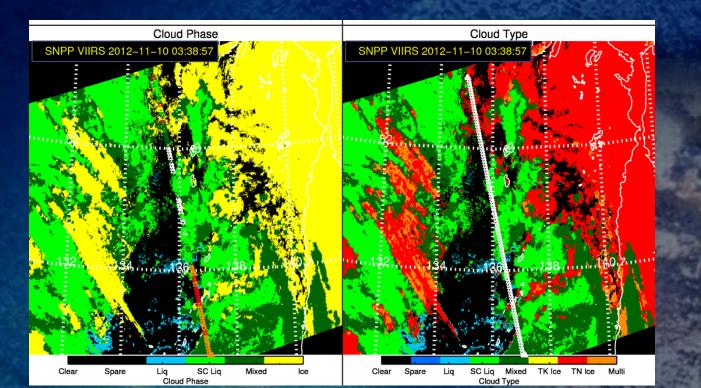
Goal: Demonstrate science quality of the VIIRS cloud phase and type products.

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VIIRS Cloud Phase/Type Overview

- Cloud type is derived through exploitation of multi-spectral signals in VIIRS infrared data (8.5 (M14), 11 (M15), 12 μm (M16))
 - » Cloud type categories: liquid water, supercooled liquid water, mixed phase, thick ice, thin ice, multilayered ice
 - » The ice related cloud type categories are combined to produce the cloud phase product
 - » The product includes data quality flags and metadata





Requirements Cloud Top Phase

Name		User & Priority		Geographic Coverage	Vertical Res.		Horiz. Res.	Msmnt. Range	Msmnt. Accuracy	Data Latency	Refresh Rate	Timeliness
Cloud Top Phase	JPSS		Global		Cloud Top	0.75 km		Liquid/solid/ super cooled/mixed (6 categories)	80% correct classification	30 minutes after granule is available	90 minutes	\leq 3 hours
	Name		User & Priority	Geographic Coverage		Temporal Coverage Onalifiers		Product Extent Qualifier		Cloud Cover Conditions Qualifier		Product Statistics Qualifier
Cloud Top F	Phase	JPSS		Global	Day and nig	ht	65 deg	itative out to at least grees LZA and ative beyond	In presence of cl optical depth >1 conditions down associated with t accuracy	. Clear to cloud top	Over specifie geographic a	



Requirements Cloud Type

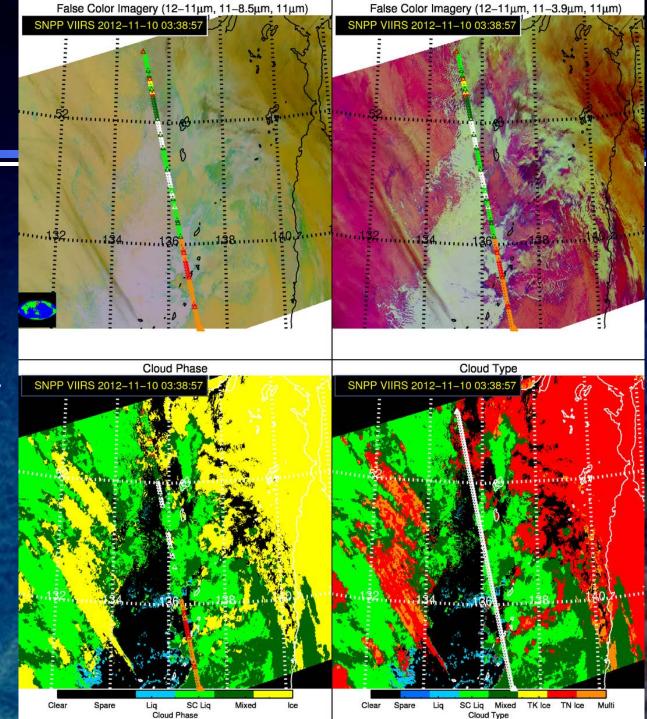
Name		User & Priority		Geographic Coverage	Vertical Res.		Horiz. Res.	Msmnt. Range	Msmnt. Accuracy	Data Latency	Refresh Rate	Timeliness
Cloud Type	JPSS	3	Globa		Cloud Top	0.75 kr	n	7 categories	60% correct classification	30 minutes after granule is available	90 minutes	≤ 3 hours
	Name	- HOLLY	User & Priority	Geographic Coverage	Qualifiers	Temporal Coverage		Product Extent Qualifier		Cloud Cover Conditions Qualifier		Product Statistics Qualifier
Cloud Type		JPSS		Global	Day and nigh	ıt	least 6	itative out to at 5 degrees LZA and tive beyond	In presence of c optical depth >1 conditions dowr top associated w threshold accura	. Clear to cloud rith	Over specific geographic a	

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Algorithm Output

S-NPP VIIRS: November 10, 2012 03:39 UTC





Validation Strategy

- Derive cloud phase and type products with full global sampling
- Collocate (in space and time) VIIRS with CALIOP (lidar)
- Combine CALIOP 1 km and 5 km vertical feature masks and convert into an equivalent passive sensor relevant cloud type using cloud object based procedure
- Perform validation with and without mixed phase clouds (the ability to identify mixed phase clouds from CALIOP is very limited)
- Generate comparative statistics and deep dive analyses



JPSS-RR Cloud Phase Validation

- The JPSS-RR cloud phase algorithm was validated using a large sampling of scenes from 2013 (provided by AIT)
- The JPSS-RR cloud phase algorithm was validated in greater detail using global VIIRS data from November 10, 2012.
- Validation was performed using collocated CALIPSO data for pixels detected as cloud from both the VIIRS and CALIPSO cloud masks.
- Validation was performed for the entire dataset but was also separated into various geographical and optical depth categories



Cloud Phase Validation – AIT Framework Output from Selected Days in 2013

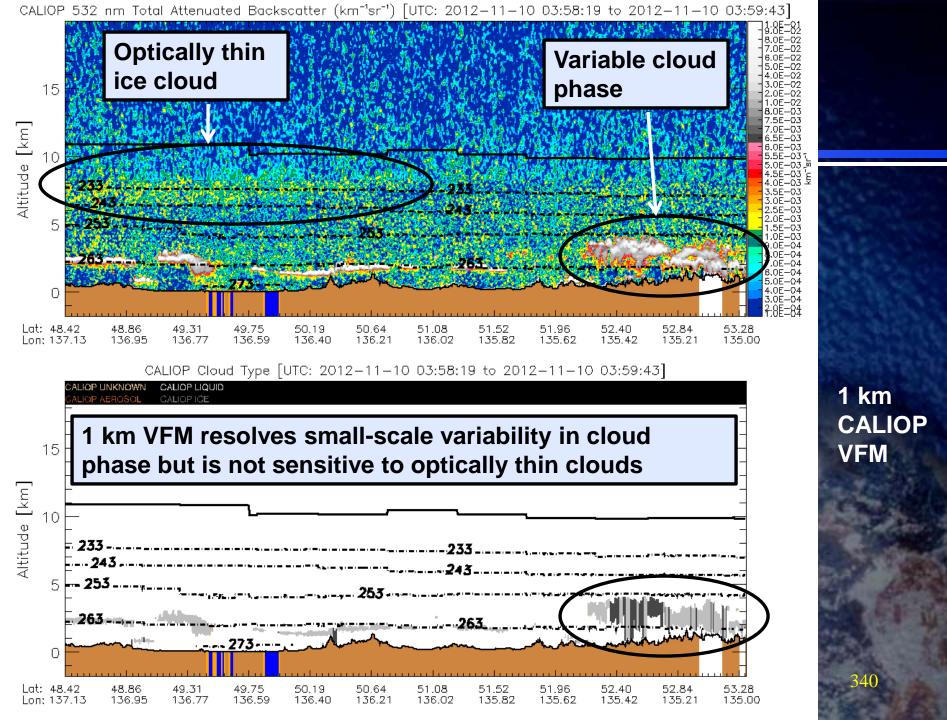
			Optical De	pth Filter	CS COM	al section	18-3-1 C
OD	>0.0	>0.1	>0.2	>0.3	>0.4	>0.5	>2.0
All data	0.826 (101144/ 122402)	0.876 (86632/ 98945)	0.882 (78632/ 89122)	0.885 (73889/ 83528)	0.885 (70792/ 79971)	0.885 (68246/ 77090)	0.849 (33375/ 39317)
Day time	0.822 (46123/ 56133)	0.875 (37517/ 42874)	0.881 (33982/ 38585)	0.880 (31653/ 35966)	0.880 (30307/ 34431)	0.880 (29267/ 33240)	0.822 (13703/ 16671)
Night time	0.830 (55021/ 66269)	0.876 (49115/ 56071)	0.884 (44650/ 50537)	0.888 (42236/ 47562)	0.889 (40485/ 45540)	0.889 (38979/ 43850)	0.869 (19672/ 22646)
Over land	0.862 (26242/ 30446)	0.897 (21655/ 24153)	0.904 (19429/ 21487)	0.907 (17766/ 19581)	0.909 (16888/ 18584)	0.910 (16193/ 17796)	0.868 (5999/ 6913)
Over water	0.815 (74902/ 91956)	0.869 (64977/ 74792)	0.875 (59203/ 67635)	0.878 (56123/ 63947)	0.878 (53904/ 61387)	0.878 (52053/ 59294)	0.845 (27376/ 32404)
Lat > 60 deg	0.860 (23218/ 26983)	0.870 (18754/ 21561)	0.873 (17127/ 19612)	0.873 (16046/ 18387)	0.873 (15407/ 17642)	0.872 (14772/ 16949)	0.782 (6264/ 8007)
Lat < 60 deg	0.817 (77926/ 95419)	0.877 (67878/ 77384)	0.885 (61505/ 69510)	0.888 (57843/ 65141)	0.889 (55385/ 62329)	0.889 (53474/ 60141)	0.866 (27111/ 31310) 338

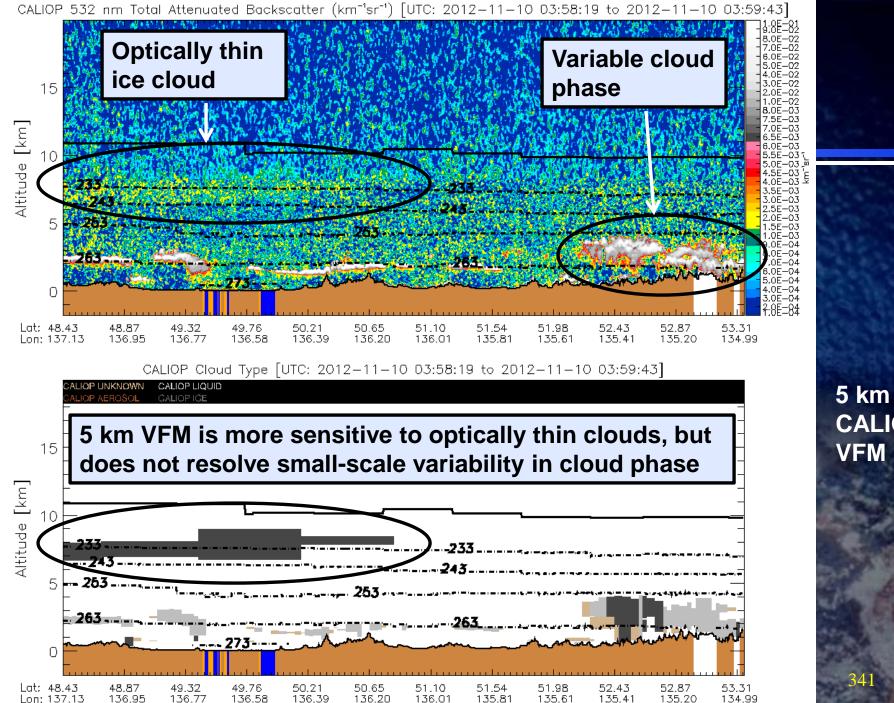


Cloud Type Validation – AIT Framework Output from Selected Days in 2013

Optical Depth Filter

OD	> 0.0	>0.1	>0.2	>0.3	>0.4	>0.5	>2.0
All	0.726 (82679/	0.778 (71968/	0.791 (65841/	0.799 (62265/	0.802 (59771/	0.805 (57802/	0.775 (28372/
data	113807)	92555)	83244)	77943)	74539)	71847)	36601)
Day	0.712 (35328/	0.775 (29527/	0.790 (27015/	0.797 (25307/	0.799 (24247/	0.803 (23514/	0.754 (11044/
time	49614)	38104)	34180)	31770)	30357)	29293)	14642)
Night	0.738 (47351/	0.779 (42441/	0.791 (38826/	0.800 (36958/	0.804 (35524/	0.806 (34288/	0.789 (17328/
time	64193)	54451)	49064)	46173)	44182)	42554)	21959)
Over	0.719 (19737/	0.753 (16429/	0.760 (14670/	0.763 (13393/	0.766 (12755/	0.768 (12261/	0.676 (4118/
Iand	27445)	21819)	19315)	17547)	16656)	15965)	6095)
Over	0.729 (62942/	0.785 (55539/	0.800 (51171/	0.809 (48872/	0.812 (47016/	0.815 (45541/	0.795 (24254/
water	86362)	70736)	63929)	60396)	57883)	55882)	30506)
Lat > 60 deg	0.803 (15903/ 19805)	0.844 (13560/ 16063)	0.865 (12557/ 14514)	0.876 (11874/ 13556)	0.881 (11399/ 12945)	0.884 (10980/ 12426)	0.837 (4846/ 5789)
Lat < 60 deg	0.710 (66776/ 94002)	0.764 (58408/ 76492)	0.775 (53284/ 68730)	0.783 (50391/ 64387)	0.785 (48372/ 61594)	0.788 (46822/ 59421)	0.764 (23526/ 30812) 339





CALIOP

Cloud Phase Validation – November 10, 2012 With Mixed Phase

Optical Depth Filter

Applica

OD	>0.01	>0.05	>0.10	>0.50	>1.0	>2.0
All data	0.767(46191)	0.769(41576)	0.763(38866)	0.729(30593)	0.696(25574)	0.631(19139)
Water	0.752(34387)	0.751(30894)	0.742(28908)	0.707(23290)	0.679(19936)	0.626(15581)
Land	0.812(11804)	0.822(10682)	0.823(9958)	0.797(7303)	0.756(5638)	0.656(3558)
Desert	0.753(4385)	0.756(3880)	0.748(3582)	0.668(2270)	0.538(1513)	0.347(974)
Lat > 60 deg	0.702(16064)	0.693(14729)	0.684(14010)	0.625(10946)	0.560(8881)	0.467(6724) 342

Cloud Phase Validation – November 10, 2012 Without Mixed Phase

Optical Depth Filter

Applica

OD	>0.01	>0.05	>0.10	>0.50	>1.0	>2.0
All data	0.910(37467)	0.919(33317)	0.920(30802)	0.912(23062)	0.904(18374)	0.878(12493)
Water	0.902(27489)	0.910(24311)	0.908(22453)	0.899(17206)	0.892(14107)	0.870(10189)
Land	0.933(9978)	0.944(9006)	0.949(8349)	0.950(5856)	0.943(4267)	0.915(2304)
Desert	0.951(3398)	0.959(2984)	0.960(2720)	0.963(1510)	0.952(795)	0.919(309)
Lat > 60 deg	0.932(11271)	0.931(10144)	0.928(9522)	0.914(6699)	0.893(4791)	0.853(2904) 343

Cloud Type Validation – November 10, 2012 With Mixed Phase

Optical Depth Filter

te Applica

OD	>0.01	>0.05	>0.10	>0.50	>1.0	>2.0
All data	0.518(48767)	0.540(43794)	0.548(40579)	0.577(31638)	0.586(26467)	0.556(19795)
Water	0.525(36497)	0.545(32679)	0.549(30271)	0.573(24094)	0.585(20647)	0.563(16124)
Land	0.498(12270)	0.526(11115)	0.545(10308)	0.591(7544)	0.590(5820)	0.524(3671)
Desert	0.487(4561)	0.513(4055)	0.528(3730)	0.541(2370)	0.475(1572)	0.300(1006)
Lat > 60 deg	0.463(16965)	0.471(15512)	0.474(14650)	0.487(11335)	0.467(9200)	0.395(6951) 344

NESDIS ST

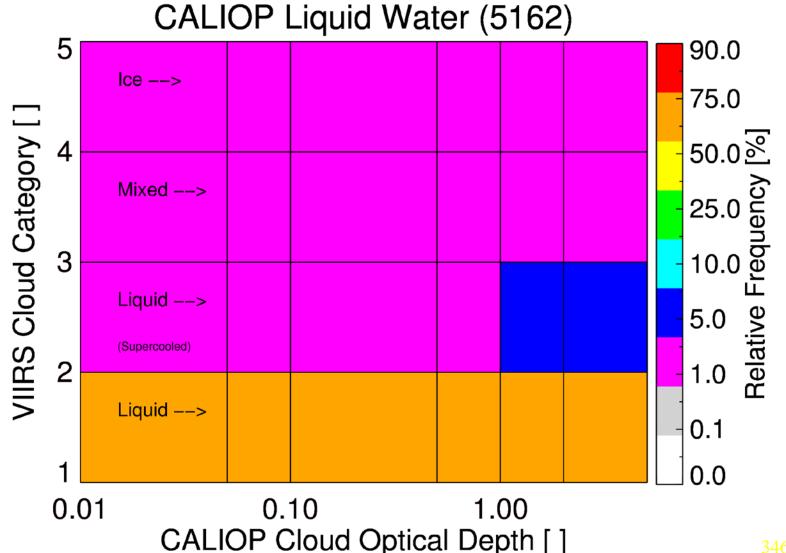
⁹ Applica

Cloud Type Validation – November 10, 2012 Without Mixed Phase

Optical Depth Filter

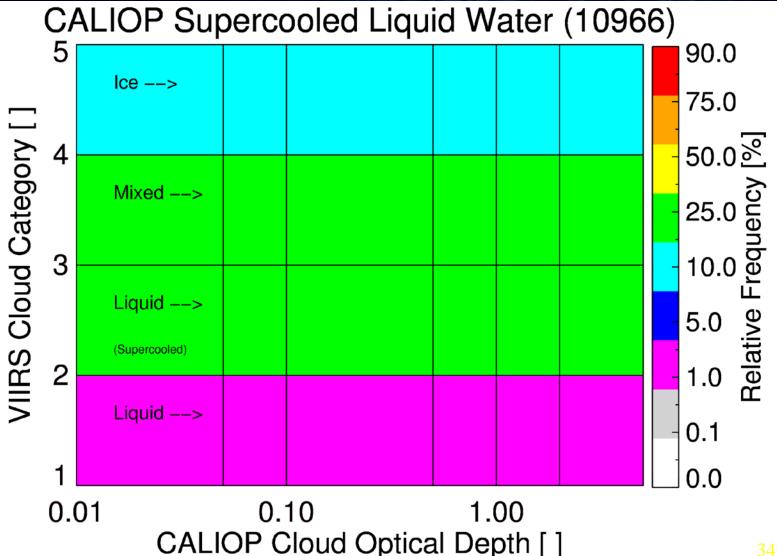
OD	>0.01	>0.05	>0.10	>0.50	>1.0	>2.0
All data	0.631(37483)	0.659(33620)	0.671(31237)	0.731(23718)	0.772(18991)	0.788(13026)
Water	0.647(27605)	0.676(24620)	0.684(22842)	0.739(17710)	0.783(14565)	0.802(10578)
Land	0.584(9878)	0.613(9000)	0.635(8395)	0.709(6008)	0.735(4426)	0.726(2448)
Desert	0.631(3334)	0.668(2949)	0.695(2702)	0.807(1530)	0.860(817)	0.830(329)
Lat > 60 deg	0.627(11313)	0.642(10286)	0.654(9718)	0.730(6988)	0.769(5064)	0.760(3134) 345

When CALIOP indicates warm liquid water, the VIIRS algorithm generally agrees (most disagreements fall into supercooled liquid water category)



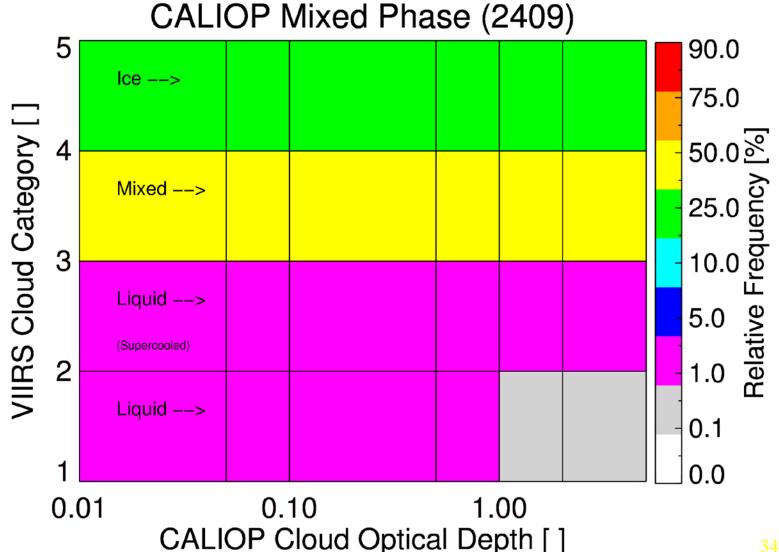


When CALIOP indicates supercooled liquid water, the VIIRS algorithm generally classifies clouds as supercoooled liquid or mixed phase



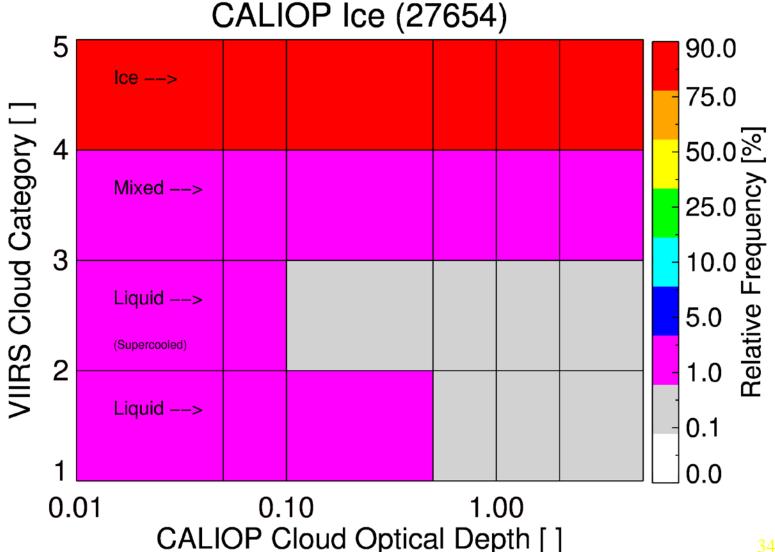


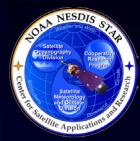
When CALIOP indicates mixed phase, the VIIRS algorithm generally agrees (most disagreements fall into ice phase category)



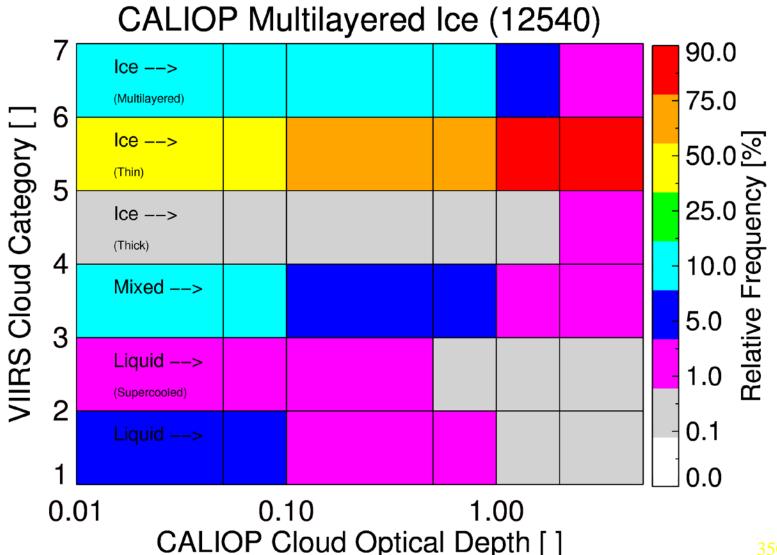


When CALIOP indicates ice phase, the VIIRS algorithm generally agrees (most disagreements fall into mixed phase category)

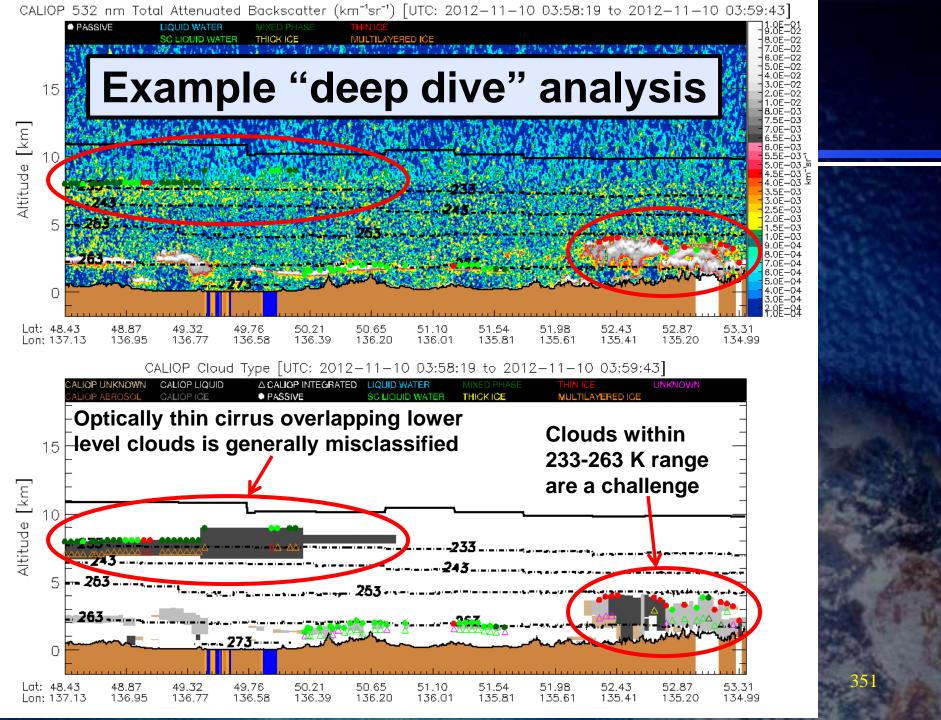




When CALIOP indicates multilayered ice, the VIIRS algorithm has a difficult time identifying the cloud as multilayered ice



50



Summary of Validation Results for VIIRS Cloud Phase and Type Products

- The NPP/VIIRS cloud phase and type products have been validated against cloud phase/type products derived from spaceborne lidar measurements
- Taking into account the uncertainty in the lidar derived products, the VIIRS cloud phase/type products fall within the accuracy specifications without invoking the cloud optical depth qualifier
- As shown by the GOES-R AWG, infrared absorption channels are important for identifying multilayered cloud systems and optically thin cirrus clouds. For JPSS, this can only be achieved by combining VIIRS and CrIS measurements.



Andrew Heidinger (presenting), Ruiyue Chen, Yue Li, Jay Hoffman and William Straka

AWG CLOUD HEIGHT ALGORITHM (ACHA) VALIDATION – ALGORITHM READINESS REVIEW (ARR)



ARR Data

- We processed the equivalence of one day's worth of data (≈1000 granules) in 2013 through ACHA implemented in the Framework/SAPF.
- These granules are chosen to be co-located with CALIPSO and spread over all seasons.
- We run our CALIPSO and VIIRS validation tools on these data to demonstrate compliance with the L1RD requirements.
- Collocated MODIS Collection 6 data are used as an additional source of verification.
- The same analysis is done with CLAVR-x.



ACHA Products

• CTT = Cloud-top Temperature

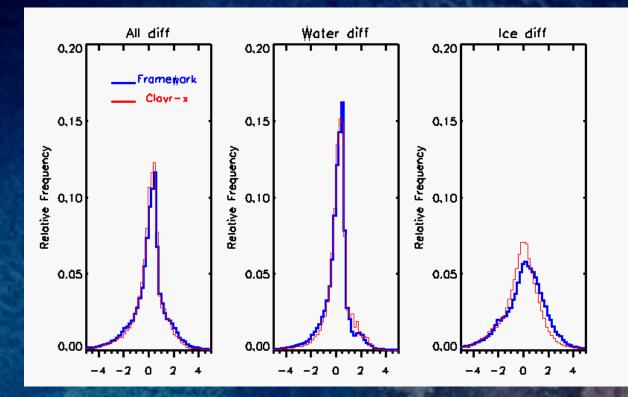
- CTH = Cloud-top Height
- CTP = Cloud-top Pressure

Attribute Analyzed	L1RD Threshold (accuracy = precision)
СТТ	3K when $\tau \ge 1$, 6K when $\tau < 1$
СТН	1km when $\tau \ge 1$, 2km when $\tau < 1$
СТР	$\tau \ge 1$: 100mb for [0,3km], 75mb for [3,7km], 50mb for > 7km

CTH ACHA/CLIPSO comparisons, Phase-matched

Differences can be attributed to:.

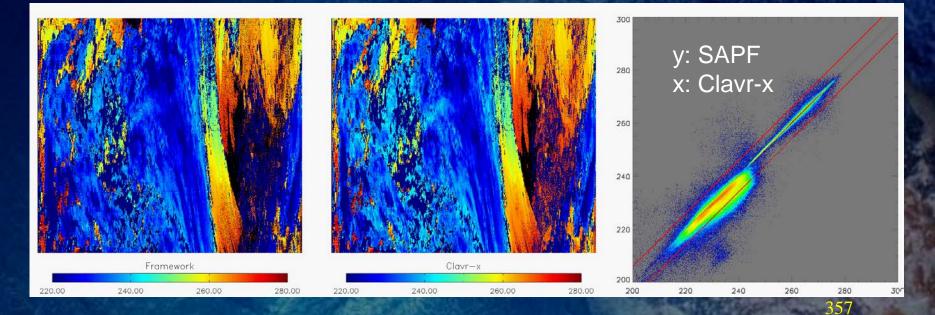
- Radiative transfer models
- NWP data
- Controlling flags such as NWP smoothing





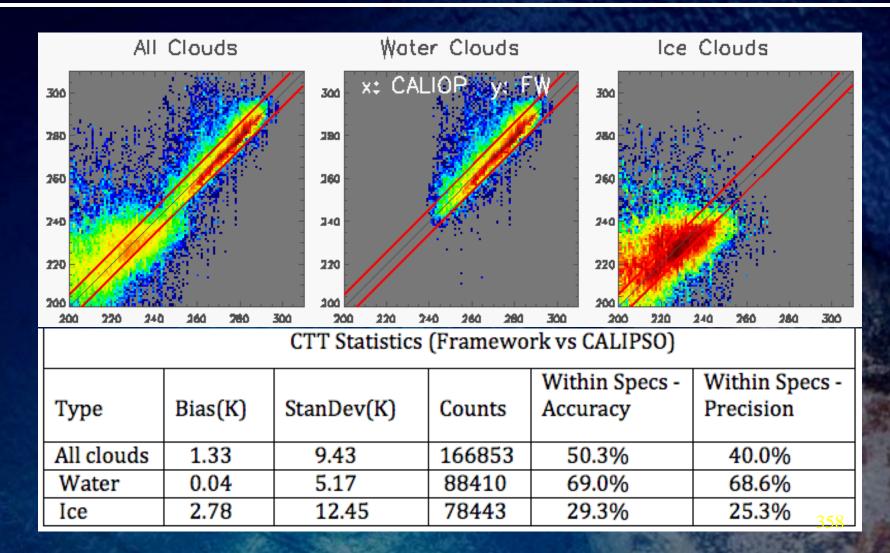
Example Granule, Phasematched

- This granule shows comparison of phasematched CTT dated 01/13/2013 at 1531 UTC.
- Both the spatial distribution and scatter plot indicate good agreement between the two datasets.



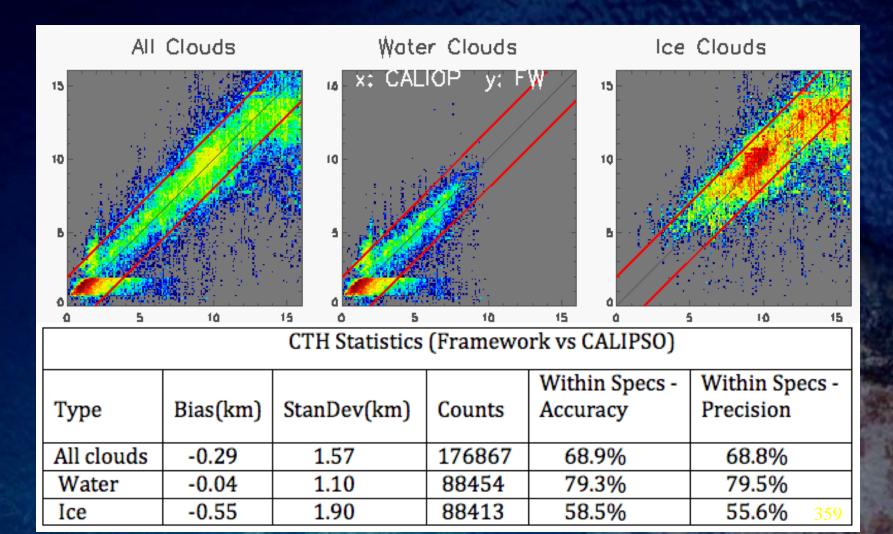


CTT - SAPF vs. Calipso



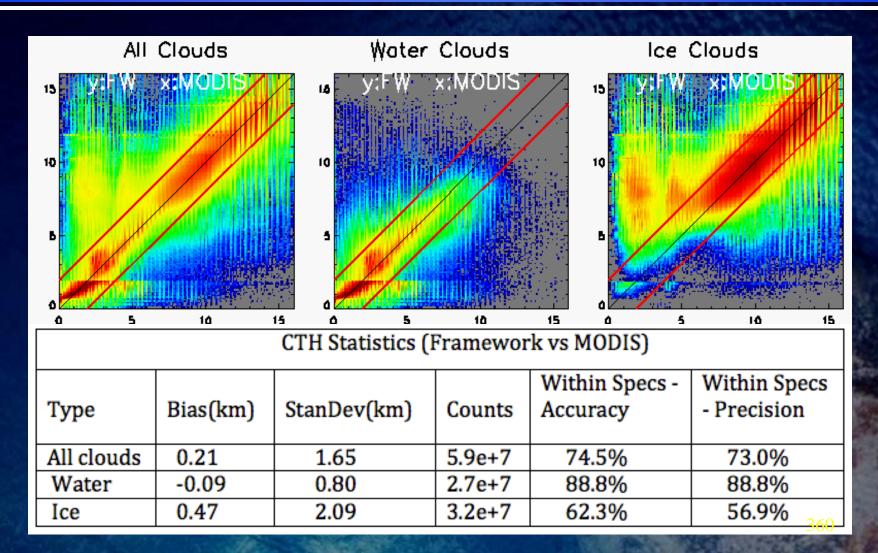


CTH - SAPF vs. Calipso



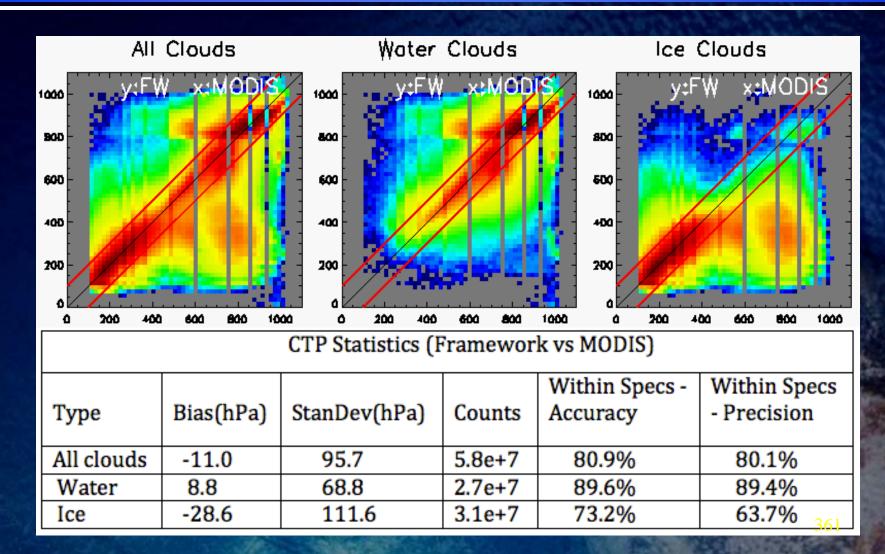


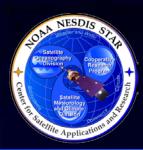
CTH - SAPF vs. MODIS





CTP - SAPF vs. MODIS





CTH Statistics based on different latitude regions

- The best performance is for water clouds over tropics.
- There are less pixels available for comparison over the polar regions; however, ACHA performance is nearly as good as in non-polar regions.

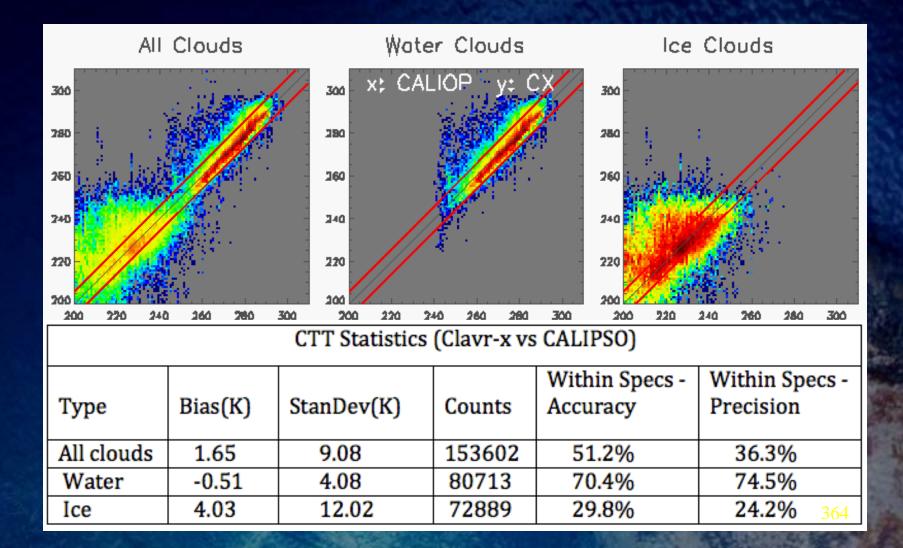
CTH Statistics (Framework vs Calipso)									
Region	Туре	Bias(km)	StanDev	Counts	Within Specs - Accuracy	Within Specs - Precision			
Region	Type	Dias(kiii)	(km)	counta	necuracy	TTCCISION			
	Water	-0.27	1.20	29655	83.1%	84.6%			
Tropical	Ice	-1.06	2.19	40809	53.6%	51.3%			
MidLat	Water	-0.07	1.03	58799	77.4%	77.2%			
	Ice	-0.11	1.47	47604	62.8%	62.1%			
Polar	Water	-0.01	1.09	11749	73.5%	73.4%			
	Ice	0.46	1.75	14381	58.2%	59.8 <mark>%</mark>			

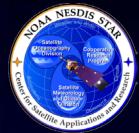


Additional Verification of CTH using Clavr-x data

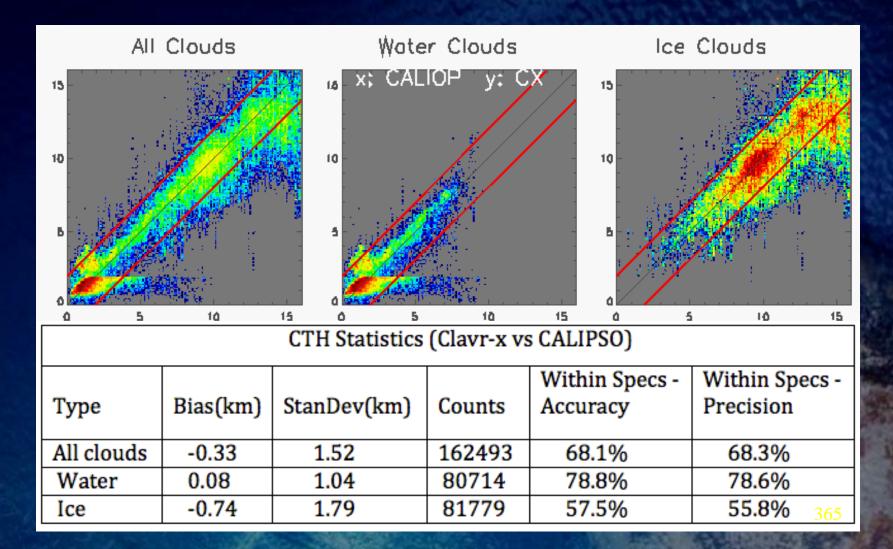








CTH – Clavr-x vs. Calipso





Summary

- Cloud top parameters generated from thousand granules in ACHA/Framework are evaluated by comparing to two independent sources – Calipso and MODIS Collection 6
- Clavr-x output from the same granules are also evaluated for comparison purpose
- It is believed ACHA is implemented correctly in Framework and the performance meets expectation
- Differences still exist between Framework and Clavr-x but this does not affect performances



Daytime Cloud Optical and Microphysical Products

Presented by Andi Walther CIMSS





DCOMP

- » DCOMP is the Daytime Cloud Optical and Microphysical Properties algorithm of the NOAA-AWG retrieval scheme PATMOS-x.
- » DCOMP was developed for GOES-AWG and works presently on VIIRS, MODIS, GOES, SEVIRI, MSAT, GOES-ABI and others.
- » DCOMP is a FORTRAN 90/95 package which works with the identical code for all sensors and software environments (e.g. CLAVR-x, GEOCAT, FRAMEWORK).
- » DCOMP was evaluated and validated in several intercomparison cloud workshops with products of 8 other stateof-the-art algorithms.
- » DCOMP in FRAMEWORK has been slightly adjusted to compiler requirements (gfortran 9.4)

Daytime Cloud Optical Microphysical Properties Overview

- » Products : Cloud Optical Thickness (COD) and Cloud Particle Size (CPS)
- » Derived products from COD and REF: Liquid water path (LWP) and Ice Water Path (IWP)
- » VIIRS SAPF mode is DCOMP-2. Use of channel combination at 0.6 and 2.2 micron (M5/M11)
- » RTM-independent.
- » DCOMP input:
 - Reflectance
 - Radiance
 - Cloud detection
 - Cloud top temperature, Cloud height
 - Cloud Phase
 - Static Aux data (white sky surface albedo, GFS temperature and humidity profiles, snow mask)



Requirements

	Requirements				
Product	Range	Accuracy	Precision		
COD	0.5-50	2 or 20% (liquid) 3 or 30% (ice)	2 or 20% (liquid) 3 or 30% (ice)	> 65 degree solar zenith	
CPS	0-50 µm	4µm /10µm (liquid/ice)	4µm /10µm	> 65 degree solar zenith	
LWP		50g/m2	30%	> 65 degree solar zenith	
IWP		100g/m2	40%	> 65 degree solar zenith	

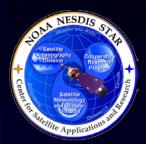


DCOMP : ARR Validation Strategies

- Retrieval uncertainties of other parameters (e.g. Cloud mask, phase height, snow mask) will heavily affect uncertainty in DCOMP retrievals. As an example, in the event of false classification of cloud phase, COD can be wrong by 50% [Wolters et al. 2008].

• ARR validation strategy:

- Visual inspection of mapped images animations and histograms to detect obvious artifacts
- MODIS Science team provides COD and CPS in collection 6. We directly compare approx.1000 granules from SAPF Framework.
- To overcome colocation errors we additionally compare DCOMP results run in CLAVR-x on MODIS level1b data to compare directly to MYD06 c6 products.
- Only for liquid clouds, the use of *passive microwave retrievals* constrain the possible solutions for COD and CPS. Validation of LWP is therefore an71 indirect validation of COD and CPS.

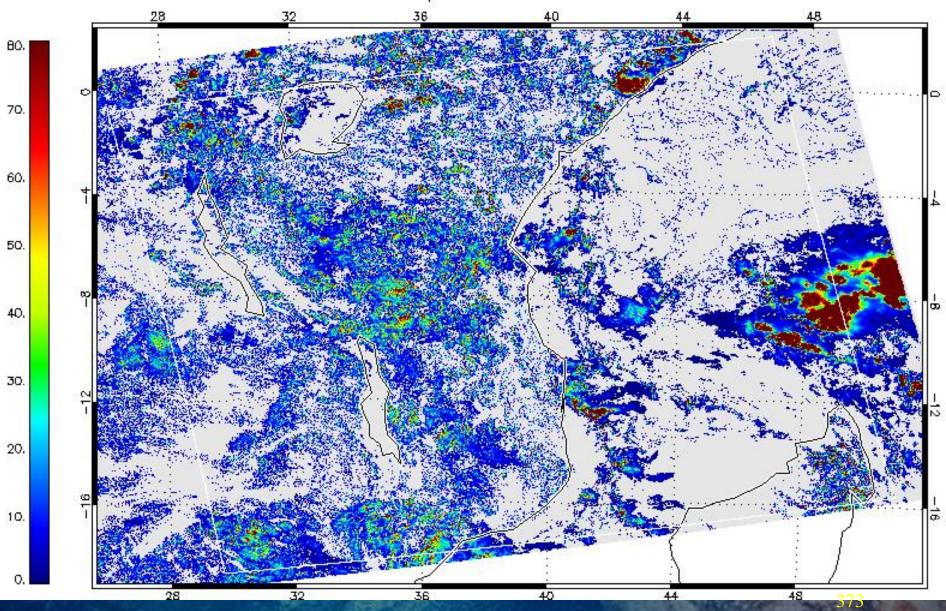


Validation with co-located MODIS-AQUA products

- MODIS Science team collection 6 products on AQUA for COD and CPS.
- Data used 10 days of all seasons. Daytime scenes for about 200 scenes.
- Problems/Challenges:
 - MODIS and VIIRS have different spatial resolution.
 - Spatial and temporal **co-location** differences (windows are 2km and 120sec)
 - MODIS approach is similar to DCOMP approach. The MODIS products are therefor **not** an **independent** validation source.
 - Basic assumptions may be different (cloud phase, cloud height, surface conditions). These assumptions are beyond control of DCOMP and have to be tested/validated outside this ARR
 - Calibration differences between MODIS-AQUA and NPP suspected (personal communication with S. Platnick)
 - Thus, perfect match cannot be expected
- <u>Solutions:</u>
 - The 1:1 comparisons shouldn't seen as validation/performance truth.
 - COD-CTP joint histograms
 - Compare only results with same phase

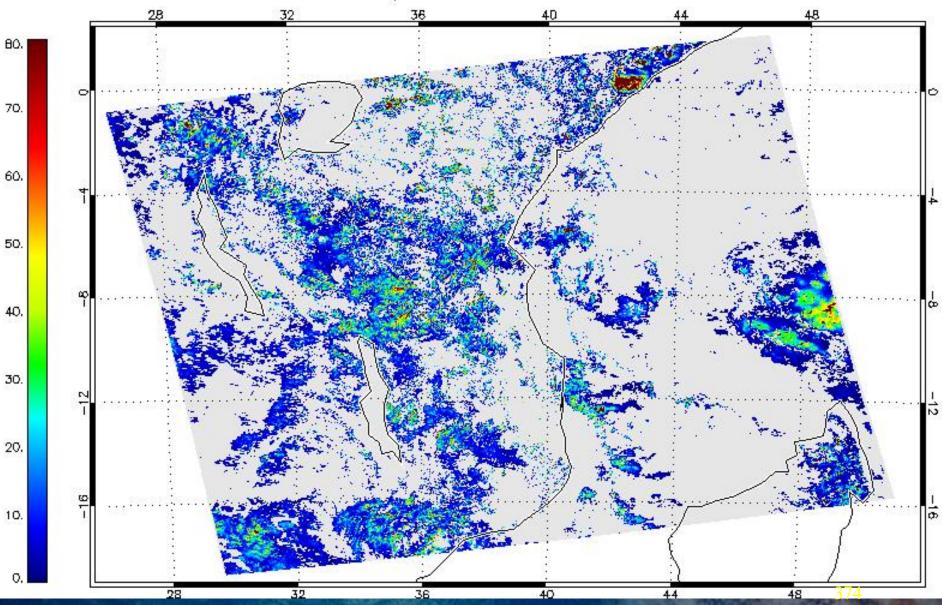


Cloud Optical Thickness SAPF



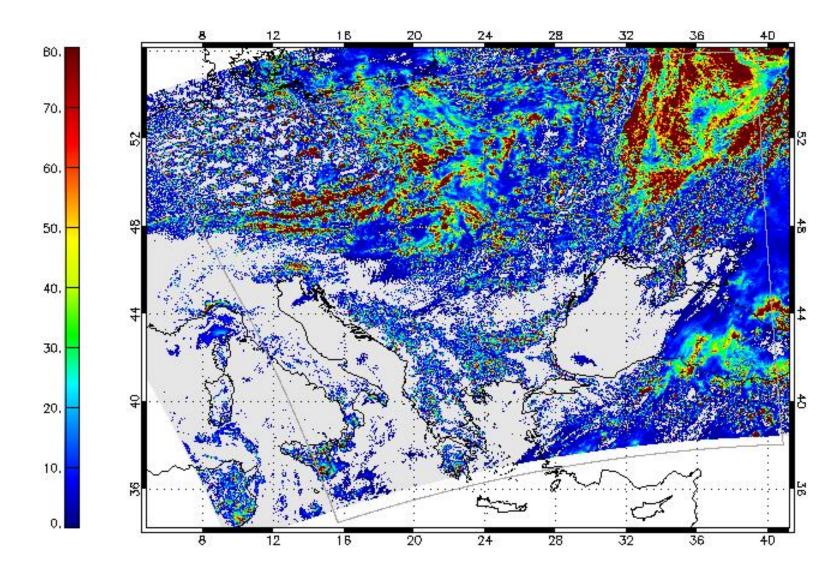


Cloud Optical Thickness MST Coll.6



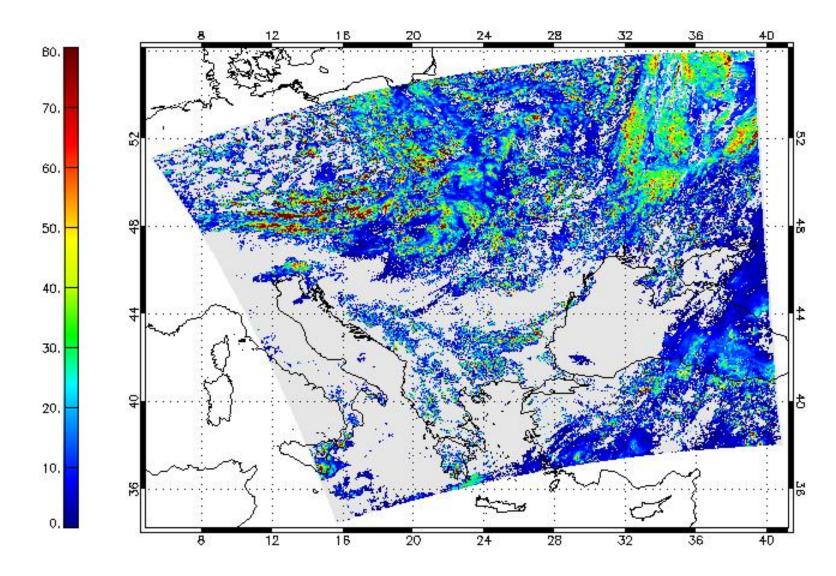


Cloud Optical Thickness SAPF



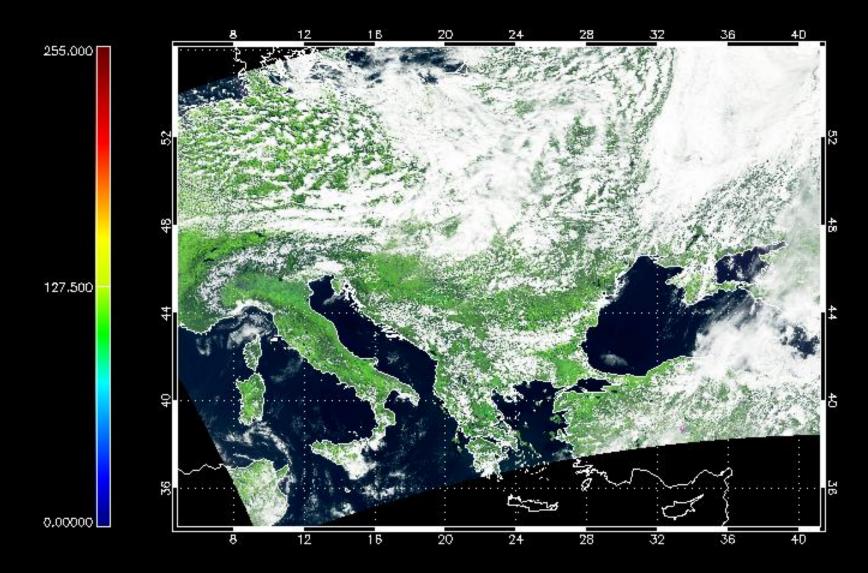


Cloud Optical Thickness MST Coll.6



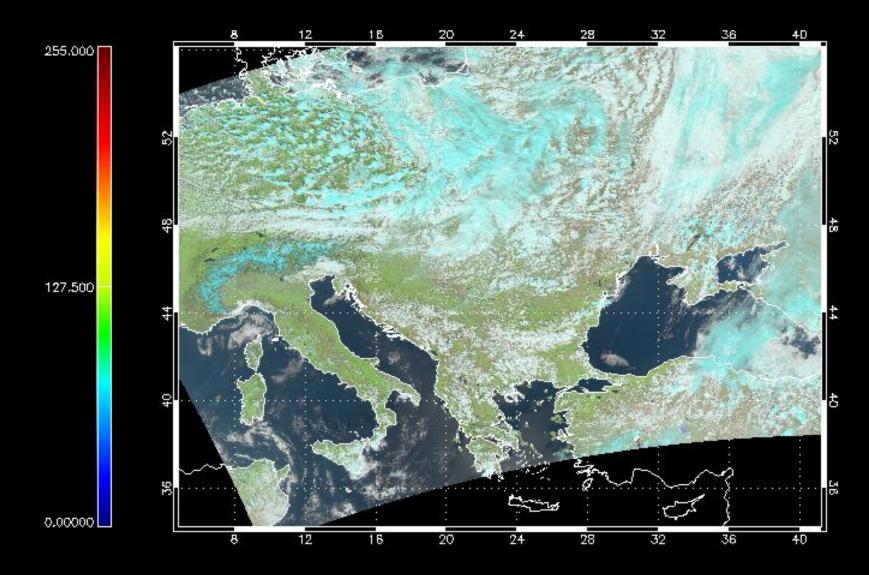


RGB: true color : ir016 / vis008 / vis006



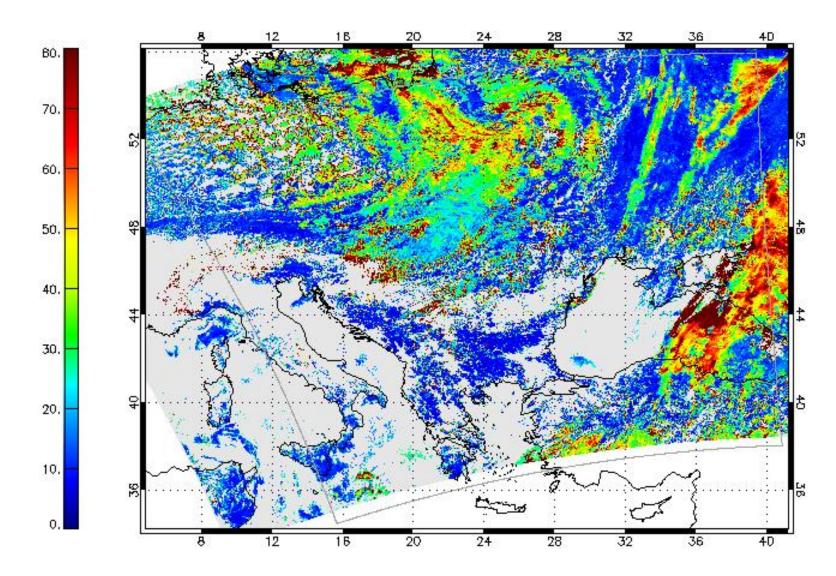


RGB: true color enhanced



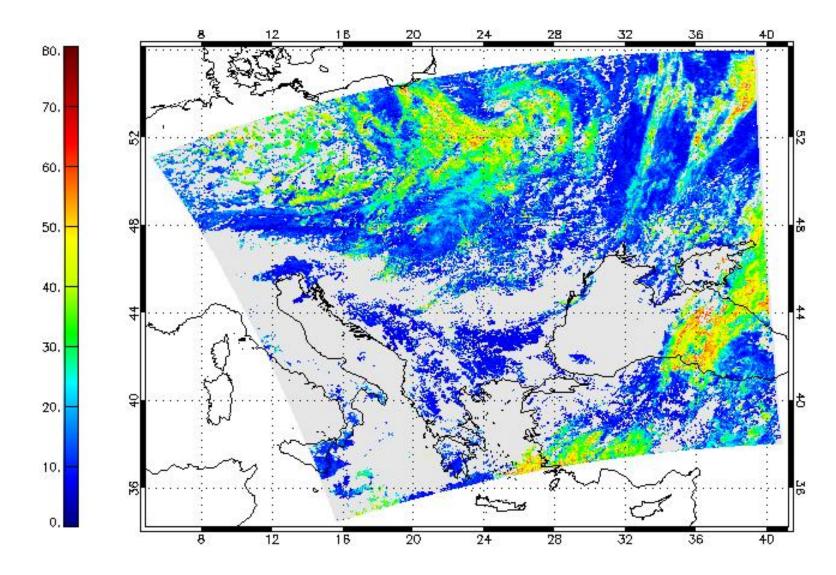


Effective Rodius SAPF



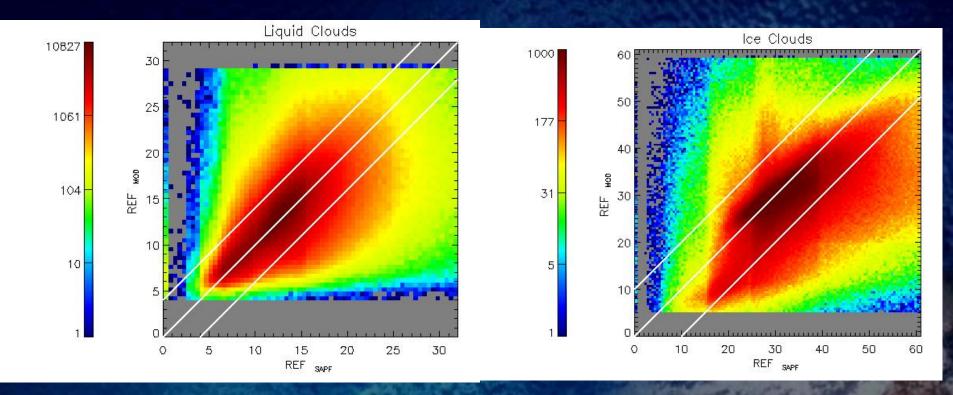


Effective Radius MST Coll.6





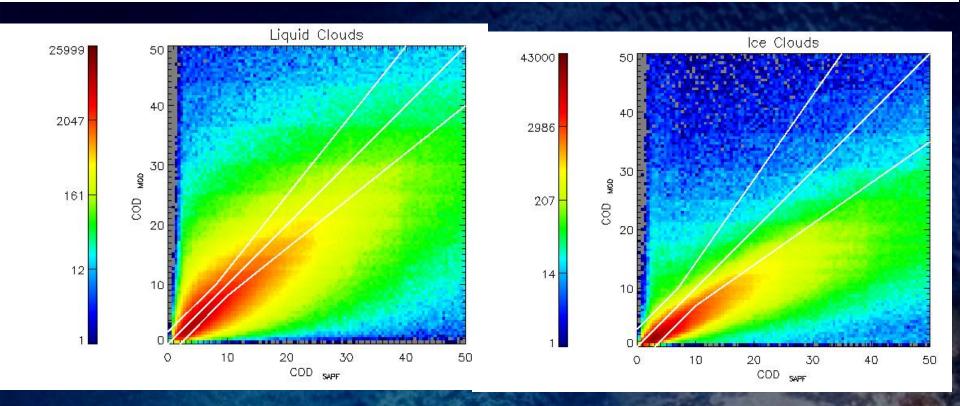
Validation results REF vs. MODIS c6



Accuracy: 0.29µm , 5.8% Precision: 4.7µm Correlation: 0.55 Accuracy: 5.91µm , 10.2% Precision: 11.5µm Correlation: 0.42



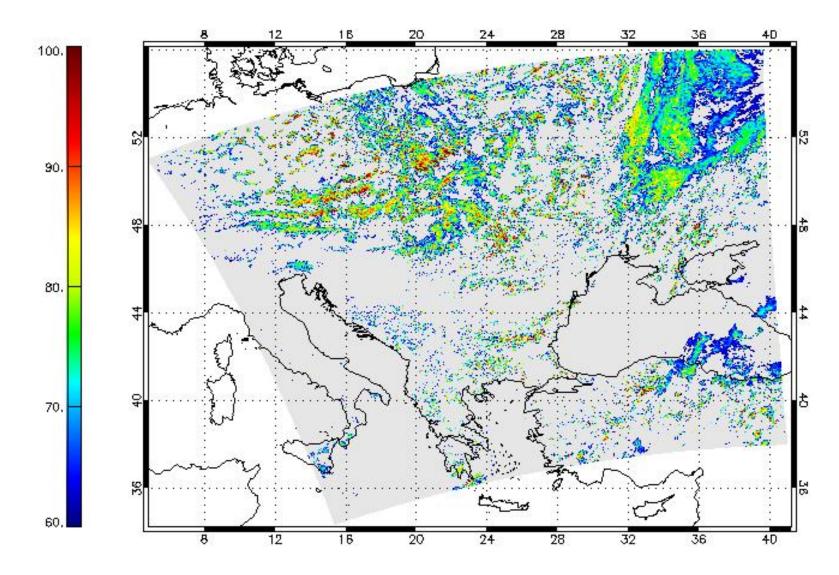
Validation results COD vs. MODIS c6



Accuracy: 2.67, 3.2% Precision: 8 Correlation: 0.71 Accuracy: 5.66 , 35 % Precision: 7.6 Correlation: 0.77

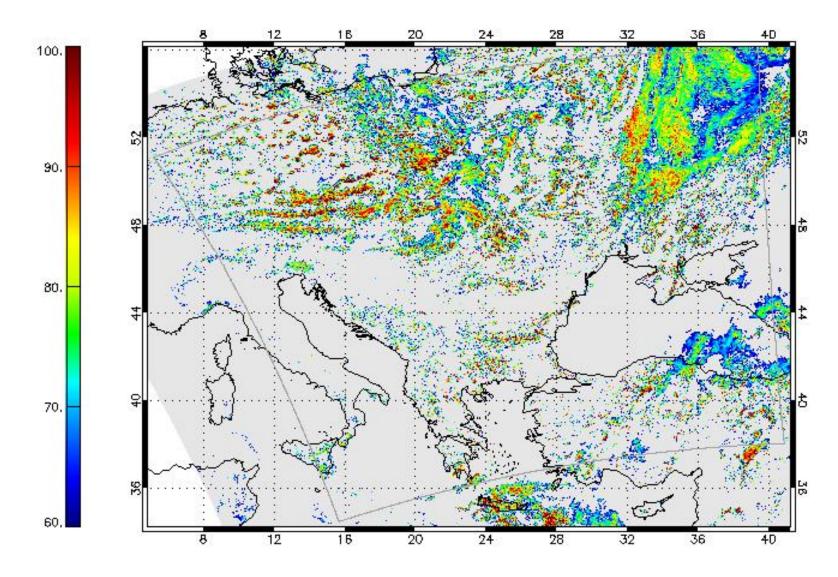


Visible Reflectance MODIS



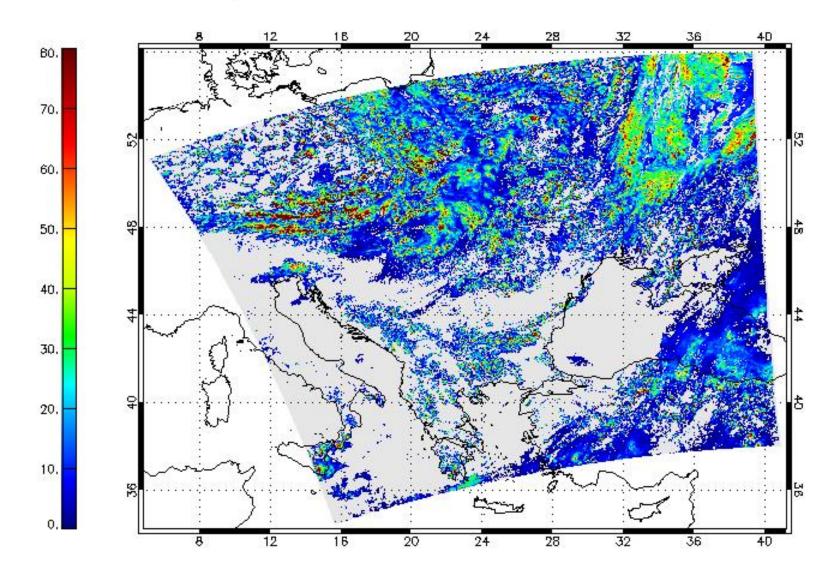


Visible Reflectance VIIRS



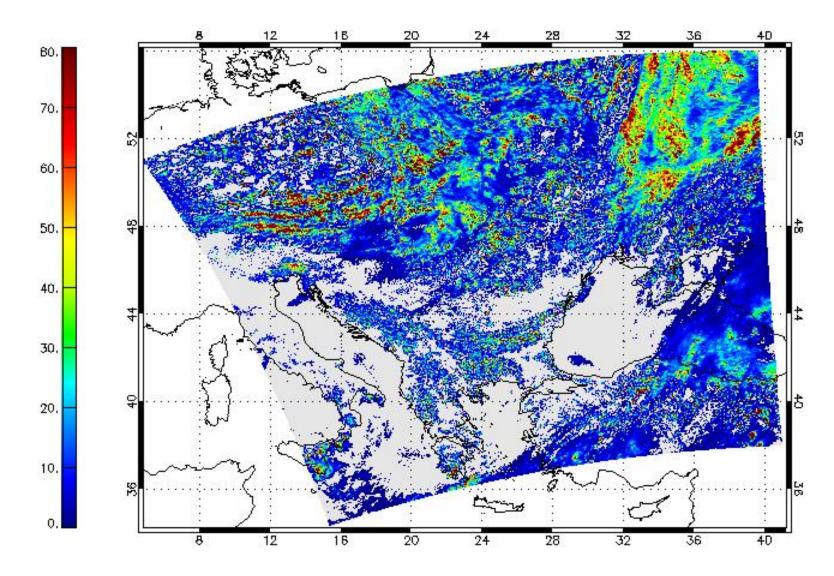


Cloud Optical Thickness MST Coll.6 MODIS



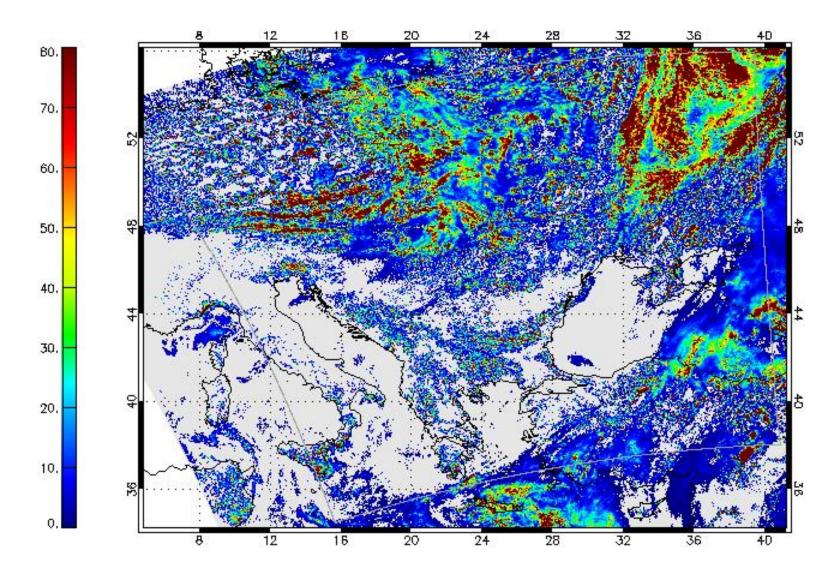


Cloud Optical Thickness CLAVR-x MODIS



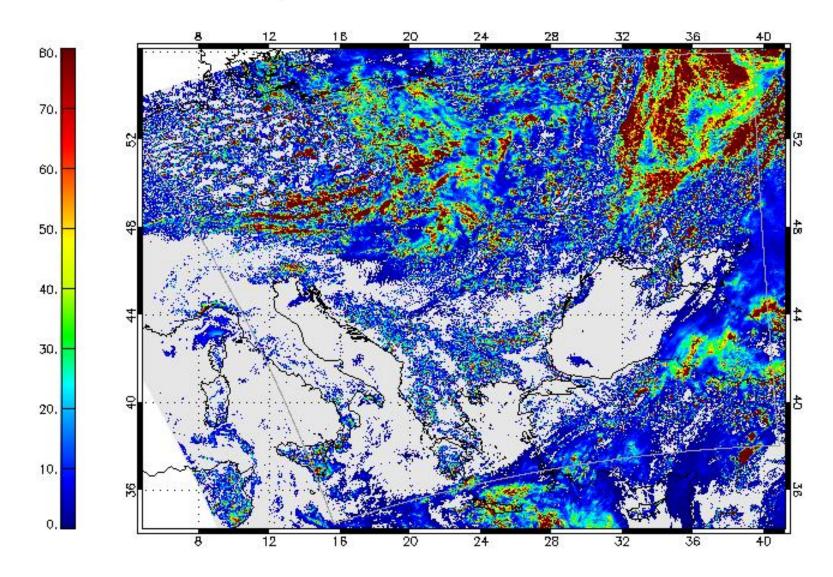


Cloud Optical Thickness CLAVR-x VIIRS



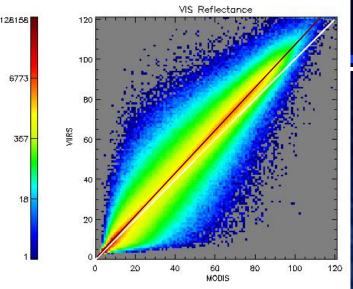


Cloud Optical Thickness SAPF VIIRS

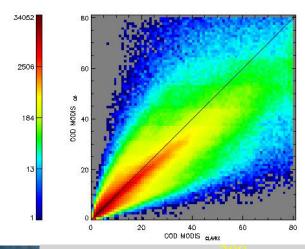


Discussion

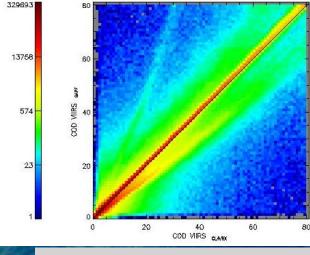
- Reflectance of 0.64 micron channels on MODIS and VIIRS seems to be inconsistent. (Geometry for both sensors are very similar for this case)
- Small changes in Reflectance for thick clouds → high impact on COD
- Since DCOMP runs as exact same code on both sensors we checked direct pixel-based results on VIIRS for CLAVR-x vs. SAPF and on MODIS for CLAVR-x and MST coll.6 and found very good agreement.



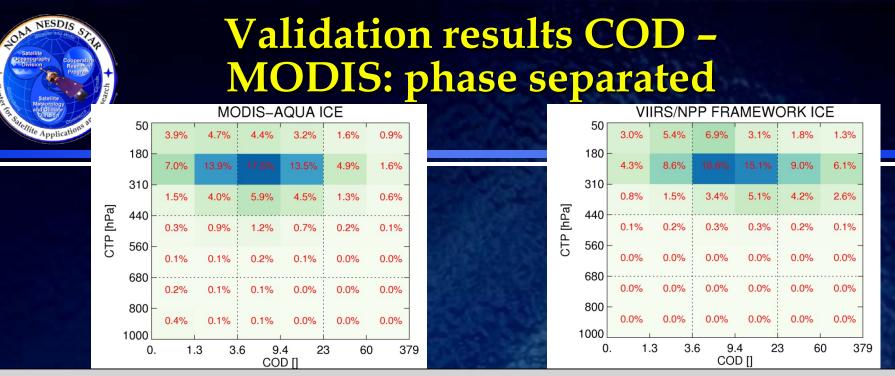
Co-located visible reflectance for MODIS-AQUA and VIIRS



COD on MODIS-AQUA: CLAVR-x vs. MAST coll.6

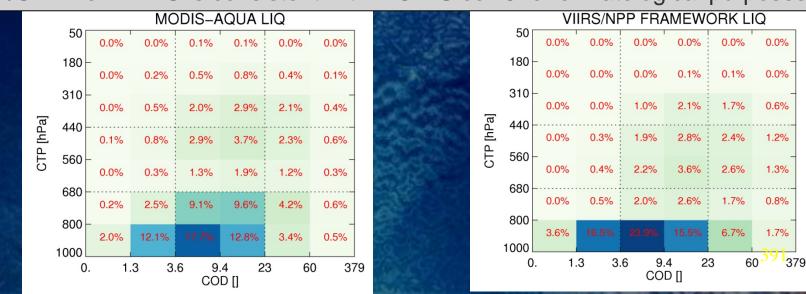


COD on VIIRS- CLAVR-x vs. SAPF (The TRR experiment)

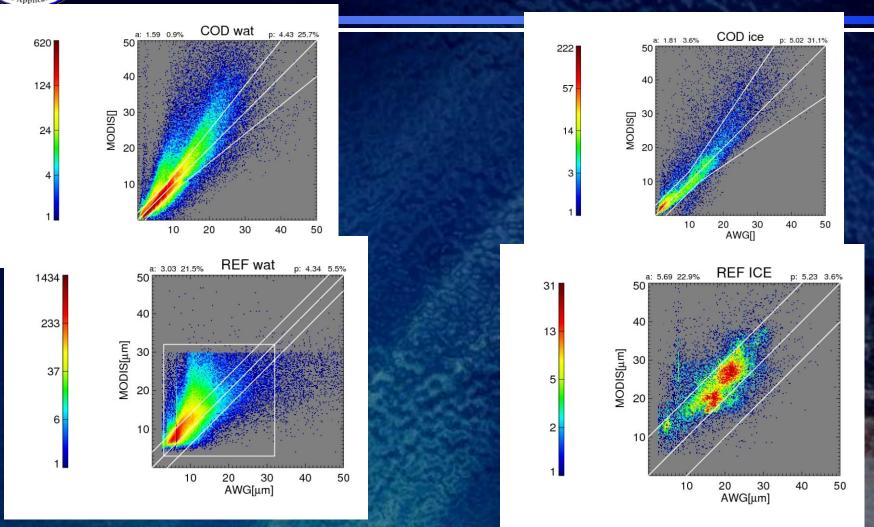


Conclusion:

DCOMP/SAPF on VIIRS is consistent with MODIS coll.6 for climatological purposes



DCOMP/MODIS on CLAVRx vs. MODIS coll.6



Comparison of DCOMP to MODIS (MYD06) products for 10,2 full days. White lines depict requirement limits.



DCOMP on CLAVR-x: Liquid water path validation

Microwave satellite based sensors offer a further validation source Validation is limited due to coarse spatial resolution and to only liquid phase sensitivity We apply several filter criteria:

- 90% of DCOMP pixels must be covered by liquid clouds
- MW is insensitive to thin clouds. We exclude clouds thinner than COD = 5.
- We exclude all MW pixels with rain flag.

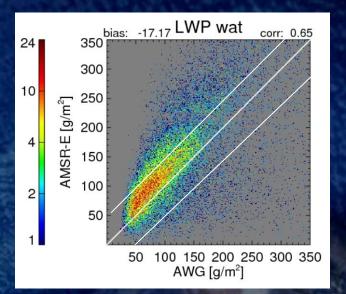


Image shows that 90 percent of pixels are within the 50 g/m2 spec.



DCOMP on CLAVR-x: Validation Summary

Product	Validation	Accuracy	Specs	Precision	Specs
	Source				
COD Water	MODIS	1.59/0.9%	2. or 20%	4.43/25.7%	2. or 20%
COD Ice	MODIS	1.81/3.6%	3. or 30%	5.02/31.1%	3. or 30%
CPS Water	MODIS	3.03µm	4µm	4.3µm	4µm
CPS Ice	MODIS	5.69µm	10µm	5.23µm	10µm
LWP	MODIS	10g/m2	50 g/m2	17 g/m2	50 g/m2
LWP	AMSR-E	17 g/m2	50 g/m2	47 g/m2	50 g/m2
IWP	MODIS	44 g/m2	100 g/m2	65 g/m2	100 g/m2

Validation summary for DCOMP in comparison to MODIS science team results.

Accuracy is met for all validation studies.

Precision is met for Water content and for Effective Radius (CPS-Cloud Particle Size). (Reasons may be spatial and temporal matching, different calibration and wrong assumptions of cloud height for atmospheric correction)



Conclusions

- Visual inspection of mapped images doesn't show any obvious errors, such as apriori peaks or artificial erroneous pattern.
- SAPF DCOMP products were validated against MODIS collection 6 and microwave data
- **COD:** Liquid clouds meet the specs for validation with MODIS. Ice clouds have a significant bias for thicker clouds and don't meet the spec there.
- **CPS:** DCOMP meets the accuracy specs for both phases. Precision is slightly outside the spec threshold.
- However, The MODIS coll.6 cannot be seen as "truth" because:
 - » Collocation uncertainty (up to 3 km and 120 seconds) may have a significant impact to precision and accuracy
 - » Different spatial resolution of both sensors (a 1-km COD is something different than a 4-km COD)
 - We could show that reflectance values in 0.64µm channels differ up to 8 percent. There might be similar difference in 2.2µm channels (It is harder to show, because SRF are not that close to identical). This has a huge impact especially to thick cloud retrievals.
- Direct comparisons of DCOMP on MODIS L1b data (vs. MYD06) and VIIRS (vs. SAPF) show good agreement.



VIIRS Nighttime Cloud and Optical Properties Algorithm Readiness

Presented by

Patrick Heck

UW-Madison CIMSS





- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS NCOMP Product.



VIIRS NCOMP Product Overview & Requirements

- VIIRS Nighttime Cloud Optical and Microphysical Properties will be derived by matching observed VIIRS thermal channels (Band M12, M15 and M16 – 3.7µm, 10.8µm and 12µm) to modeled radiances and minimizing errors using an iterative technique.
 - » Cloud Optical Depth, Cloud Particle Size, Liquid Water Path and Ice Water Path are derived for nighttime and twilight cloudy pixels. Only nighttime pixels (Solar Zenith Angle ≥ 90°) are required to meet validation specs.
 - » NCOMP products are generated for Viewing Zenith Angle < 72°</p>
 - » The product will include location, time, data quality and processing flags, and other metadata



VIIRS NCOMP Product Overview & Requirements (2)

VIIRS NCOMP products and requirements

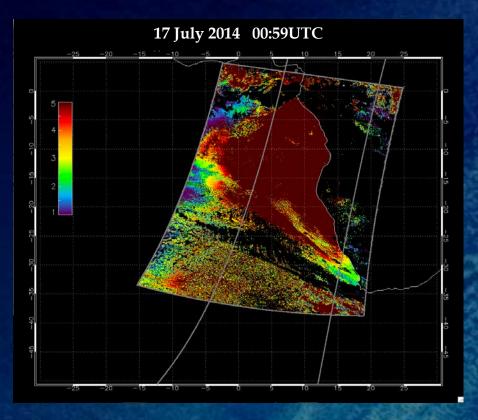
Product	Range	Accuracy	Precision
COD	1.0 - 5.0	30%	Max of 0.8 or 30%
CPS	2 – 32 µm (liquid) 2 – 50 µm (ice)	Max of 4 µm or 30% (liquid) 10 µm (ice)	Max of 4 µm or 25% (liquid) 10 µm or 25% (ice)
LWP	25 – 100 g/m2	Greater of 25 g/m2 or 15%	Greater of 25 g/m2 or 40%
IWP	25 – 175 g/m2	Greater of 25 g/m2 or 30%	Greater of 25 g/m2 or 40%

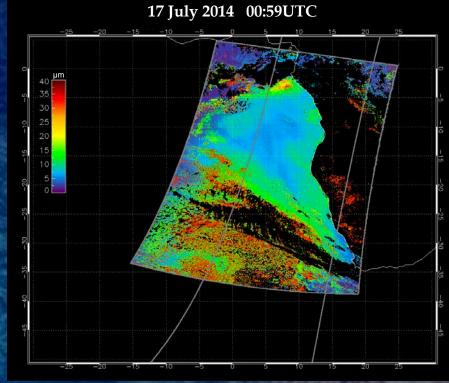


Algorithm Output

Cloud Optical Depth

Cloud Particle Size





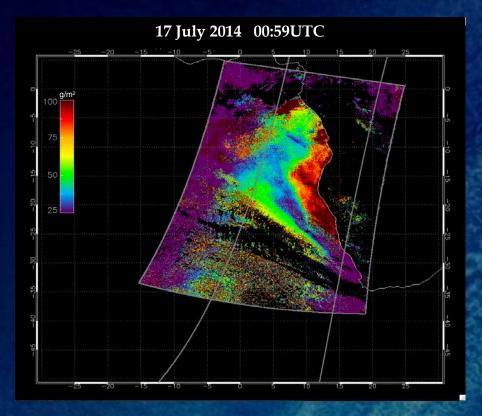
400

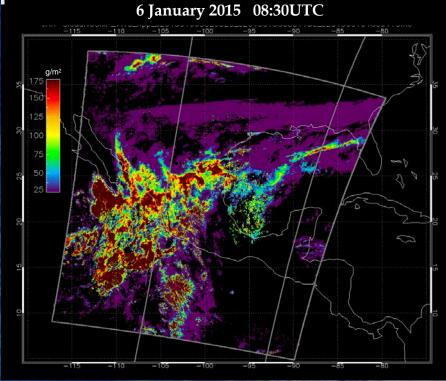


Algorithm Output (2)

Cloud Liquid Water Path

Cloud Ice Water Path





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Validation Strategy

 Typical truth datasets are not available, so use independent sources that are most directly comparable, i.e., derived water path for water clouds (LWP) and optical depth for ice clouds (COD).

• LWP

- » Microwave instruments provide the most direct comparison opportunity
- » AMSR-2 is the current validation source and follow-ons are expected.
- » AMSR-2 can be compared at nadir-only or for gridded data off nadir to expand the colocation opportunities.

• COD

- » Lidar retrievals from CALIOP are used.
- » Thin ice clouds provide good validation opportunities for both NCOMP and CALIOP, although CALIOP's strength is very thin clouds whereas very optically thin clouds (COD < 1.0) are outside of NCOMP's retrieval range.

Accuracy and Precision results are generated for LWP and COD

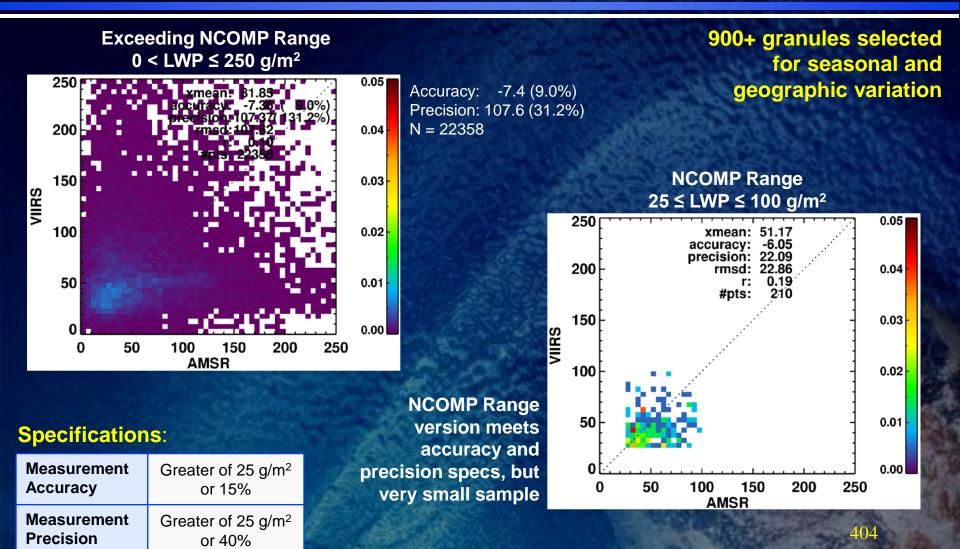


Validation Strategy (2)

- NCOMP products are compared to the analogous CERES VIIRS products from NASA Langley to check consistency.
 - » NCOMP COD, LWP and IWP comparisons to CERES VIIRS products provide reasonable consistency check opportunities.
 - » NCOMP CPS comparisons to CERES VIIRS are not useful because CERES VIIRS algorithm uses different ice particle sizes and a different thresholding technique in incorporated into CERES VIIRS for water particle sizes.



LWP Comparisons to AMSR-2 *Nadir only*





LWP Comparisons to AMSR-2 (2) *Expansion to full swath - gridded*

900+ granules selected for seasonal and geographic variation

0.5° x 0.5° latitude longitude grid

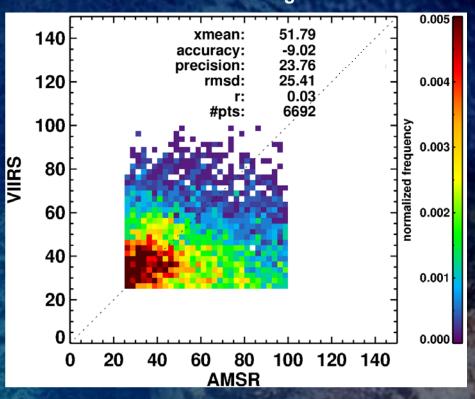
> Limited to $1 \le COD \le 5$ CF > 0.8

Higher number of samples - meets accuracy and precision specs

Specifications:

Measurement	Greater of 25 g/m ²
Accuracy	or 15%
Measurement	Greater of 25 g/m ²
Precision	or 40%

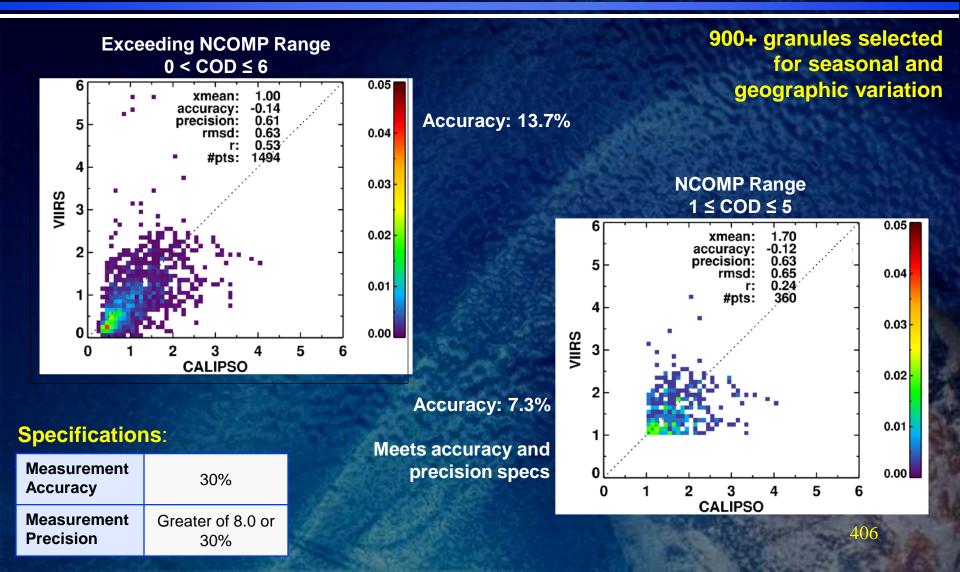
NCOMP Range $25 \le LWP \le 100 \text{ g/m}^2$



405



COD Comparisons to CALIOP *Nadir only*





COD and LWP Validation Summary Table

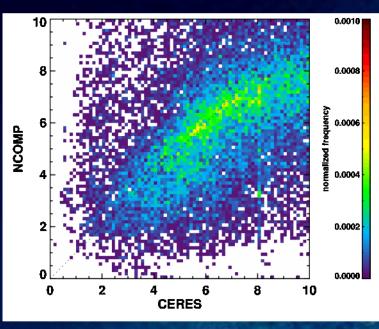
Product	Range	Validation Source	Accuracy	Precision	Samples
COD (Ice)	0 ≤ COD ≤ 6	CALIOP (Nadir)	-0.14 (13.7%)	0.61	1494
COD (Ice)	1 ≤ COD ≤ 5	()		0.63 (Max of 0.8 or 30%)	360
LWP	0 < LWP ≤ 250	AMSR-2 (Nadir)	-7.4 (9.0%)	107.6 (31.6%)	22358
LWP	25 ≤ LWP ≤ 100 1 ≤ COD ≤ 5	AMSR-2 (Nadir)	-6.05 (Max of 25g/m² or 15%)	22.09 (Max of 25g/m ² or 40%)	210
LWP	25 ≤ LWP ≤ 100 1 ≤ COD ≤ 5	AMSR-2 (Full Swath- Gridded)	-9.02	23.76	6692

Red are NCOMP product requirements Black-only rows are supplementary validations

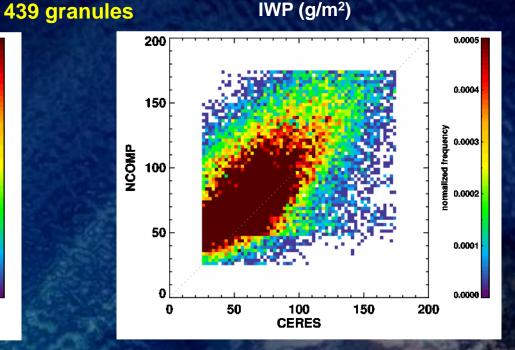


Comparisons to CERES VIIRS Gridded

COD Water Clouds



- NCOMP COD is similar to CERES
- Algorithms are conceptually related, but not the same. Also differing spatial resolutions.
- Framework and inputs also vary, including Cloud Temperature and Phase, profiles, etc., hence exact agreement is not expected.



- NCOMP IWP is similar, but there is a bias and larger variance.
- CERES IWP calculations are different than those in NCOMP.
- Same caveats as COD comparison, hence only general agreement expected.



Summary of Validation Results for VIIRS NCOMP Product

- NPP/VIIRS LWP and COD products have been validated against Microwave and Lidar retrievals, respectively.
- The accuracy and precision of the NPP/VIIRS LWP and COD falls within specifications.
- Despite a lack of truth datasets, water cloud CPS can be assumed to be reasonable since LWP and COD meet specifications.
- The accuracy and precision of ice cloud CPS and IWP have yet to be evaluated due to lack of reliable validation sources, but IWP comparisons to CERES VIIRS products imply NCOMP IWP is reasonable.
- Comparisons with CERES VIIRS products, while not independent, provide assurance that products are acceptable.



VIIRS Aerosol Optical Depth and Aerosol Particle Size Algorithm Readiness

Presented by

Istvan Laszlo

NOAA/NESDIS/STAR



Outline

- Product Overview
- Product Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS aerosol optical depth product.

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VIIRS Aerosol Optical Depth Product Overview

- Products:
 - » Aerosol Optical Depth, AOD (at 550nm and at VIIRS M1-11 bands),
 - » Aerosol Particle Size, APS (Ångström Exponent) over water,
 - » quality flags.
- VIIRS AOD is derived over global cloud-free area during daytime.
- Separate algorithms used over land and water
- AOD retrieval over land
 - » Use M1, M2, M3, M5 and M11 bands
 - » Over dark surface
 - » Experimental retrieval over bright surface (desert) and Angstrom Exponent
- AOD retrieval over water
 - » Use M4, M5, M6, M7, M8, M10 and M11 bands
 - » Over glint-free surface

 APS is calculated from AOD values at 550nm vs. 865nm and 865nm vs. 1610nm



Product Requirements VIIRS Aerosol Optical Depth

Product Name	Aerosol Optical Depth		
	Over land:	Over water:	
Measurement Accuracy	AOD < 0.1: 0.06	AOD < 0.3: 0.08	
	0.1 ≤ AOD ≤ 0.8: 0.05	AOD ≥ 0.3: 0.15	
	AOD > 0.8: 0.20		
Measurement Precision	AOD < 0.1: 0.15	AOD < 0.3: 0.15	
	0.1 ≤ AOD ≤ 0.8: 0.25	AOD ≥ 0.3: 0.35	
	AOD > 0.8: 0.45		
Measurement Range	-0.05 to +5.0		
Latency	30 minutes after granule data	a is available	
Refresh	90 minutes		
Timeliness	≤ 3 hours		
Coverage	Global		
Horizontal Resolution	0.75 km (nadir)		
Vertical coverage	Total column 413		



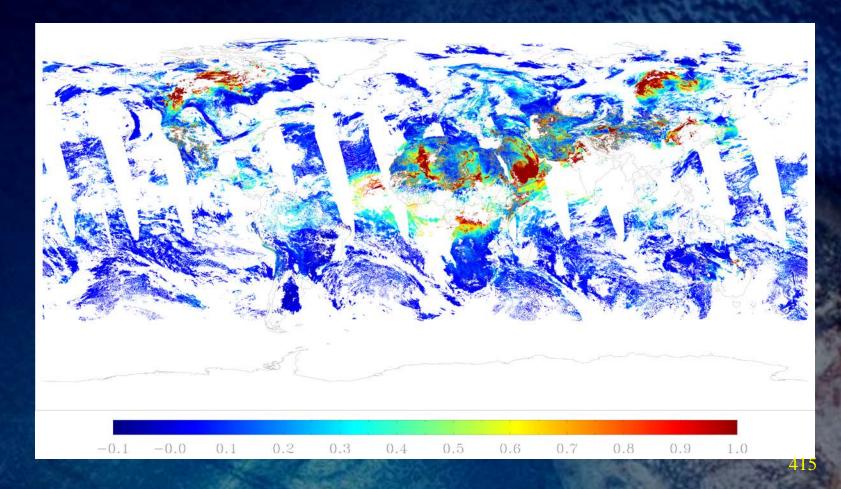
Product Requirements Aerosol Particle Size

Product Name	Aerosol Particle Size (over water)
Measurement Accuracy	0.3
Measurement Precision	0.6
Measurement Range	-1 to +3
Latency	30 minutes after granule data is available
Refresh	90 minutes
Timeliness	≤ 3 hours
Coverage	Ocean
Horizontal Resolution	0.75 km (nadir)
Vertical coverage	Total column



Algorithm Output - AOD

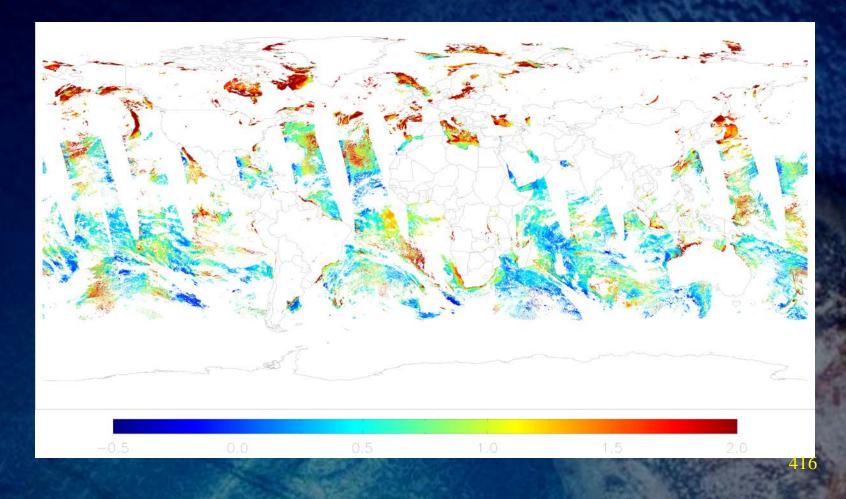
Aerosol Optical Depth at 550nm (07/15/2014)





Algorithm Output - APS

Aerosol Particle Size (07/15/2014) – Ångström Exponent (550 vs. 865nm)





Validation Strategy

- Retrieve aerosol optical depth with global NPP/VIIRS measurements during daytime.
- Retrieve aerosols with full product precedence in place
 - » Official NPP cloud mask product is used
 - » Official NPP snow/ice product is used
- Time period: 2.5 months
 - » 2014: 04/10-04/25; 07/10-07/25; 10/10-10/25
 - » 2015: 01/01-01/31
- Collocate (in space and time) retrieved aerosol optical depth with reference ("truth") ground AERONET Level 1.5 measurements
- Generate comparative statistics (Retrieval Reference aerosol optical depth and Ångström Exponent)
 - » Accuracy
 - » Precision



AOD and APS Test Plan -Offline Validation: Truth Data

- AERONET: ground-based measurements over 100 stations worldwide for more than 10 years; quality assured aerosol optical properties (*Holben et al.*, 1998).
- Collocated AERONET and retrieved AOD dataset
 - Spatial average: high quality retrievals within a circle of 27.5-km radius centered on AERONET stations.
 - Temporal average: AERONET measurements within one-hour window centered on the NPP overpass time, at least three measurements are available.



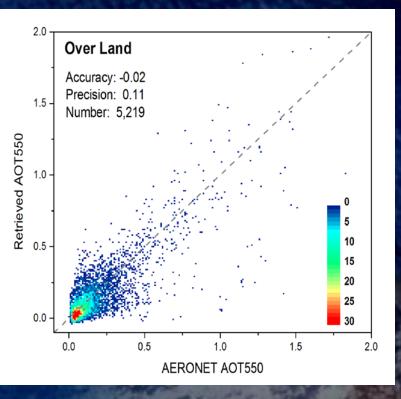


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AOD Validation Results (Land)

AOD	Retrieval	Specification				
AOD550 < 0.1						
Accuracy	0.00	0.06				
Precision	0.06	0.15				
Sample#						
0.1 ≤ AOD550 ≤ 0.8						
Accuracy	-0.04	0.05				
Precision	0.12	0.25				
Sample#	2,309	1. 2. 2. 8				
	AOD550 > 0.	8				
Accuracy	-0.23	0.20				
Precision	0.43	0.45				
Sample# 92						

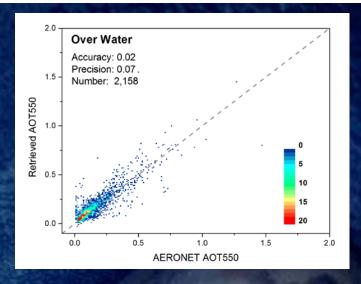


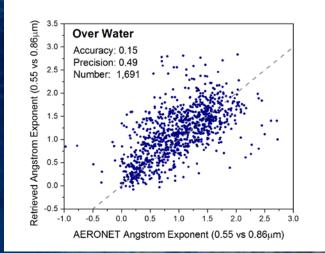
Retrievals meet requirements except at high AOD range where sample size is small

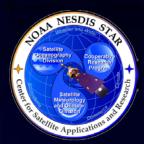


AOD & APS Validation Results (Ocean)

AOD	Retrieval	Specification				
AOD550 < 0.3						
Accuracy	0.02	0.08				
Precision	0.05	0.15				
Sample#	1,954					
AOD550 ≥ 0.3						
Accuracy	0.00	0.15				
Precision	0.16	0.35				
Sample# 204		1. S. S.				
APS (Ång	ström Exponent					
Accuracy	0.15	0.30				
Precision	0.49	0.60				
Sample#	1,691					







Summary of Validation Results for VIIRS Aerosol Optical Depth Product

- NPP/VIIRS aerosol optical depth product has been validated against AERONET ground observations.
- The accuracy and precision of the VIIRS aerosol optical depth meet the accuracy and precision specifications (except at high values over land)



VIIRS Aerosol Detection Algorithm Readiness Presented by Shobha Kondragunta

NOAA/NESDIS/STAR

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Outline

- Product Overview
- Product Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS Aerosol detection product.



VIIRS Aerosol Detection Product Overview

- Products:
 - » Smoke /dust flag, volcanic ash flag (from VCM product)
 - » Quality flags
- VIIRS smoke/dust detection is derived over the globe for cloud-free and snow/ice free (glint-free over water) areas during daytime.
- Dust detection
 - » Uses multiple visible and IR bands
 - Based on threshold test using Absorbing Aerosol Index (AAI) and Dust Smoke Discrimination Index (DSDI)

 $\Delta \gamma \Delta$

 $\begin{aligned} \text{AAI} &= -100^* [\log_{10}(\text{R}_{\text{M1}}/\text{R}_{\text{M2}}) \text{-} \log 10(\text{R}^{'}_{\text{M1}}/\text{R}^{'}_{\text{M2}})] \\ \text{DSDI} &= -10^* [\log_{10}(\text{R}_{\text{M1}}/\text{R}_{\text{M11}})] \end{aligned}$

R is the observed TOA reflectance R' is the Reflectance from Rayleigh scattering

- » Also uses various spectral difference threshold tests
- Smoke Detection
 - » Use M1, M2, M5, M7, M10 and M11 bands
 - » Based on threshold tests on AAI and DSDI
 - » Based on spectral contrast and variability test in visible .



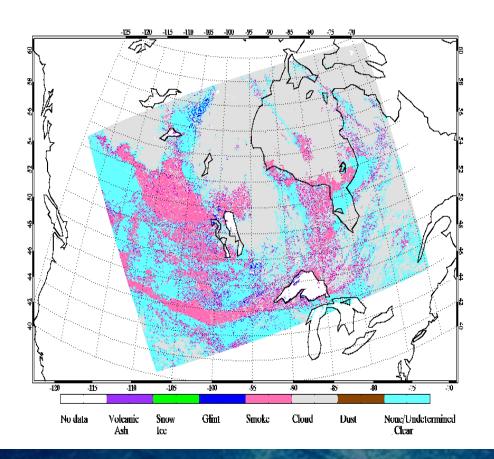
Product Requirements VIIRS Aerosol Detection

Product Name	Aerosol Detection			
	Dust smoke			
Measurement Accuracy	80% over land 80% over water	70% over land 70% over water		
Measurement Range	N/A			
Latency	30 minutes after granule data is available			
Refresh	90 minutes			
Timeliness	≤ 3 hours			
Coverage	Global			
Horizontal Resolution	0.75 km (nadir)			
Vertical coverage	Total column			



Algorithm Output – example

Smoke outbreak over U.S. (07/09/2015)

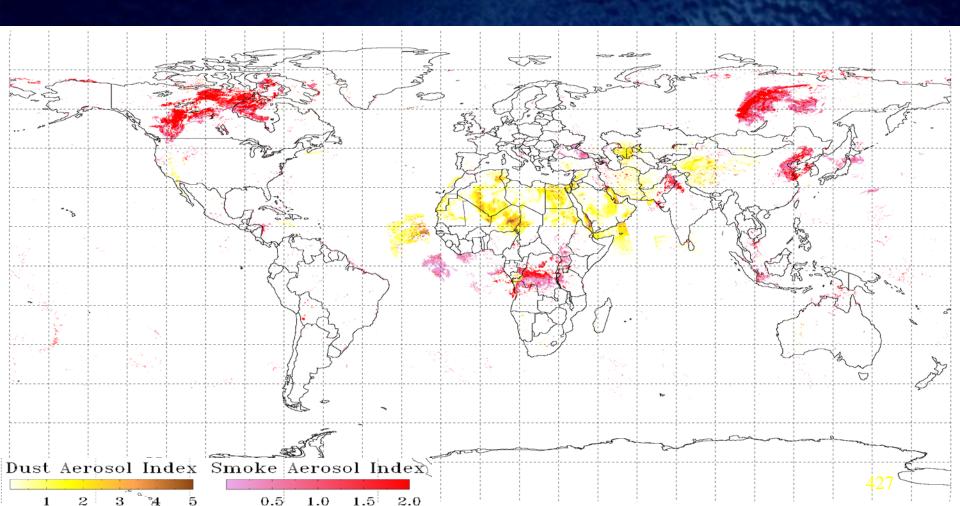


N.C. F.

RGB image

Algorithm Output – Smoke/Dust global

Smoke/dust Detection (07/15/2014)





Validation Strategy

- Aerosol Detection algorithm run on VIIRS with global NPP/VIIRS measurements during daytime.
 - with full product precedence in place
 - Official NPP cloud mask product is used
 - Official NPP snow/ice product is used
 - Time period: 2.5 months
 - 2014: 04/10-04/25; 07/10-07/25; 10/10-10/25
 - 2015: 01/01-01/31
- VIIRS smoke and dust detection matchups with CALIPSO VFM and AERONET (Level 1.5)
- Derive performance metrics
 - » Accuracy
 - » Probability of Correct Detection (POCD)
 - » Probability of False Detection (POFD)

TRUTH DATA						
	Yes	No				
Yes	А	В				
No	С	D				

POCD = A/(A+C)POFD = B/(A+B)Accuracy* = (A+D)/(A+B+C+D)

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Aerosol Detection Test Plan -Offline Validation: Truth Data (1)

- AERONET: ground-based measurements over 100 stations worldwide for more than 10 years; quality assured aerosol optical properties (*Holben et al.*, 1998).
- Collocated AERONET and smoke/dust detection results
 - Dominant type from high quality retrievals of a 50 by 50 box centered on AERONET stations.
 - Temporal average: AERONET measurements within half hour window centered on the NPP overpass time, at least three measurements are available.

Classification of Aerosol Type over AERONET:

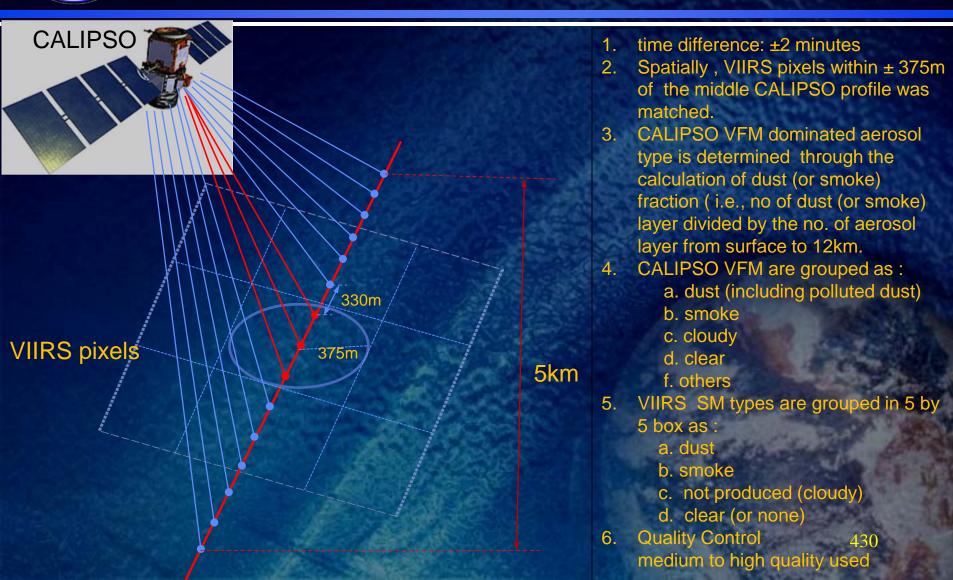
» Smoke:

AOD>0.3 and AE>1.1

» Dust: AOD>0.3 and AE<0.6</p>



Aerosol Detection Test Plan -Offline Validation: Truth Data (2)





VIIRS ADP vs. CALIPSO

		L	and		Sec. 1		
Туре	True positive	False positive	True negative	False Negative	Accuracy (%)	POCD (%)	POF D (%)
Dust	2202	69	2397	375	91.1	85.3	3.1
Smoke	117	98	4214	1	95.4	99.2	45.5
		V	Vater			1	
						14. A.A.A.A.A.A.A.A.A.A.A.A.A.A.A.A.A.A.A	1996
Туре	True positive	False positive	True negative	False negative	Accuracy (%)	POCD (%)	POF D (%)
Dust	297	11	139	10	95.4	96.4	3.3
Smoke	107	85	2309	3	92.7	97.2	44.2



VIIRS ADP vs. AERONET

Туре	True positive	False positive	True negative	False negative	Accuracy	POCD	POFD
Dust	124	22	2140	30	97.7	80.5	15.1
Smoke	19	5	1101	11	98.6	63.3	20.8



Summary of Validation Results for Aerosol Detection Product

- VIIRS Aerosol detection product has been validated against both AERONET observations and CALIPSO VFM product for the time period of 2.5 month run.
- VIIRS Aerosol Detection product meet the accuracy specifications with a relative higher POFD for smoke.



VIIRS Volcanic Ash Algorithm Readiness Presented by Michael Pavolonis

NOAA/NESDIS/STAR







- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS volcanic ash products.



VIIRS Volcanic Ash Overview & Requirements

- VIIRS Volcanic Ash algorithm consists of two parts—ash detection and an ash cloud property retrieval. The ash detection algorithm uses VIIRS bands M14, M15, and M16 (8.5, 11, and 12 µm) and the ash retrieval algorithm uses VIIRS bands M15 and M16 (11 and 12 µm)
 - » The VIIRS Volcanic ash detection algorithm classifies pixels as: high confidence ash, moderate confidence ash, low confidence ash, very low confidence ash, and no ash.
 - » The VIIRS volcanic ash retrievals are performed for all pixels with ash detection confidence of "very low" and higher confidence. The bulk of volcanic ash pixels fall into the high and moderate confidence categories, but the low and very low categories are retained as needed for more complete detection of ash clouds (some ash clouds pixels will be spectrally ambiguous).
 - » The required output products are ash cloud top height (km) and ash mass loading (ton/km²). The ash detection results and ash effective radius (µm) are available within data quality flags. Additional data quality flags and metadata are also generated.

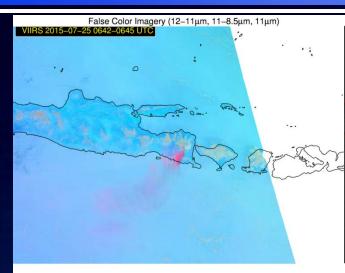


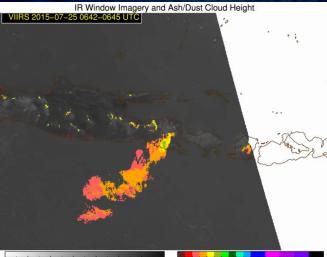
VIIRS Volcanic Ash Overview & Requirements

Name		Sensor	Coverage		Vertical Res.	Horiz. Res.	Measuremnt Range	Accuracy	Measuremnt	Measuremnt Precision	Refresh Rate	Data Latency
Volcanic Ash Detection and Height	VIIRS		Global		km (top ight)	750 m	0-50 tom/km ²	2 tons/kr	n²	2.5 tons/km ²	90 min	30 min
										17th		
	Name			Sensor		Coverage		Temporal Coverage		Cover Cond. Qualifiers	Cloud	Product Statistics Qualifiers
Volcanic Asl Detection ar Height		VIIF	RS		Global		Day and nig	ht	dow inte with	ar conditions n to feature c rest associate threshold uracy	of scenes	olcanic ash



Algorithm Output





180 200 220 240 260 280 300 320 0 2 4 6 8 10 12 14 16 18 20 11 μm BT [K] IR Window Imagery and Ash/Dust Effective Radius



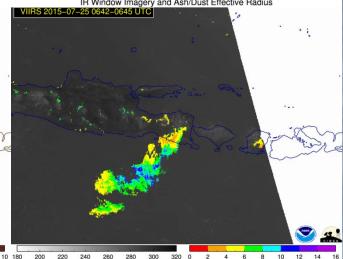
~0643 UTC 25 July 2015

Pink colors in RGB image indicate areas of volcanic ash

IR Window Imagery and Ash/Dust Loading

Ash/Dust Loading [g/m²]

11 µm BT [K]



Ash/Dust Effective Radius [µm]

11 µm BT [K]



220 240 260 280

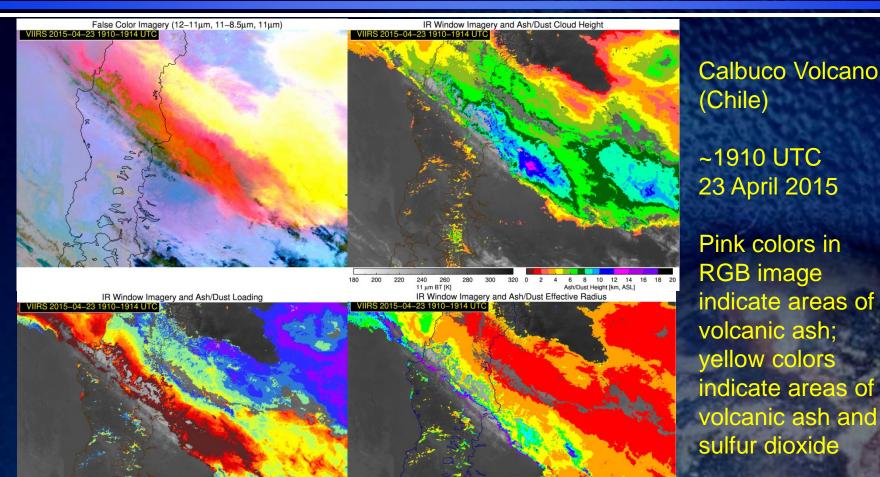
11 µm BT [K]

320 0

3 4 5 6

Ash/Dust Loading [g/m²]

Algorithm Output



240 260 11 μm BT [K] 280 300

320 0 2

4 6 8 10 12 Ash/Dust Effective Radius [um]

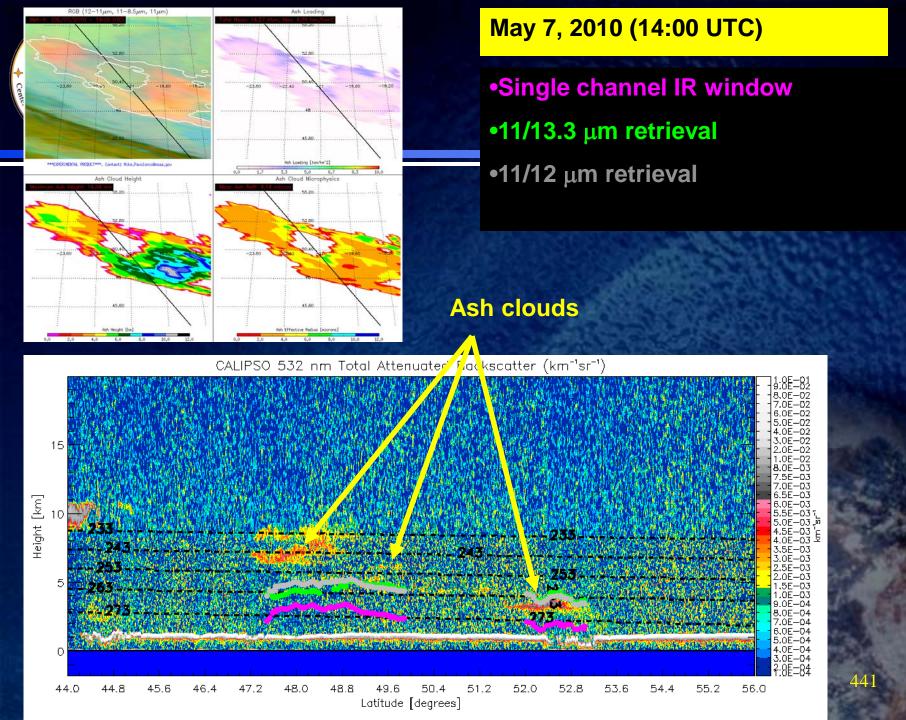
200 220

180



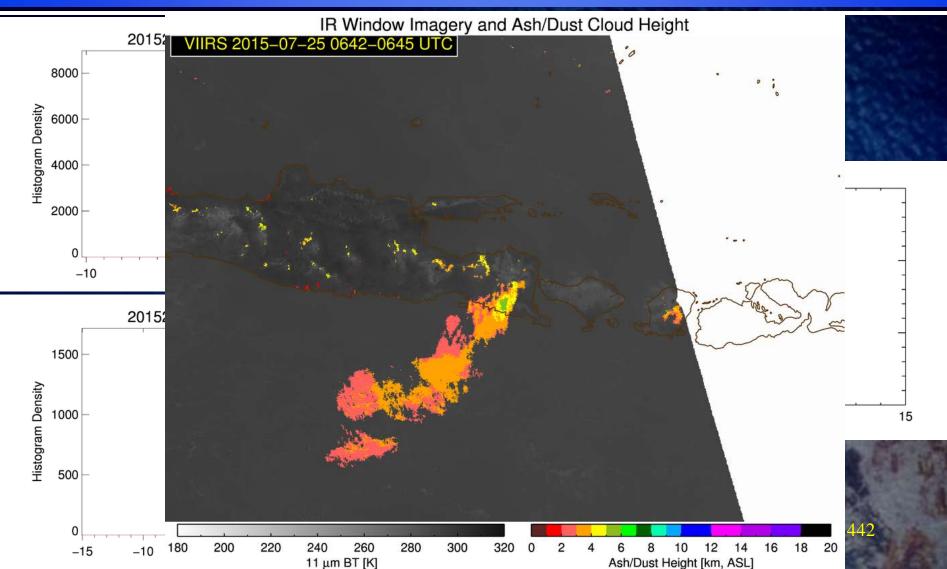
Validation Strategy

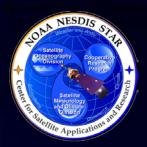
- CALIOP (space-borne lidar) provides accurate information of the vertical structure of clouds (60 m vertical resolution)
 - CALIOP ash cloud boundaries can be also used to compute mass loading (using the same microphysical assumptions as the VIIRS ash retrieval)
- Since volcanic ash is rare (relative to many other cloud types), there is a limited number of CALIOP observations of volcanic ash
 - » This is especially true for VIIRS/CALIOP matchups since VIIRS and CALIOP seldom overlap
- Thus, CALIOP co-locations with MODIS are leveraged (the VIIRS algorithm is simply applied to MODIS)
- In addition, dust clouds exhibit very similar spectral signatures as volcanic ash and are far more common. Dust pixels have been leveraged to increase the sample size of validation dataset



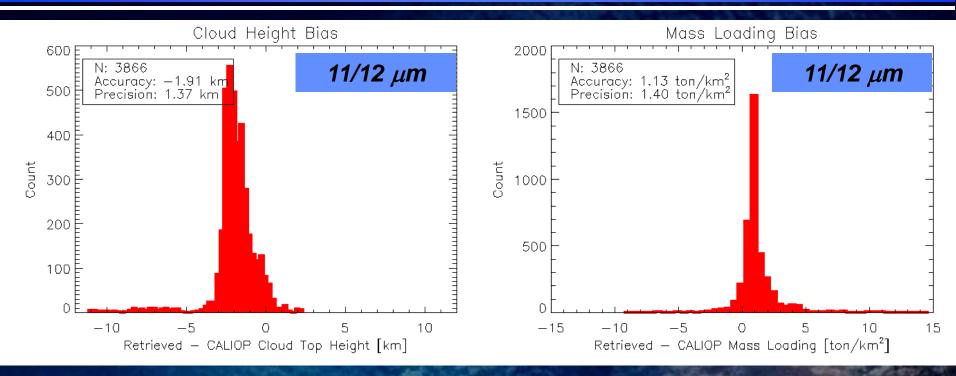


Validation Strategy Using MODIS with VIIRS Channels





Validation Strategy Using MODIS with VIIRS Channels



The VIIRS algorithm applied to MODIS is <u>well within</u> <u>specifications</u> for both ash cloud height and ash mass loading.



Validation Strategy Null Case Validation

- We can confidently identify VIIRS scenes absent of volcanic ash, known as the null case.
 - » The truth mass loading in these scenes is 0.00 tons/km². The results below indicate the VIIRS volcanic ash algorithm is well within specifications for the null cases analyzed (using moderate and high confidence ash pixels).

Day	Time Range	Accuracy (tons/km ²)	Precision (tons/km ²)	Total Pixels
2015265	04:56 – 05:11 UTC	0.009	0.179	2.458x10 ⁷
2015265	07:16 – 07:30 UTC	0.045	0.381	2.458x10 ⁷
2015053	04:34 – 04:47 UTC	0.006	0.144	2.212x10 ⁷
2015053	0830 – 08:46 UTC	0.081	0.731	2.458x10 ⁷
Mean/Total	-	0.036	0.364	9.586x10 ⁷



Summary of Validation Results for VIIRS Volcanic Ash Algorithm

- The VIIRS volcanic ash algorithm produces consistent results when applied to VIIRS and MODIS
- VIIRS/CALIOP co-locations with volcanic ash present are exceptionally rare
- The VIIRS algorithm applied to MODIS is well within specifications when compared to CALIOP
- We will validate any future matchups of VIIRS and CALIOP observations of volcanic ash, but these opportunities will be quite limited
- The VIIRS ash cloud heights are biased by about 1.91 km and the mass loading is biased high by 1.13 ton/km². This is an expected result.



VIIRS Ice Product Algorithm Readiness:

Ice Concentration and Cover
 Ice Surface Temperature
 Ice Thickness and Age





- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS sea ice products.



VIIRS Ice Concentration Algorithm Readiness

Presented by

Yinghui Liu¹ or Jeff Key²

¹Cooperative Institute for Meteorological Satellite Studies (CIMSS) ²NOAA/NESDIS/STAR



VIIRS Ice Concentration Overview

- The JPSS VIIRS Ice Concentration and Ice Mask Product will be produced for each VIIRS image and will provide ice mask, and ice concentration over all water surfaces of the globe.
 - Procedures of ice concentration and cover algorithm
 - 1. Use threshold tests to detect possible ice cover: Daytime and Nighttime
 - 2. Use a tie-point algorithm to derive reflectance (temperature) for pure ice pixel, and then calculate ice concentration
 - Reflectance (temperature) of pure ice and pure water are tied to points in a frequency histogram, and the ice fraction in a pixel (ice concentration) is determined by linearly interpolating between these tie points
 - Ice pixels with retrieved ice concentration larger than 15% are identified as ice. Ice pixels with retrieved ice concentration smaller than 15% are not identified as ice.



VIIRS Ice Concentration Requirements

Ice concentration:

Name	User & Priority	Geographic Coverage (G, H, C, M)	Vertical Res.	Horiz. Res.	Mapping Accuracy	Msmnt. Range	Msmnt. Accuracy	Product Refresh Rate/Coverage Time	Vendor Allocated Ground Latency	Product Measurement Descrision	Temporal Coverage Qualifiers	Product Extent Qualifier	Cloud Cover Conditions Qualifier	Product Statistics Qualifier
Ice Concentrati on	JPSS VIIRS	All ice- covered regions of the global ocean	lce Surface	1 km		Ice concentrati on – 0/10 to 10/10	Ice concentrati on – 10%	At least 90% coverage of the globe every 24 hours	3236 sec	30%	All conditio ns	Quantitati ve under all conditions	Clear conditions associated with threshold accuracy	Over specified geographic area

Ice cover:

Name	User & Priority	Geographic Coverage (G, H, C, M)	Vertical Res.	Horiz. Res.	Mapping Accuracy	Msmnt. Range	Msmnt. Accuracy	Product Refresh Rate/Coverage	Vendor Allocated Ground Latency	Product Measurement Precision	Temporal Coverage Qualifiers	Product Extent Qualifier	Cloud Cover Conditions Qualifier	Product Statistics Qualifier
Ice: Cover (mask)	JPSS VIIRS	FD	N/A	1 km	1 km	From the 100% ice concentration at the land edge to the less then 15% ice concentration that is the ice extent	1 km	180 min	90% coverage of the globe every 24 hours	80% probabili ty of correct typing	All conditio n	All condition	Clear conditions associated with threshold accuracy	Over specified geographic area



Algorithm Output

• Output :

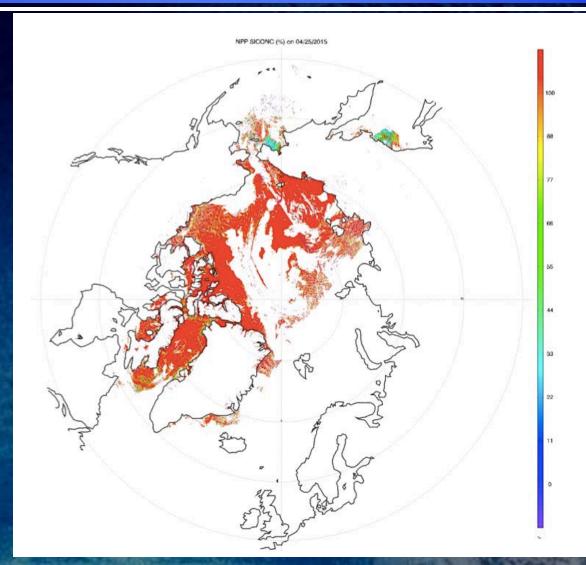
- Ice concentration and cover can be presented in a variety of methods
- Ice surface skin temperature derived by this algorithm

Name	Туре	Description	Dimension
Ice cover	output	Output contains ice extent map for each pixel with water surface type	Scan grid (xsize, ysize)
Ice concentration	output	Output contains ice concentration for each pixel identified as ice	Scan grid (xsize, ysize)
QC flags for Ice Concentration/cover	output	Quality Control Flags for every pixel	Scan grid (xsize, ysize)
Ice surface skin temperature	output	Output contains ice surface skin temperature for each pixel identified as ice	Scan grid (xsize, ysize)
QC flags for ice surface skin temperature	output	Quality Control Flags for every pixel	Scan grid (xsize, ysize)



Algorithm Output

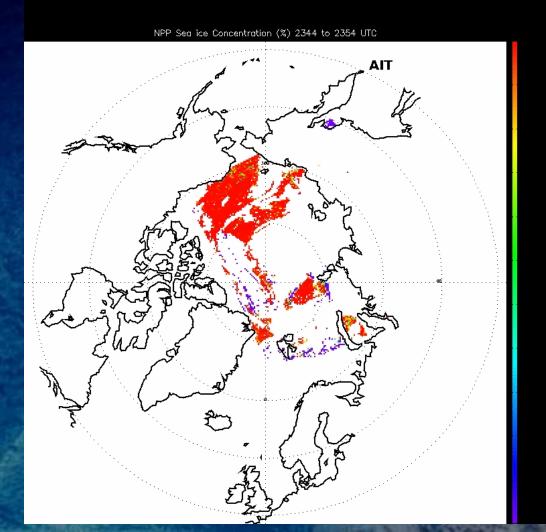
Example of VIIRS ice concentration over the Arctic on 25 April 2015.





Algorithm Output: CIMSS vs. AIT

Ice concentration from CIMSS and from the Framework. (animation)





Validation Strategy

Truth Measurements and other products » Truth

- AMSR-E/Aqua Daily L3 12.5 km Sea Ice Concentration (pixel averaging of ABI ice fraction is needed because AMSR-E is lower resolution)
- Ice chart from National Ice Center and Canadian Ice Service with 0.25 degree resolution (pixel averaging of ABI ice fraction is needed because AMSR-E is lower resolution)

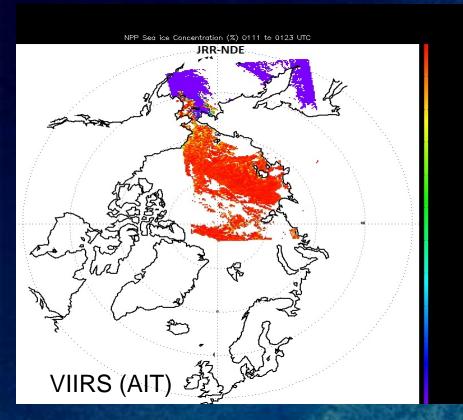
» Verification (qualitative)

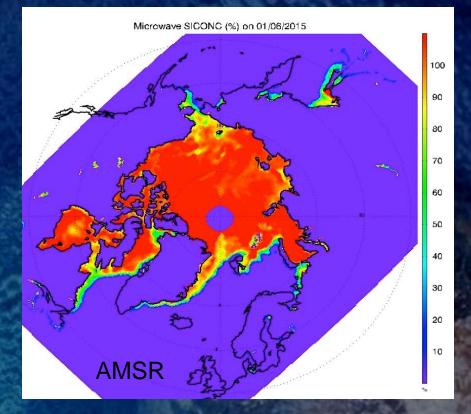
MODIS true color imagery



Validation Results: Arctic Winter Case Study

01/06/2015 - Arctic

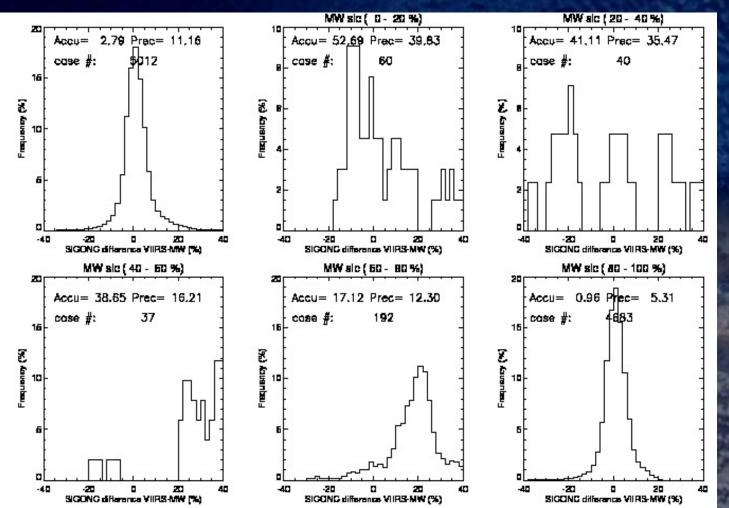






Validation Results: Arctic Winter Case Study

01/06/2015 - Arctic





Validation Results: Arctic Winter Case Study

Statistical results of the comparison in sea ice concentration between VIIRS (AIT) and AMSR.

	Arctic		Antarctic					
	Accu	Prec	Cases	Accu	Prec	Cases		
04/14	0.51	14.45	7749	9.63	16.35	14774		
07/14	7.52	40.79	258	5.94	10.79	12090		
10/14	8.80	19.60	12580	12.17	15.69	4302		
01/15	1.46	9.00	42581	18.51	32.95	700		



Summary of Validation Results for VIIRS Ice Concentration

- CIMSS and the AIT Framework are nearly identical, with differences attributed to the different use of the cloud shadow flag.
- The NPP/VIIRS Ice Concentration product (AIT) has been validated against lower-resolution passive microwave ice concentration.
- The VIIRS ice concentration (AIT) product meets the accuracy and precision specifications.



VIIRS Ice Surface Temperature Algorithm Readiness

Presented by

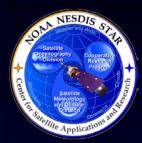
Yinghui Liu¹, Rich Dworak¹, or Jeff Key²

¹Cooperative Institute for Meteorological Satellite Studies (CIMSS) ²NOAA/NESDIS/STAR



VIIRS Ice Surface Temperature Overview

- The JPSS VIIRS Ice Surface Temperature Product will be produced for each VIIRS image and will provide values over all water surfaces of the globe.
- Procedures of ice surface temperature algorithm
 - 1. Select pixels for IST retrieval: clear sky, ice pixels only. Daytime and nighttime.
 - 2. Use a regression algorithm similar to the conventional split-window (infrared) sea surface temperature algorithms. IST is a simple calculation based on two channels with regression coefficients that are a function of temperature.



VIIRS Ice Surface Temperature Requirements

Name	User & Priority	Geographic Coverage (G, H, C, M)	Vertical Res.	Horiz. Res.	Mapping Accuracy	Msmnt. Range	Msmnt. Accuracy	Product Refresh Rate/Coverage Time	Vendor Allocated Ground Latency	Product Measurement Precision	Temporal Coverage Qualifiers	Product Extent Qualifier	Cloud Cover Conditions Qualifier	Product Statistics Qualifier
Ice Surface Tempera ture	JPSS VIIRS	All ice- covered regions of the global ocean	Ice Surface	1.6 km	1.6 km	213 – 275 K	1 K	At least 90% coverage of the globe every 24 hours	3236 sec	1 K	All conditi ons	Quantita tive under all conditio ns	Clear condition s associated with threshold accuracy	Over specified geographic area



Algorithm Output

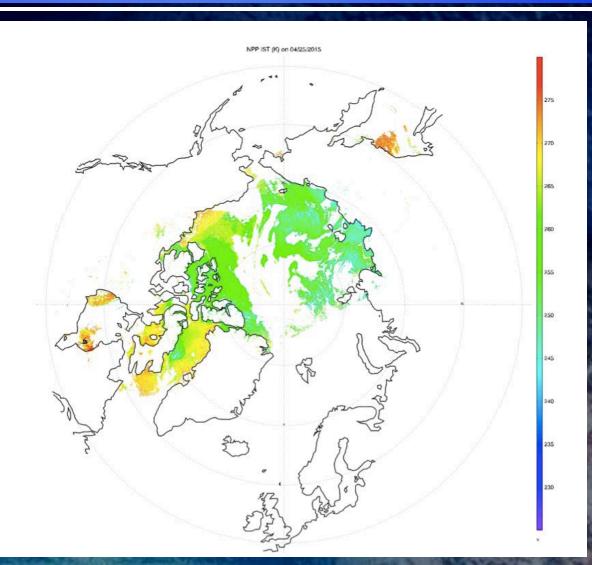
- Output Data:
 - Ice surface skin temperature derived by this algorithm

Name	Туре	Description	Dimension
Ice surface skin temperature	output	Output contains ice surface skin temperature for each pixel identified as ice	Scan grid (xsize, ysize)
QC flags for ice surface skin temperature	output	Quality Control Flags for every pixel	Scan grid (xsize, ysize)



Algorithm Output

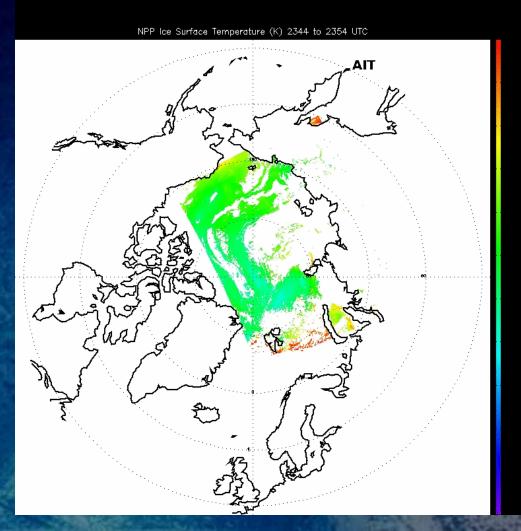
Example of VIIRS ice surface temperature over the Arctic on 25 April 2015.





Algorithm Output: CIMSS vs. AIT

IST from CIMSS and from the Framework. (animation)





Validation Strategy

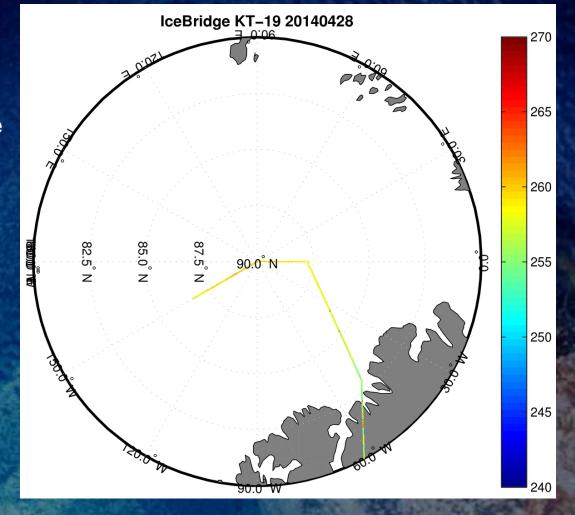
Truth Measurements and other products

- » In situ observations of ice surface temperature from field campaign, Ice Bridge KT-19 Sensor @ 15 m resolution averaged into 750 m collocated VIIRS pixel
- » Co-located ice surface temperature retrievals from MODIS



Validation Results

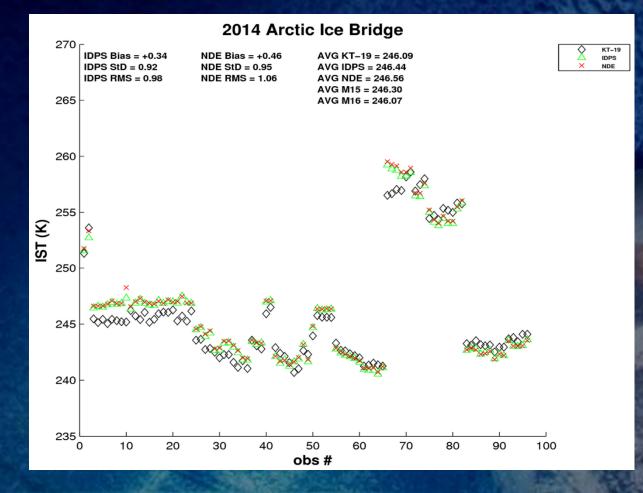
Sea Ice Surface Temperature versus IceBridge KT-19 (animation)





Validation Results

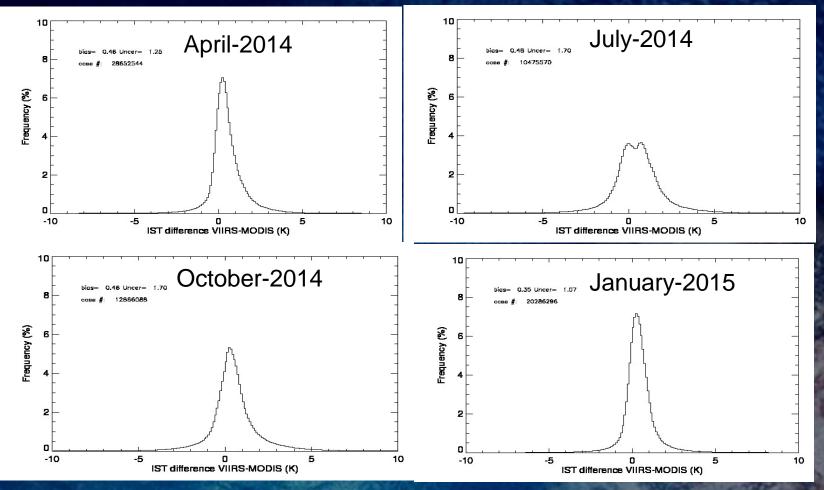
Ice Surface Temperature versus IceBridge KT-19





Validation Results

Ice Surface Temperature versus MODIS, Arctic + Antarctic





Validation Results

Statistical results of the comparison in sea ice concentration between VIIRS (AIT) and MODIS.

	Arctic			Antarctic			
	Bias	Uncer	Cases	Bias	Uncer	Cases	
04/14	0.38	0.95	18679744	0.80	1.68	9972799	
07/14	1.18	1.72	2914658	0.20	1.69	7560912	
10/14	0.70	1.68	7847217	0.10	1.78	5018871	
01/15	0.31	1.01	18403556	0.74	1.57	1882740	

Cases where only near simultaneous overpasses occur between S-NPP and MODIS.



Summary of Validation Results for VIIRS Ice Surface Temperature

- There were no significant differences between the results generated by the Framework and our locally-generated results.
- NPP/VIIRS ice surface temperature product has been validated against a similar product from MODIS and aircraft measurements from the NASA IceBridge campaign.
- The VIIRS ice surface temperature product meets the accuracy and precision specifications, though a warm bias is observed compared to MODIS and IceBridge.



VIIRS Ice Thickness and Age Algorithm Readiness

Presented by

Xuanji Wang¹ or Jeff Key²

¹Cooperative Institute for Meteorological Satellite Studies (CIMSS) ²NOAA/NESDIS/STAR



VIIRS Ice Thickness/Age Overview

- The VIIRS sea ice thickness and age product provides a continuous range of ice thickness values as well as ice age classes.
- One-dimensional Thermodynamic Ice Model (OTIM) algorithm design:
 - Solid physical foundation with all components of surface energy budget considered,
 - Capable of retrieving daytime and nighttime sea and lake ice thickness under both clear and cloudy sky conditions,
 - Very computationally efficient,
 - Flexible, fast and easy to maintain and improve later with more and accurate satellite retrieved products like radiative fluxes, snow cover and snow depth over ice,
 - Independent of historical records for ice thickness and age estimation.



VIIRS Ice Thickness/Age (Characterization) Requirements

User & S Priority PS	(G, H, C, M) All ice- covered regions of the global ocean	Vertical Res. Ice Surface	Horiz. Res. 1	Mapping Accuracy 1	Range Msnnt. Ice thickness, ice free, New/Young ice, all other ice	Accuracy 70% probabilit y of detection	At least 90% coverage of the globe every 24 hours	Vendor Allocated Ground 80	Product Measuremen t Precision	Temporal Coverage Day and night	Product Extent Qualifier	Clear conditions associated with threshold accuracy	Qualifier Statistics Over specified geographic area	
							(monthly average)							



Algorithm Output

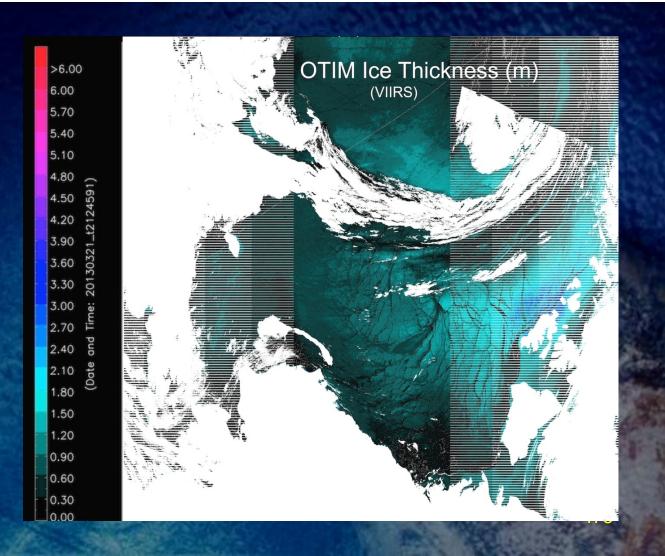
OTIM output:

Name	Туре	Description	Dimension
Ice Thickness	Output	Ice thickness is defined as the total vertical length of the ice under and above water surface. The reliable ice thickness retrieved from this algorithm ranges between $0 \sim 5.0 m$.	2-D
Ice age	Output		2-D
1: New	Output	New ice $0 \sim 10 \text{ cm}$ thick. Recently formed ice which includes frazil ice, grease ice, slush, shuga, and nilas. These types of ice include ice crystals which are only weakly frozen together (if at all) and have a definite form only while they are afloat, and a thin elastic crust of ice that is easily bending on waves and swell and under pressure growing in a pattern of interlocking "fingers" (finger rafting).	2-D
2: Grey	Output	Young ice <i>10-15 cm</i> thick. Less elastic than nilas and breaks on swell. Usually rafts under pressure.	2-D
3: Grey-white	Output	Young ice 15-30 cm thick. Under pressure it is more likely to ridge than to raft.	2-D
4: First-year Thin	Output	First-year ice of not more than one winter's growth, 30-70 cm thick.	2-D
5: First-year Medium	Output	First-year, ice <i>70-120 cm</i> thick.	2-D
6: First-year Thick	Output	First-year ice 120-170 cm thick.	2-D
7: Old Ice	Output	Sea ice which has survived at least one summer's melt. Topographic features generally are smoother than first-year ice, and <i>more than 170 cm</i> thick. May be subdivided into second-year ice and multi-year ice. Second-year Ice: Old ice which has survived only one summer's melt. Multi-year Ice: Old ice which has survived at least two summer's melt.	2-D



Algorithm Output

Example of VIIRS ice thickness over the Arctic on 21 March 2013.



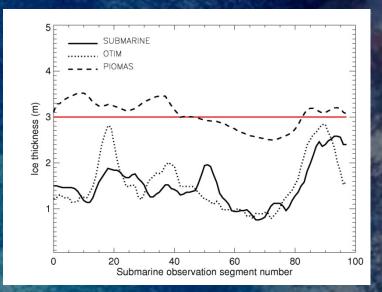


Validation Strategy

Truth Measurements and other products

- » In situ observations of ice surface temperature from the IceBridge aircraft campaign
- » Previous validation has been done with upward-looking sonar from nuclear submarines, in situ thickness measurements, CryoSat-2, and an ice-ocean model.

Validation with submarine sonar and modeled ice thicknesses.



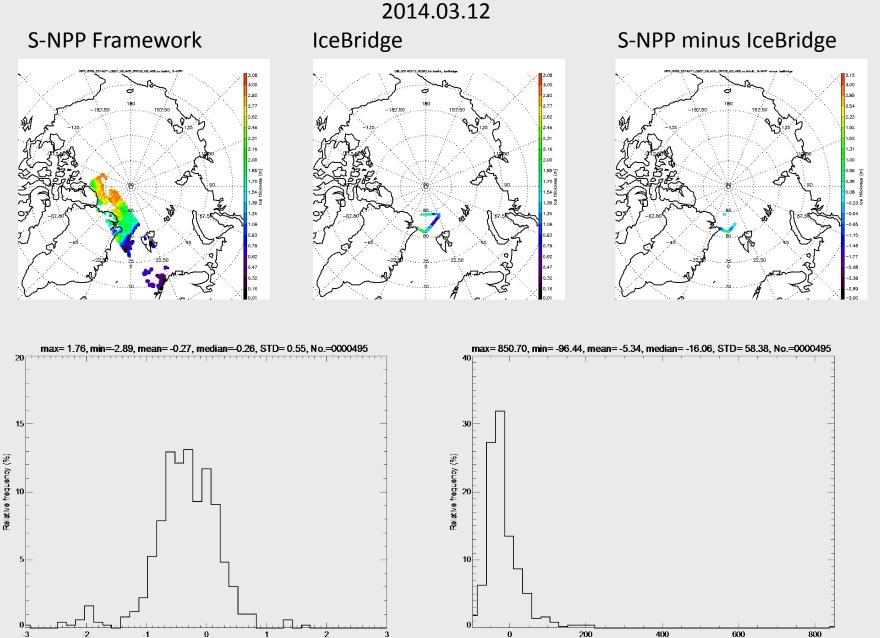


Validation Results

Statistical results of the comparison in sea ice thickness between S-NPP and IceBridge for matched locations (S-NPP pixels).

Case	Case _		S-NPP		IceBridge		S-NPP minus IceBridge			
no Date	mean	STD	mean	STD	mean	STD	percent (%)	matched pixels		
1	2014.03.12	1.18	0.52	1.45	0.69	-0.27	0.55	-5.34	495	
2	2014.03.13	2.48	0.55	2.24	0.52	0.24	0.55	16.49	438	
3	2014.03.24	1.88	0.78	2.33	0.48	-0.45	0.78	-6.31	803	
4	2014.03.31	2.28	0.21	2.56	0.35	-0.28	0.43	-8.97	37	
5	2015.03.24	2.06	0.59	2.45	0.43	-0.39	0.75	-11.63	1050	
6	2015.03.29	1.72	0.43	1.88	0.54	-0.16	0.74	-1.69	5153	
A	verage	1.93	0.50	2.15	0.50	-0.22	0.63	-2.91	7976 (total)	

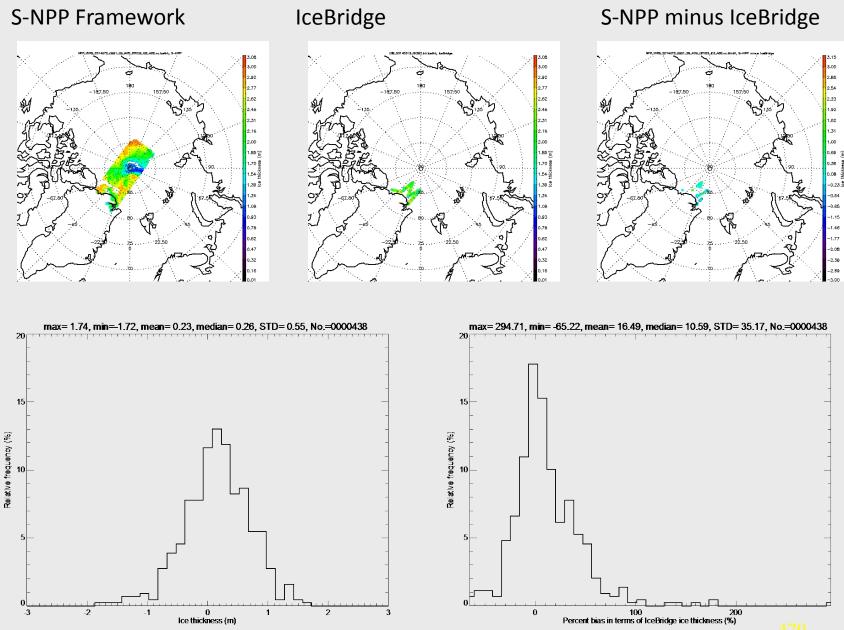
From 24 cases of S-NPP granule data when IceBridge has measurements, 6 cases out of the total 24 cases from S-NPP have good overlapped locations with IceBridge where they both have ice thickness values for comparison.



Ice thickness (m)

Percent bias in terms of IceBridge ice thickness (%)

⁴⁷⁸

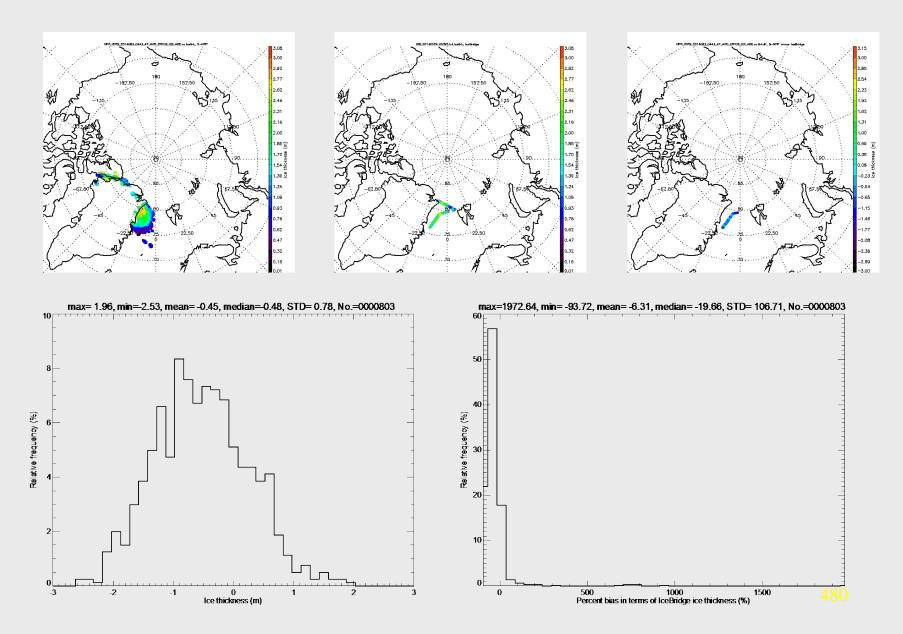


2014.03.13



2014.03.24 IceBridge

S-NPP minus IceBridge





Summary of Validation Results for VIIRS Ice Thickness and Age

- There were no significant differences between the results generated by the Framework and our locally-generated results.
- NPP/VIIRS ice thickness/age product has been validated against aircraft measurements from the NASA IceBridge campaign. (The IceBridge data in about 7 m resolution were grouped up in S-NPP 750 m resolution box, and then averaged to match S-NPP 750 m pixel size sea ice thickness for comparison.)
- The VIIRS ice thickness/age product meets the accuracy and precision specifications as expected.



VIRS Binary Snow Cover Algorithm Readiness Presented by

Peter Romanov

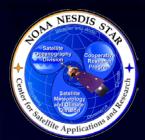
NOAA-CREST/CUNY and NOAA/NESDIS/STAR





- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS binary snow cover product.



VIIRS Binary Snow Cover Product Overview & Requirements

- VIIRS Binary Snow Cover will be derived from daytime VIIRS observations in the visible, near IR, shortwave IR and longwave IR spectral bands at the imagery resolution of 375m
 - » Snow cover is identified over cloud-clear land surface only.
 - » The coverage of the product is global.
 - » The product will include data quality flags, and metadata

System Capability	Objective
Vertical Coverage	N/A
Horizontal Resolution	1 km
Mapping Uncertainty	3 km
Measurement Range	Binary (0,1)
Measurement Uncertainty	90% probability of correct snow/no-snow classification
Measurement Accuracy	
Latency	
Refresh	90% coverage of the globe every 24 hours



Algorithm Output

VIIRS binary snow map

S-NPP/VIIRS Binary Snow Map derived from VIIRS observations on April 10, 2014 (day 2014100)

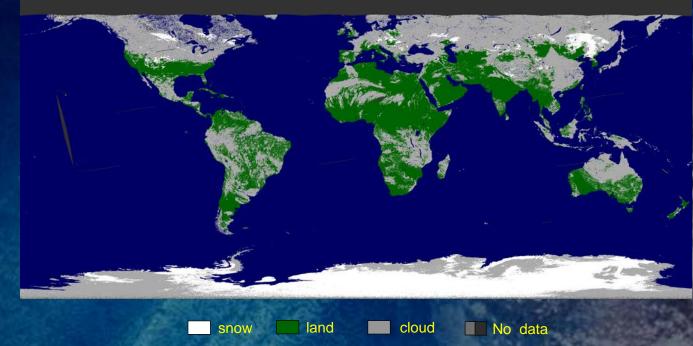




Algorithm Output

VIIRS binary snow map

S-NPP/VIIRS Binary Snow Map derived from VIIRS observations on January 06, 2015 (day 2015006)





Validation Strategy

Approach

Compare the derived daily binary snow cover maps with NOAA Interactive snow/ice maps and with collocated in situ snow observations

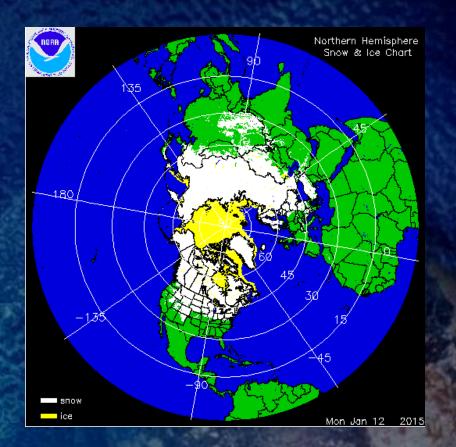
Technique

- Generate daily global binary snow map
- Employ NDE cloud mask and land/water mask
- Collocate IMS or in situ data with VIIRS clear sky snow retrievals.
- Generate overlays (for visual analysis and assessment)
- Generate comparative statistics (for quantitative evaluation)
 - » Generate full hits/misses statistics
 - » Estimate probability of correct typing



Validation Data Sources: IMS

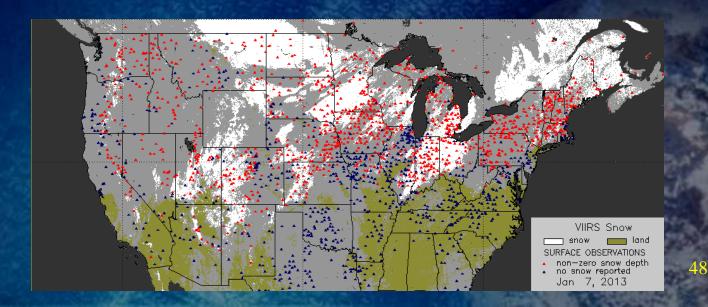
- IMS: NOAA Interactive Multisensor Snow and Ice Mapping System
- One of the most accurate and detailed characterization of the snow and ice extent in the Northern Hemisphere
- Maps are generated interactively
- Daily at 4 km (1 km since 2015)
- Product is used by NCEP in all operational NWP models





Validation Data Sources: In Situ Snow Reports

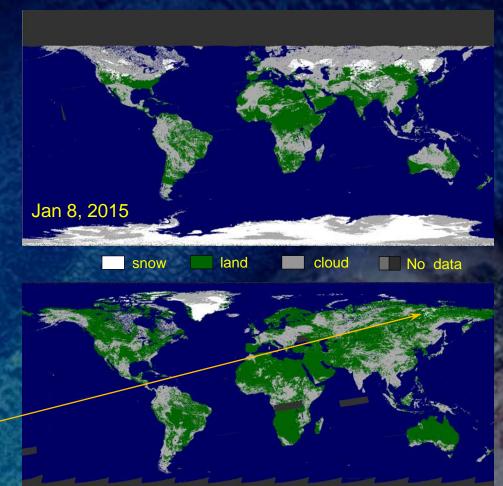
- Reports from WMO (first order) stations
- US Cooperative stations
- Total: Several thousand snow reports daily
- Other networks to consider:
 - SNOWTEL
 - CoCoRaHS





VIIRS Snow Map: Qualitative Assessment

- NH Winter: Adequate characterization of snow cover extent
- Too conservative cloud mask at low solar elevation angles (below 15-20 deg)
- NH summer: Some false snow identifications over boreal forests in Eurasia



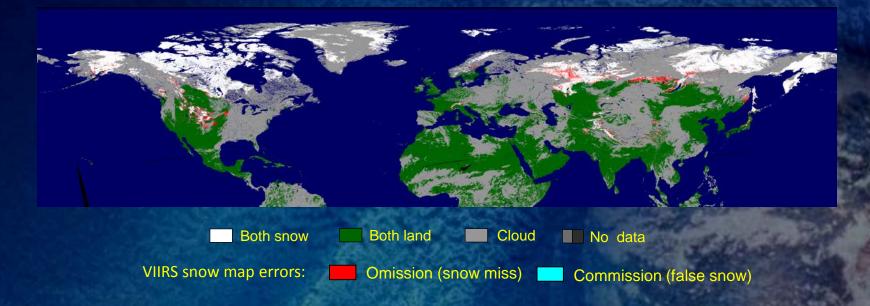
"False snow" identifications

Jul 11, 2014



Comparison with IMS (1/4)

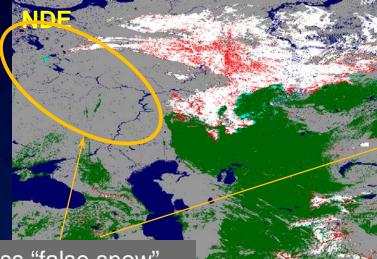
- Overlaid images help to visually evaluate disagreement between daily products
- Need to remember that IMS analysts are inclined to overestimate rather than underestimate the snow extent





Comparison with IMS (2/4)

• NDE and IDPS vs. IMS (Apr 14, 2014, Day 2014104)



Less "false snow" identifications

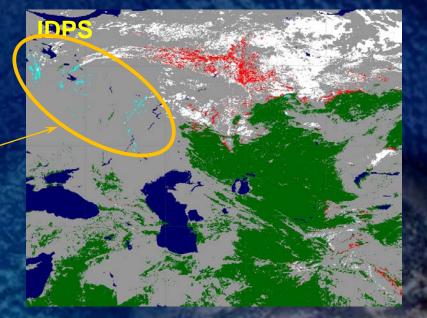
VIIRS snow map errors:

Omission (snow miss)

Commission (false snow)

• NDE vs. IDPS: less snow misses (red) and snow false identifications (light blue)

- NDE vs. IDPS: less clouds over mountains and along the snow cover boundary
- VIIRS snow misses are mostly due to shallow snow pack or dense forest ⁴⁹²/₄₀₀/₄₀₀





Comparison with IMS (3/4)

		Agree,	Disagr,	Snow Miss,	False Snow,	Cloudy,
Year	Day	%	%	%	%	%
2014	100	96.8	3.2	2.7	0.5	51.9
2014	101	96.9	3.1	2.8	0.3	49.6
2014	102	97.4	2.6	2.2	0.4	49.7
2014	103	96.9	3.1	2.6	0.5	50.4
2014	104	97.1	2.9	2.5	0.3	47.5
2014	105	99.2	0.8	0.7	0.1	15.8
2014	191	97.8	2.2	0.9	1.3	60.4
2014	192	97.7	2.3	1	1.3	61.9
2014	193	97.9	2.1	1	1.1	64.1
2014	194	97.7	2.3	0.8	1.5	62.1
2014	195	97.8	2.2	0.8	1.5	61.4
2014	196	97.4	2.6	0.8	1.8	63.4
2014	283	97	3	1.9	1.1	51.8
2014	284	97.3	2.7	1.9	0.8	52.5
2014	285	97.1	2.9	2.2	0.7	51.5
2014	286	97.3	2.7	2	0.8	52.7
2014	287	97.9	2.1	1.7	0.4	50.2
2015	1	96.9	3.1	2.5	0.6	35.5
2015	2	96.5	3.5	2.9	0.6	32.9
2015	3	96.9	3.1	2.6	0.5	32.9
2015	4	97	3	2	1	32.2
2015	5	97.4	2.6	1.9	0.7	33.7
			•••••			
2015	25	96.2	3.8	3.4	0.4	40.4
2015	26	96.1	3.9	3.5	0.4	40
2015	27	97.1	2.9	2.7	0.2	40.8
2015	28	97.3	2.7	2.2	0.5	40.4
2015	29	96.8	3.2	2.7	0.4	39.1
2015	30	97.1	2.9	2.5	0.3	40.6
2015	31	97.2	2.8	2.3	0.5	44.3

- Quantitative comparison performed over NH, for 60 days in January 2015 (30 days), April 2014 (10 days), Jul 3.5y 2014 (10 Days), October 2014 (10days)
- VIIRS gridded (1 km) snow map used
 Accuracy estimates made daily

	Mean	Range
Agreement	96.8%	96.1 ÷ 99.2
Snow misses	2.6%	0.7 ÷ 3.5
"False" snow	0.6%	0.1 ÷ 1.8
Cloud fraction	42.6%	32.2 ÷ 63.4
		493



Comparison with IMS (4/4)

Other possible reasons for disagreement between VIIRs and IMS besides the finite accuracy of VIIRS snow retrievals:

- Time difference (VIIRS: ~1330 local time, IMS: ~1300 ÷ 1700 EST)
- Frequent overestimates of snow extent by IMS analysts (see example below)



Red: Areas identified as snow-free by VIIRS but mapped as "snow" by IMS analysts

Red: Snow seen in MODIS imagery

 VIRS show map with IMS overlaid , Jan 6, 2015

 snow
 land
 cloud
 No data
 494

 omission (snow miss)
 commission (false snow)



Comparison with In Situ Data

Year	Day	Match-ups	Agree %	Snow Miss, %	False Snow, %
2015	1	564	92.6	5.3	2.1
2015	2	460	90	6.7	3.3
2015	3	187	88.2	4.3	7.5
2015	4	335	92.8	4.8	2.4
2015	5	686	96.5	1	2.5
2015	6	567	94	1.9	4.1
2015	7	1051	91.8	4.9	3.3
2015	8	789	88.3	4.7	7
2015	9	920	93.7	2.6	3.7
2015	10	759	92.8	3.8	3.4
2015	11	221	93.7	4.1	2.3
2015	12	726	95.5	2.8	1.8
2015	13	1038	94.3	3.2	2.5
2015	14	609	90.8	3.6	5.6
2015	15	1280	92	3.8	4.1
2015	16	1047	91.7	3.4	4.9
2015	17	885	92.1	3.2	4.7
2015	18	850	90.1	3.6	6.2
2015	19	929	92.4	2	5.6
2015	20	831	92.8	2.3	4.9
2015	21	633	93.8	3.2	3
2015	22	738	91.2	3.8	5
2015	23	785	88	4.7	7.3
2015	24	673	92.6	1.2	6.2
2015	25	697	91.8	1.4	6.7
2015	26	939	90.3	2.7	7
2015	27	897	95.4	1.4	3.1
2015	28	1011	95.5	1.7	2.8
2015	29	502	97.4	1	1.6
2015	30	697	94	4.4	1.6

- Quantitative comparison performed over North America for 31 days in January 2015
- VIIRS gridded(1 km) snow map used
- Accuracy estimates made daily
- From 221 to 1280 daily match-ups with station data
- Part of the disagreement (about 1%) may be due to errors in in situ snow reports

	Mean	Range
Agree	92.5%	88.0 ÷ 97.4
Snow misses	3.2%	1.0 ÷ 6.7
"False" snow	4.3%	1.6 ÷ 7.5
Match-ups	735	221 ÷ 1280



Summary of Validation Results for VIIRS Binary Snow Cover Product

- S-NPP/VIIRS binary snow product generated with the new NDE algorithm has been validated
- The estimated probability of correct typing in the VIIRS binary snow product
 - » 96.8% when compared to IMS
 - » 92.5% when compared to in situ data

 The accuracy of the product is above the accuracy specification of 90% probability of correct typing



VIIRS Binary Snow Cover Product: Remaining Issues

- False snow identifications over boreal forests in summer
 - » Possibly related to smoke due to forest fires
 - » May require adjustment of the snow identification algorithm
- Too conservative cloud masking at high solar zenith angles, above 70-75 deg
 - » Reduces the effective area coverage of the Snow Map Product
 - » Affects the product mostly during winter months



VIRS Snow Fraction Algorithm Readiness Presented by Peter Romanov

NOAA-CREST/CUNY and NOAA/NESDIS/STAR







- Product Overview and Requirements
- Product Examples
- Validation Strategy
- Validation Results

Goal: Demonstrate science quality of the VIIRS snow fraction product.



VIIRS Snow Fraction Product Overview

- Snow Fraction is assumed to be "viewable" snow fraction. It only includes snow "seen" by the satellite sensor, i.e., snow that is not masked by vegetation canopy or topography.
- VIIRS Snow Fraction will be derived from daytime VIIRS observations in the visible, spectral band at the imagery resolution of 375m
 - » Derived over cloud-clear land surface only
 - » Estimated for pixels identified as "snow covered" by the VIIRS binary snow mask
 - » Global coverage
 - » The product will include data quality flags, and metadata



VIIRS Snow Fraction Product Overview (Cont'd)

Two algorithms and two snow fraction products

- NDSI-based algorithm
 - » MODIS heritage
 - » Widely utilized by MODIS data users

Reflectance-based algorithm

- » GOES, AVHRR heritage (single-band version)
- » Applied to MODIS regionally (multiband version) (Painter, 2009)
- » Approved for and implemented with GOES-R ABI (multi-band version)

The two approaches are different and may result in different estimates of the snow fraction. Implementing both approaches with VIIRS answers the interests of both MODIS and GOES/GOES-R user communities.



NDSI-Based Snow Fraction

The Salomonson-Appel (2004) algorithm linearly relates snow fraction to the observed NDSI*

 $SF_{NDSI} = a + b*NDSI$

Parameters **a** =-0.01 and **b**=1.45 of the linear function have been established empirically through comparison of MODIS data with Landsat.

NASA MODIS team (D.Hall, G.Riggs) has found that the optimal values of a and b for VIIRS are the same as for MODIS (a = -0.01; b = 1.45)

*NDSI = $(R_{0.6} - R_{1.6})/(R_{0.6} + R_{1.6})$: Normalized Difference Snow Index



Reflectance-Based Snow Fraction

Single-band dual-end member algorithm (Romanov et al, 2003) linearly relates snow fraction to normalized visible reflectance

 $SF_{R} = (R_{1} - R_{1 \text{land}})/(R_{1 \text{snow}} - R_{1 \text{land}}),$

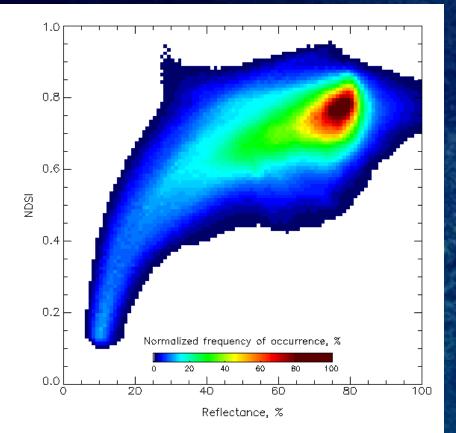
where R_1 is VIIRS-observed reflectance in band I1, R_{1land} is reflectance of snow-free land in VIIRS band I1 R_{1snow} is reflectance of snow in VIIRS band 1

Both endmembers R_{1land} and R_{1snow} vary with the observation geometry but are assumed independent of location and time of the year



Reflectance vs NDSI

Scatter plot of VIIRS visible (band 1) reflectance and NDSI for snow-covered pixels





VIIRS snow map , April 9, 2014

The difference between NDSI and Reflectance causes difference in the snow fraction estimated from these parameters



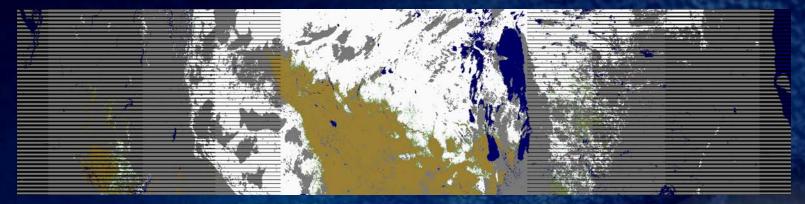
VIIRS Snow Fraction Product Requirements

System Capability	Objective
Vertical Coverage	N/A
Horizontal Resolution	1 km
Mapping Uncertainty	3 km
Measurement Range	Snow fraction (0,100)
Measurement Uncertainty	10% ?
Measurement Accuracy	10%
Latency	
Refresh	90% coverage of the globe every 24 hours

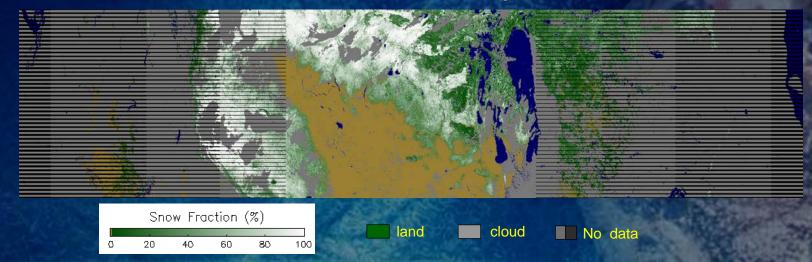


NDE vs IDPS Snow Fraction

VIIRS IDPS snow fraction: derived through 2x2 pixel aggregation of the binary map



VIIRS NDE reflectance-based snow fraction: sub-pixel snow fraction retrieval



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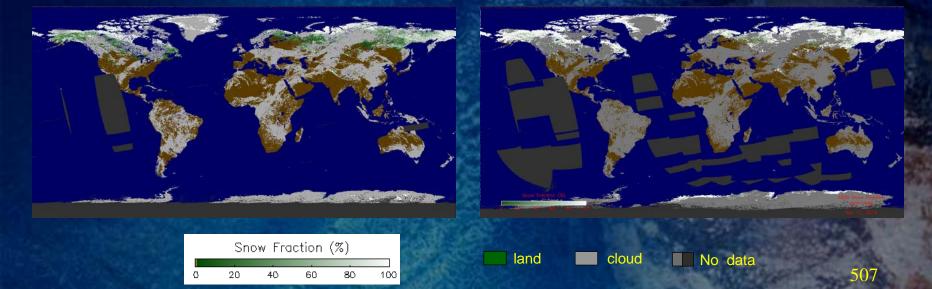
Global Snow Fraction

VIIRS snow fraction maps

S-NPP/VIIRS Snow Fraction Maps derived from VIIRS observations on April 10, 2014 (day 2014100)

Reflectance-based

NDSI-based





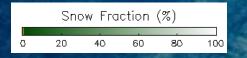
Regional Snow Fraction



S-NPP/VIIRS Snow Fraction Maps from VIIRS February 9, 2014

Some similarity in the snow fraction patterns in the two products on the regional scale. NDSI-based snow fraction is larger in the forest







cloud

land

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No data



Snow Fraction Product Verification

Snow fraction is not observed in situ. Proper quantitative validation of the product accuracy is virtually impossible.

General approach to the product verification

- Consistency testing Self-consistency: Lack of abnormal spatial patterns Day-to-day repeatability of spatial patterns Consistency with the forest cover distribution Consistency with in situ snow depth data over open flat areas.

- Comparison with higher spatial resolution data

Verification was conducted using the results of the 10-weeks algorithm runs with VIIRS data performed by AIT.



Validation Data Sources

 Surface snow depth observations: Station data over Great Plains and Canadian Prairies





• Forest cover fraction dataset (GLCF, Univ of Maryland)

Landsat Imagery





VIIRS Snow Fraction: Consistency with Forest Cover Distribution

- To verify consistency we calculated daily correlation of the derived "viewable" snow fraction and the forest fraction in the Northern Hemisphere.
- Derived "viewable" snow fraction decreases with increasing forest fraction (correlation is strongly negative) and thus is consistent with forest cover data.
- Reflectance-based snow fraction demonstrates a better agreement to forest fraction than the NDSIbased snow fraction





Snow Fraction vs Forest Fraction Statistics

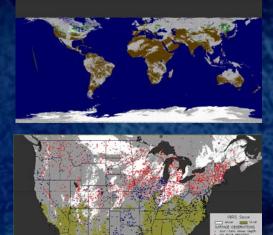
_	Mean	Reflectance	-based	NDSI-based	
Date	forest fraction	Mean SnFrac	Correl	Mean SnFrac	Correl
01/01/15	0.22	0.48	-0.57	0.79	-0.39
01/02/15	0.26	0.44	-0.60	0.75	-0.42
01/14/15	0.26	0.46	-0.58	0.79	-0.37
01/14/15	0.26	0.46	-0.58	0.79	-0.37
01/16/15	0.26	0.47	-0.59	0.77	-0.39
01/17/15	0.22	0.49	-0.59	0.79	-0.48
01/18/15	0.23	0.45	-0.57	0.76	-0.44
01/19/15	0.24	0.48	-0.61	0.78	-0.42
01/30/15	0.24	0.53	-0.65	0.81	-0.52
01/31/15	0.29	0.49	-0.68	0.80	-0.54
Mean	0.24	0.47	-0.60	0.78	-0.44

 NDSI algorithm generates larger snow fraction values as compared to the reflectance11 algorithm



VIIRS Snow Fraction: Consistency with Observed Snow Depth

- Daily correlation between the snow fraction and in situ snow depth calculated over flat non-forested areas (Great Plains)
- Derived snow fraction increases with increasing snow depth (correlation is positive) and thus is consistent with in situ snow depth data
- Two products exhibit approximately the same level of consistency (correlation) with snow depth



VIIRS Snow Fraction

In Situ Snow Depth

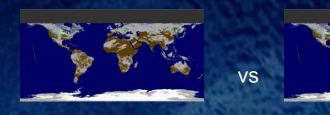
Snow Fraction vs Snow Depth Statistics

Dete	Snow Depth	Number of	Reflectance	e-based	NDSI-based		
Date	Range, cm	match-ups	Mean SnFrac	Correlation	Mean SnFrac	Correlation	
01/01/15	2 - 43	106	0.66	0.68	0.92	0.44	
01/04/15	2 - 25	58	0.53	0.54	0.74	0.55	
01/07/15	2 - 27	302	0.60	0.70	0.84	0.68	
01/09/15	2 - 30	184	0.60	0.53	0.79	0.59	
01/14/15	2 - 27	66	0.57	0.31	0.83	0.29	
01/17/15	2 - 25	47	0.43	0.52	0.79	0.49	
01/18/15	2 - 15	42	0.25	0.40	0.57	0.47	
Mean			0.52	0.52	0.78	0.50 51	



VIIRS Snow Fraction: Self-Consistency

- Compare snow fraction derived on two consecutive days. Calculate correlation and mean absolute difference.
- Spatial patterns and the mean snow fraction are reproduced well indicating consistency of retrievals



VIIRS Snow Fraction, Day N VIIRS Snow Fraction, Day N+1

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Data 1 Data 2		Ref	lectance-ba	ased	NDSI-based		
Date 1	Date 2	SnFrac1	SnFrac2	Correl	SnFrac1	SnFarc2	Correl
01/03/15	01/04/15	0.46	0.46	0.89	0.78	0.76	0.83
01/10/15	01/11/15	0.50	0.50	0.88	0.78	0.79	0.84
01/16/15	01/17/15	0.55	0.52	0.83	0.83	0.82	0.81
01/17/15	01/18/15	0.55	0.52	0.85	0.83	0.82	0.84
01/18/15	01/19/15	0.51	0.50	0.86	0.80	0.79	0.84
01/22/15	01/23/15	0.57	0.57	0.89	0.83	0.83	0.82
01/25/15	01/26/15	0.63	0.63	0.91	0.86	0.88	0.84
01/30/15	01/31/15	0.57	0.56	0.91	0.83	0.83	0.86
Mean				0.88			0.83

Snow Fraction : Day N vs Day N+1 Correlation



VIIRS Snow Fraction: Verification with Landsat Data

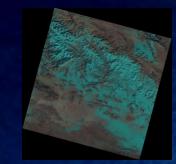
<u>Approach</u>

- Generate binary snow mask for a Landsat scene at 30 m resolution
- (2) Aggregate Landsat binary snow identifications to estimate snow fraction at VIIRS spatial resolution
- (3) Compare with VIIRS sub-pixel snow fraction estimate



VIIRS-Landsat Matching: Example



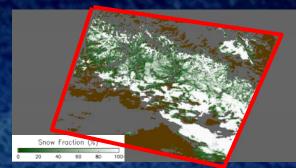


Landsat RGB

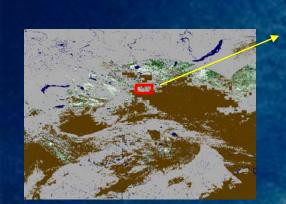


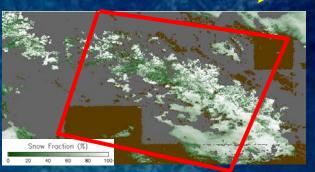
Landsat Binary Snow

Matched

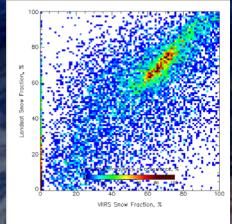


Landsat Aggregated Snow Fraction





VIIRS Snow Fraction matched with Landsat



VIIRS-Landsat Match-up Statistics Correlation: 0.85 Bias: -0.076 RMSE: 0.162 515



Algorithm Verification with Landsat Data

Location of VIIRS and Landsat Comaprison (Apr 2014-Jan 2015)





Reflectance-based Snow Fraction Algorithm Verification

VIIRS reflectance-based snow fraction vs Landsat

									1 - H - H - H - H - H - H - H - H - H -
Date	Place	Dath	Path Row		1 km			5 km	
Date	Date Place	Patri	ROW	Corr	Bias	RMSE	Corr	Bias	RMSE
01/01/15	Mongolia	140	28	0.78	-0.054	0.247	0.91	-0.076	0.162
01/13/15	Germany	192	26	0.78	-0.004	0.04	0.93	-0.006	0.021
01/13/15	Austria	192	27	0.67	0.064	0.208	0.87	0.077	0.144
01/14/15	Iran	167	35	0.88	-0.031	0.122	0.94	-0.039	0.096
01/14/15	Iran	167	36	0.82	-0.018	0.085	0.91	-0.027	0.072
01/15/15	Caucasus	174	28	0.95	-0.035	0.150	0.98	-0.037	0.082
01/15/15	Caucasus	174	29	0.93	-0.025	0.174	0.98	-0.026	0.079
01/15/15	Turkey	174	32	0.76	-0.025	0.263	0.94	-0.037	0.089
01/16/15	Kazakhstan	165	27	0.92	-0.025	0.197	0.95	-0.019	0.163
01/22/15	Rocky Mnts	38	30	0.80	-0.095	0.210	0.89	-0.105	0.134
04/10/14	Himalaya	150	36	0.95	0.001	0.099	0.93	0.002	0.106
04/10/14	Himalaya	150	35	0.89	-0.013	0.193	0.87	0.001	0.112
07/14/14	Greenland	6	13	0.93	-0.040	0.181	0.84	-0.046	0.156
07/14/14	Greenland	6	14	0.86	-0.070	0.154	0.95	-0.07	0.128
07/14/14	Greenland	6	15	0.93	-0.045	0.150	0.95	-0.051	0.114
Mean				0.84	-0.036	0.174	0.89	-0.054	0.127

Statistics was calculated for observations aggregated within 1 km and 5 km grid boxes.

Each Landsat-VIIRS matched scene includes from about 400 to several thousand matched snow fraction estimates.

The RMSE between VIIRS and Landsat snow fraction estimates is 17.4% for 1 km grid cells and 12.7 % for 5 km aggregation



Reflectance-based Snow Fraction Algorithm Verification

VIIRS reflectance-based and NDSI snow fraction

Data	Place	Reflec	tance-based	l, 5km	NDSI-based, 5 km		
Date	Place	Corr	Bias	RMSE	Corr	Bias	RMSE
01/01/15	Mongolia	0.91	-0.076	0.162	0.86	0.115	0.245
01/13/15	Germany	0.93	-0.006	0.021	0.91	0.022	0.080
01/13/15	Austria	0.87	0.077	0.144	0.84	0.236	0.362
01/14/15	Iran(1)	0.94	-0.039	0.096	0.94	0.001	0.092
01/14/15	Iran (2)	0.91	-0.027	0.072	0.90	-0.007	0.066
01/15/15	Caucasus (1)	0.98	-0.037	0.082	0.94	0.096	0.176
01/15/15	Caucasus (2)	0.98	-0.026	0.079	0.88	0.210	0.281
01/15/15	Turkey	0.94	-0.037	0.089	0.82	0.307	0.367
01/16/15	Kazakhstan	0.95	-0.019	0.163	0.83	0.188	0.310
01/22/15	Rocky Mnts	0.89	-0.105	0.134	0.71	0.279	0.329
Mean		0.93	-0.003	0.104	0.86	0.145	0.223

Comparison of NDSI and Reflectance based snow fraction was limited to 5 scenes Correlation of both types of snow fraction to Landsat is high (0.82-0.98) Smaller bias and RMSE of the reflectance-based snow fraction Considerable positive bias (~0.09) of the heritage NDSI algorithm



VIIRS-Landsat Comparison: Limited Validity

Comparison of VIIRS and Landsat snow fraction can not be viewed as a legitimate validation of VIIRS snow fraction retrievals for the following reasons:

- The same algorithm and same spectral bands are used to identify snow in Landsat and VIIRS imagery, therefore products are not independent
- Landsat snow retrievals and Landsat cloud mask have not been validated and their accuracy is largely unknown.
- Landsat scene is assumed to have no partially snow covered pixels. This condition is unrealistic and can never be satisfied unless the whole VIIRS footprint is completely snowcovered or snow-free.
- Aggregation of binary snow retrievals at finer spatial resolution is not a proper way to estimate the "viewable" snow fraction. This was the primary reason for replacing the current VIIRS IDPS snow fraction algorithm with subpixel snow fraction estimates.

Summary of Validation/Verification Results for VIIRS Snow Fraction

- S-NPP/VIIRS snow fraction products generated with the new NDE algorithm have been evaluated and their quality has been assessed.
- The VIIRS Snow Fraction product realistically reproduces the fractional snow cover is consistent with related environmental datasets.
- VIIRS reflectance-based snow fraction demonstrates better consistency with the forest cover as compared to the NDSI-based snow fraction.
- VIIRS snow fraction (both reflectance-based and NDSI-based) agrees to within 10-25% to the snow fraction derived through aggregation of Landsat binary snow cover estimates.
- MODIS heritage NDSI-based algorithm applied for VIIRS results in overestimated snow fraction values



VIIRS Snow Fraction Products: Remaining Issues

Reflectance-based snow fraction

- Snow and snow-free land BRDF model may need adjustment
- The algorithm may be improved by accounting for shadowed portions of the scene. Disregard of shadows may cause some underestimate of the snow fraction in forests.

NDSI-based snow fraction

- Introduce geometry-corrected NDSI for land and snow endmembers
- Correspondence between VIIRS and MODIS NDSI should be evaluated.
- The MODIS NDSI algorithm applied to VIIRS results in overestimated snow fraction. Adjustment may be needed to algorithm coefficients.



VIIRS Snow Fraction Products: Remaining Issues

Both algorithms

 The true fractional snow cover (characterizing the portion of land surface covered with snow) is needed besides the "viewable" snow fraction. To estimate the "true" snow fraction, the masking effect of forests has to be accounted for in the "viewable" snow fraction.



Outline

- Introduction
- Risks and Actions
- Requirements
- Algorithm Readiness
- Software Architecture
- Delivered Algorithm Package
- Risks Summary
- Summary and Conclusions



JPSS RR Product System (JPSS RR PS) Software Architecture and Detailed Design

Andy Heidinger, Denis Botambekov, Mike Pavolonis, Corey Calvert, Pat Heck, Andy Walther, Shobha Kondrangunta, Pubu Ciren, Istvan Laszlo, Hongqing Liu, Jeff Key, Xuanji Wang, Yinghui Liu, Richard Dworak, Peter Romanov Hua Xie, Shanna Sampson, Aiwu Li, Tianxu Yu, Ruiyue Chen, Tom King,

Mike Walters, Alexander Ken, John Lindeman, Walter Wolf, William Straka III, Peter Kheen, Meizhu Fan, Veena Jose



JPSS RR PS Software Architecture

Outline

- JPSS RR PS System Overview
- JPSS RR PS Detailed Design
- JPSS RR PS Algorithm Software
- AIT Framework
- Transition to Operations



JPSS RR PS Processing Architecture

Hardware Environment

- » STAR Science Development
- » System Development and Unit Testing
- » Test and Production

Software Description

- » External-Level Flow
- » System Level Flow
- » Unit Level Flow
- » Sub-Unit Flow

Data Files

- » Input Files
- » Static/Ancillary Files
- » Output Files
- » Log Files
- » Resource Files
- » File Formats



JPSS RR PS Development Hardware

- The JPSS RR science development occurs in the STAR Collaborative Environment.
- Science development hardware:
 - » Dell Intel
 - » OS Version: Red Hat Enterprise Linux 6.7
 - » Fortran Compiler: Intel 13.0.1, GNU 4.4.7
 - » C/C++ Compiler: Intel 13.0.1, GNU 4.4.7

STAR machines

- » rhw1044 Algorithm Integration
- » rhw1045 Testing
- » orbit242I SDR reformatting
- » orbit2411 Validation



JPSS RR PS Development Environment

 JPSS RR Processing System development occurs on rhw1044 located in the STAR Collaborative Environment.

• The current rhw1044 configuration is:

- » Dell Intel
- » OS Version: Red Hat Enterprise Linux 6.7
- » Disk space: 2 TB
- » Number of Processors: 16
- » Total Memory: 32 GB
- » Processor Clockspeed: 3.20 GHz
- » Fortran Compiler: Intel 13.0.1, GNU 4.4.7
- » C/C++ Compiler: Intel 13.0.1, GNU 4.4.7
- Upgrades: No plans for upgrades at this time.



JPSS RR PS Test Hardware at STAR

 JPSS RR Product System testing occurs on rhw1045 located in the STAR Collaborative Environment.

The current rhw1045 configuration is:

- » Dell Intel
- » OS Version: Red Hat Enterprise Linux 6.7
- » Disk space: 2 TB
- » Number of Processors: 16
- » Total Memory: 32 GB
- » Processor Clockspeed: 3.20 GHz
- » (No compiler)

Upgrades: No plans for upgrades at this time.



JPSS RR PS NDE Hardware

- The JPSS RR Product System official test machine is located within the NDE2.0 environment
- The JPSS RR Product System operational machine is located within the NDE environment.



JPSS RR PS Software Package Summary

- The JPSS RR PS is an integrated system built on top of the GOES-R AIT framework.
- The system is written in C/C++, FORTRAN, PERL
- Two third-party software applications are used.

Description	File and Language	Number of Files	Number of Lines
System/Sub-system processing control scripts	Perl scripts	20	5727
AIT Framework (Including SDR reader, CRTM, Clouds, Aerosols, Cryosphere algorithms, etc.)	C/C++, FORTRAN 90, Makefiles, XML, etc.	1549	463315
SDR Gap-filling*	Python scripts (python 2.7.3)	2	332
JPSS HDF5 to netCDF4 Convertor*	C, Makefiles	8	1814

JPSS RR PS Software Package Summary (cont.)

- Third-party software applications*:
 - » SDR Gap-filling utility tool
 - Python package for mending bowtie removed pixels in a VIIRS SDR image.
 - <u>ftp://ftp.ssec.wisc.edu/pub/shellb3/ShellB3-Linux-x86_64-20120621-r713-core.tar.gz</u>

» JPSS HDF5 to NetCDF4 conversion utility (*h5augjpss*, v1.1.0)

- Command line tool that modifies JPSS HDF5 files by adding associated data or metadata or by hiding HDF5 elements in order to make the file accessible to NetCDF4 based applications and tools.
- <u>http://www.hdfgroup.org/projects/jpss/h5augjpss_index.html</u>

* Source code of the 3rd-party tools will be included in the JPSS RR PS DAP

JPSS RR PS Software Package Summary (cont.)

Libraries and Utilities:

- » NetCDF4 Library version 4.1.3 (available from Unidata website)
 - Compiled as 64 bit
 - Libraries supplied by NDE
- » HDF5 Library version 1.8.10 (available from HDF Group website)
 - Compiled as 64 bit
 - Requires szip 2.1 and zlib zlib-1.2.5
 - Libraries supplied by NDE
- » CRTM Library version 2.0.2 (available from Joint Center for Satellite Data Assimilation (JCSDA)
 - Fortran 90 code
 - Compiled as 64 bit
 - Source code supplied within the JPSS RR PS DAP
- » wgrib2 version 0.1.8.2 (available from NCEP CPC website)
 - C and Fortran 90 code
 - Compiled as 64 bit
 - Utility tool supplied by NDE
- » Libxml2 devel version 2.7.6 (available from website xmlsoft.org or gnome.org)
 - C code
 - Compiled as 64 bit
 - Utility tool supplied by NDE



JPSS RR PS Data Storage Information

 The storage usage for all JPSS RR PS primary and ancillary input data, intermediate data, and output data for one day.

Storage Item	Size (1 day data storage)
Data Products Files	~1.72 TB
Incoming SDR Data and IP	~825 GB
Gap-filled/converted SDR	~645 GB
Static Ancillary	~17 GB
GFS Forecasts	~1.1GB
OISST Daily	~8 MB
System Code (executables, include third party of H5augjpss and	
gap-filling)	~23 MB
System scripts	~208 KB
System Resource Files	96 KB
CRTM version 2.0.2 package	~101 MB
Total	~2.7 TB

* The information in the table is based on the assumption of ~1000 granules per day.

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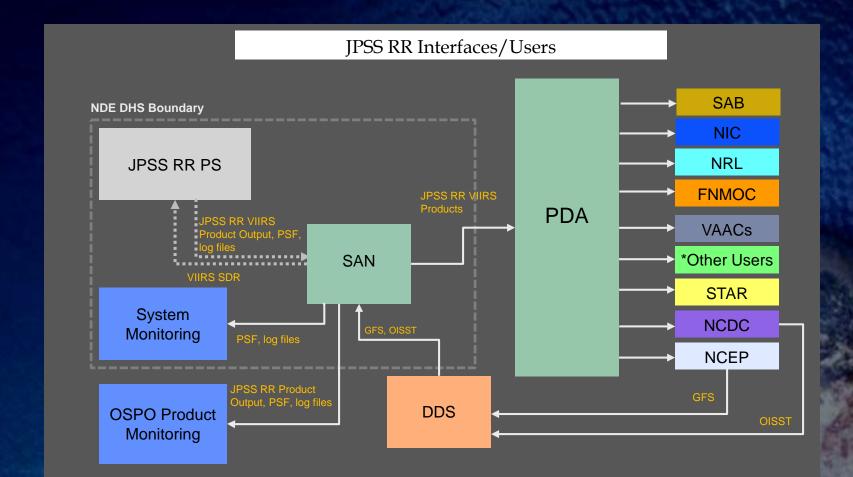


JPSS RR PS External-Level Interface

- All JPSS RR Product System external interfaces are shown on the following 4 slides
 - » 1 slide showing production and user interface flow chart
 - » 1 slide illustrating the external level data flow
 - » 2 slides on external-level interfaces in NDE DHS environment

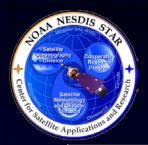


JPSS RR PS Interfaces/Users



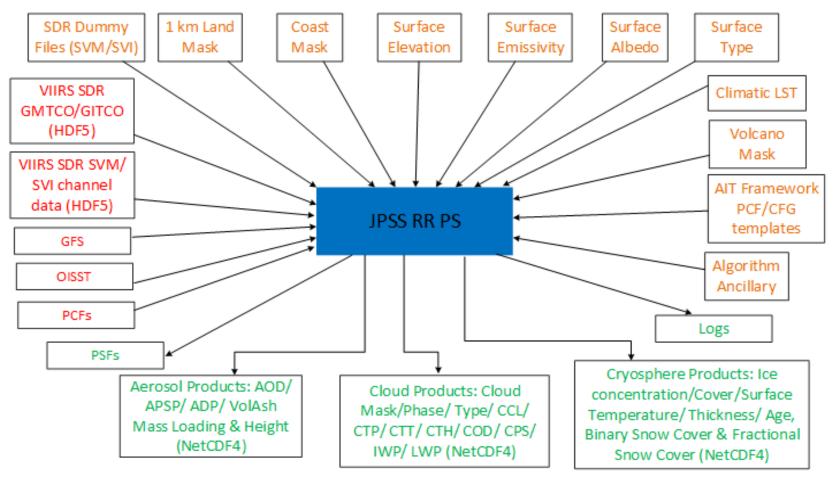
*Other Users: Climate users, International NWP Users, NWP FOs

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JPSS RR PS Context Level Data Flow

JPSS RR Processing System: Context -level data flow



Static Input Data

Dynamic Input Data

Output Data



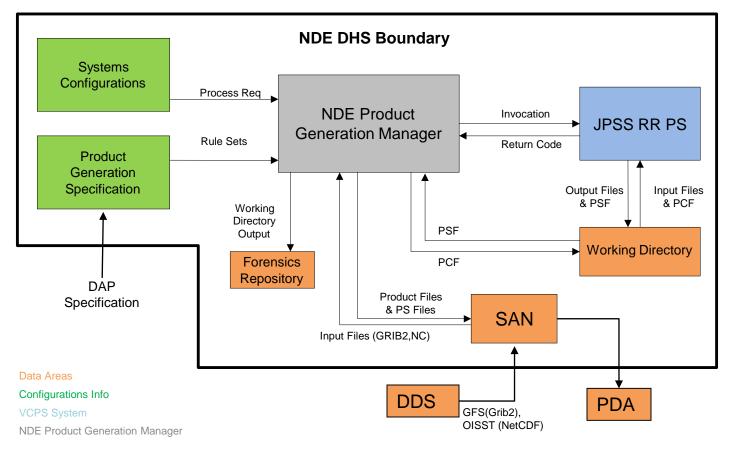
JPSS RR PS External Interfaces

- The JPSS RR Processing System will be run via execution of top level driver script that will be invoked, monitored, and managed by the NDE Data Handling System(DHS)
- The driver script is designed to run in a single working directory. All unit output will be produced in the same working directory
- The processing run will receive a Process Control File (PCF) from the NDE Product Generation Manager (PGM) containing all input file locations, parameters and other information needed by the Processing System
- The processing run will produce a PSF containing information about product files



JPSS RR PS External Interfaces

JPSS RR PS External Interfaces





JPSS RR PS Software Architecture

Outline

- JPSS RR PS System Overview
- JPSS RR PS Detailed Design
- JPSS RR PS Algorithm Software
- AIT Framework
- Transition to Operations



JPSS RR PS System Level

- The JPSS RR Product System consists of seven sub-systems (units) – one pre-processing unit and six stand-alone production units:
 - » SDR Data Preparation Unit
 - » Cloud Mask Product Generation Unit
 - » Clouds Product Generation Unit
 - » Cryosphere Ice product Generation Unit
 - » Cryosphere Snow product Generation Unit
 - » Aerosol AOD and ADP Product Generation Unit
 - » Aerosol Volcanic Ash Product Generation Unit .

Pre-process

Production

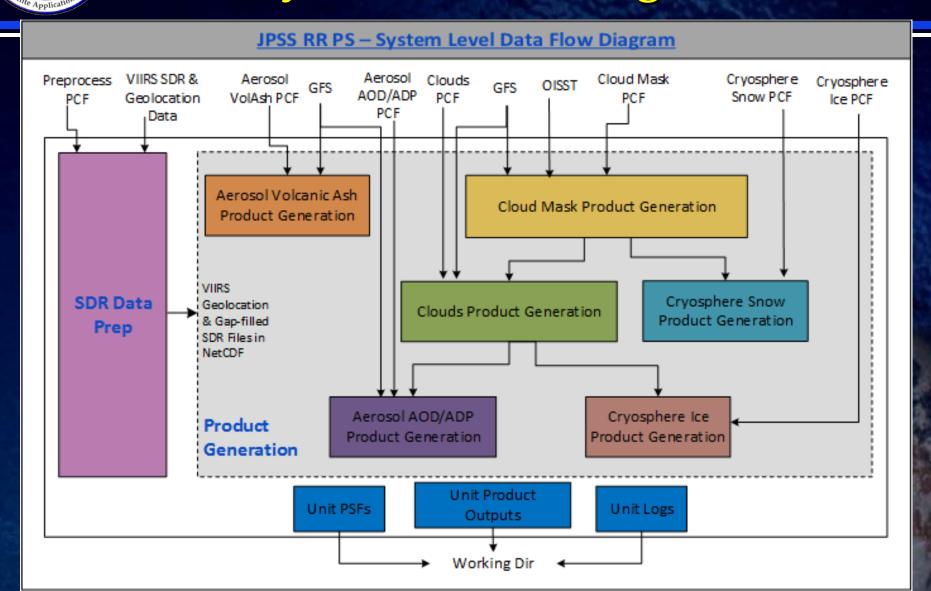


JPSS RR PS System Level

- SDR Data Preprocessing is carried out once, for use by all product generation units or sub-systems.
- Cloud Mask Product Generation and Volcanic Ash Product Generation have no product precedence.
- Cloud Mask Product Generation is a pre-requisite for Clouds, Aerosol AOD/ADP, and Cryosphere Snow product generation units
- Whereas, Clouds Product Generation is a pre-requisite for Aerosol AOD/ADP, and Cryosphere Ice product generation units

JPSS RR PS System Level Diagram

NESDIC





System PCFs

File	Data Type	Size of single file	Source	Format
JRR_PREPROCESS_SDR.pl.PCF	Dynamic Primary Input	2.7 KB	NDE	ASCII
JRR_PRODUCT_AEROSOL_AODADP.pl.PCF	Dynamic Primary Input	5.1K	NDE	ASCII
JRR_PRODUCT_AEROSOL_VOLASH.pl.PCF	Dynamic Primary Input	6.5K	NDE	ASCII
JRR_PRODUCT_CLOUD_CLOUDS.pl.PCF	Dynamic Primary Input	20K	NDE	ASCII
JRR_PRODUCT_CLOUD_MASK.pl.PCF	Dynamic Primary Input	19K	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_ICE.pl.PCF	Dynamic Primary Input	4.0K	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PCF	Dynamic Primary Input	17K	NDE	ASCII

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Satellite data

Data File/ Resolution	No of files/ day	Data Type	Apprx. size / day	Source	Format
VIIRS Geo-location File for M-Bands	~1000	Primary Dynamic Input	56 GB	IDPS	HDF5
VIIRS SDR M-Band Files	~16000	Primary Dynamic Input	172 GB	IDPS	HDF5
VIIRS Geo-location File for I-Bands	~1000	Primary Dynamic Input	219 GB	IDPS	HDF5
VIIRS SDR I-Band Files	~5000	Primary Dynamic Input	201 GB	IDPS	HDF5
VIIRS Geo-location File for M-Bands	~1000	Inter. Input/Output	56 GB	JPSS RR PS	NetCDF4
Gap-filled VIIRS SDR M- Band Files	~16000	Inter. Input/Output	172 GB	JPSS RR PS	NetCDF4
VIIRS Geo-location File for I-Bands	~1000	Inter. Input/Output	219 GB	JPSS RR PS	NetCDF4
Gap-filled VIIRS SDR I- Band Files	~5000	Inter. Input/Output	201 GB	JPSS RR PS	NetCDF4

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Dynamic Ancillary Input

Data	No of files/ day	Data Type	Apprx. size / day	Source	Format
*Half deg. NWP GFS	16	Primary Dynamic Input	1.1 GB	NCEP	GRIB2
Quarter deg. OISST Daily	1	Primary Dynamic Input	8 MB	NCDC	NetCDF4
CRTM	N/A	Dynamic Input (framework internal computation)	Not saved to disk	JPSS RR PS	NetCDF4
*SNOW_MASK_NWP	N/A	Dynamic Input (framework internal computation)	Not saved to disk	JPSS RR PS	NetCDF4
3.9 um Pseudo Emissivity	N/A	Dynamic Input (framework internal computation)	Not saved to disk	JPSS RR PS	NetCDF4

*Might require up to 8-10 GFS files (trace back); although, system makes use of only 2 files for each processing run

*Snow Mask NWP will be replaced with IMS Snow Mask, as it gets implemented in framework



Static Ancillary Input

Data/Description	No of files	Data Type	Size of single file	Source	Format
LAND_MASK_MODIS_250M	318	Static Input	108 KM – 1.7 MB	DAP/ NDE	NetCDF4
LAND_MASK_NASA_1KM	1	Static Input	890 MB	DAP/ NDE	NetCDF4
COAST_MASK_NASA_1KM	1	Static Input	890 MB	DAP/ NDE	NetCDF4
SFC_ELEV_GLOBE_1KM	1	Static Input	1.8 GB	DAP/ NDE	NetCDF4
SFC_TYPE_AVHRR_1KM	1	Static Input	890 MB	DAP/ NDE	NetCDF4
SFC_EMISS_SEEBOR	12	Static Input	693 MB	DAP/ NDE	NetCDF4
SFC_ALBEDO	69	Static Input	28 MB	DAP/ NDE	NetCDF4
VOLCANO_SMITH_1KM	1	Static Input	890 MB	DAP/ NDE	NetCDF4
CLIMATIC_LST_ISCCP	12	Static Input	47 KB	DAP/ NDE	NetCDF4
DESERT_MASK_CALCLTED (framework internal computation)	N/A	Static Input	Not saved to disk	JPSS RR PS	NetCDF4



Static Algorithm Ancillary Input

Data/Description	No of files	Input Data Type	Size of single file	Source	Format
npp_viirs_ancil.nc VIIRS SDR Ancil Files for I/M bands	2	Static Algorithm Ancillary	2.2 - 2.6 KB	DAP/ NDE	NetCDF4
VIIRS SDR Dummy files (SVI01/04, SVM01/12/13)	5	Static Algorithm Ancillary	9.3 - 50 MB	DAP/NDE	NetCDF4
NCOMP coeff file for VIIRS	1	Static Algorithm Ancillary	47KB	DAP/ NDE	NetCDF4
DCOMP channel ref/ems Coeff files for ice/water phases	10	Static Algorithm Ancillary	91-99MB	DAP/ NDE	NetCDF4
Volcanic Ash IR retreival coeff. file	1	Static Algorithm Ancillary	35 KB	DAP/ NDE	NetCDF4
CloudCoeff.bin CRTM coeff file	1	Static Algorithm Ancillary	1.6MB	DAP/ NDE	Binary
AerosolCoeff.bin CRTM coeff file	1	Static Algorithm Ancillary	5.5MB	DAP/ NDE	Binary
EmisCoeff.bin CRTM coeff file	1	Static Algorithm Ancillary	1.9MB	DAP/ NDE	Binary
viirs-m_npp.SpcCoeff.bin CRTM coeff file	1	Static Algorithm Ancillary	472B	DAP/ NDE	Binary
viirs-m_npp.TauCoeff.bin CRTM coeff file	1	Static Algorithm Ancillary	104KB	DAP/ NDE	54Binary



Static Algorithm Ancillary Input

Data/Description	No of files	Input Data Type	Size of single file	Source	Format
VIIRS_Aerosol_LUT.nc Aerosol LUT File	1	Static Algorithm Ancillary	39 MB	DAP/ NDE	NetCDF4
VIIRS_BrightSfc_Refl_Coeff.nc Aerosol coeff. File	1	Static Algorithm Ancillary	47 MB	DAP/ NDE	NetCDF4
VIIRS_Coeff_File.nc Aerosol coeff. File	1	Static Algorithm Ancillary	6.8 KB	DAP/ NDE	NetCDF4
VIIRS_Aerosol_Sunglint_Lut.nc Aerosol LUT File	1	Static Algorithm Ancillary	179 MB	DAP/ NDE	NetCDF4
AITA_Coefficients_ResiFlux.nc Ice Age Coeff. file	1	Static Algorithm Ancillary	1.4 KB	DAP/ NDE	NetCDF4
AITA_INPUT_Coefficients_ResiFlux.nc Ice Age Coeff. file	1	Static Algorithm Ancillary	1.4 KB	DAP/ NDE	NetCDF4
IceSrfTempCoeff_NPP_VIIRS.nc Ice Conc. Coeff. file	1	Static Algorithm Ancillary	1.2 KB	DAP/ NDE	NetCDF4
viirs_default_nb_cloud_mask_lut.nc Bayesian Cloud Mask coeff. File	1	Static Algorithm Ancillary	94 KB	DAP/ NDE	NetCDF4
snow_occurrence_lation_week_??.nc Climatic snow files for Snow Cover	52	Static Algorithm Ancillary	576 KB	DAP/ NDE	NetCDF4



Output Product Files

		CONTRACTOR IN A REAL PROPERTY AND		[3] A. L. L. L. M. M. Mark, 2007.	
Data	No of files/ day	Data Type/ Resolution	Apprx. size / day	Source	Format
JPSS RR VIIRS Cloud Mask	~1000	Product Output (750 m)	140 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Cloud Phase: Phase & Type	~1000	Product Output (750 m)	40 GB	JPSS RR PS	GRIB2
JPSS RR VIIRS Cloud Height: Cloud- top Height/ Pressure/ Temperature	~1000	Product Output (750 m)	155 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Daytime Cloud Optical Properties: CPS, COD, LWP, IWP	~1000	Product Output (750 m)	113 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Nighttime Cloud Optical Properties: CPS, COD, LWP, IWP	~1000	Product Output (750 m)	113 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Aerosol Detection: Smoke & Dust	~1000	Product Output (750 m)	61 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Aerosol Optical Depth: AOD & Aerosol Particle Size Parameter	~1000	Product Output (750 m)	303 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Aerosol Volcanic Ash: Mass Loading and Height	~1000	Product Output (750 m)	110 GB	JPSS RR PS	NetCDF4



Output Product Files

Data/Resolution	No of files/ day	Data Type /Resolution	Apprx. size / day	Source	Format
JPSS RR VIIRS Cryosphere Ice Conc. and Ice Surface Temperature	~1000	Product Output (750 m)	51GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Cryosphere Ice Thickness and Age	~1000	Product Output (750 m)	47 GB	JPSS RR PS	NetCDF4
JPSS RR VIIRS Cryosphere Snow Cover: Binary Snow Mask, NDSI Snow Fraction and Reflectance based Snow Fraction	~1000	Product Output (375 m)	61 GB	JPSS RR PS	NetCDF4



System PSFs

File	Data Type	Size of single file	Source	Format
JRR_PREPROCESS_SDR.pl.PSF	Output	4.1 KB	NDE	ASCII
JRR_PRODUCT_AEROSOL_AODADP.pl.PSF	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_AEROSOL_VOLASH.pl.PSF	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CLOUD_CLOUDS.pl.PSF	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CLOUD_MASK.pl.PSF	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_ICE.pl.PSF	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PSF	Output	< 1 KB	NDE	ASCII



System Log files

File	Data Type	Size of single file	Source	Format
JRR_PREPROCESS_SDR.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_AEROSOL_AODADP.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_AEROSOL_VOLASH.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CLOUD_CLOUDS.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CLOUD_MASK.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_ICE.pl.log	Output	< 1 KB	NDE	ASCII
JRR_PRODUCT_CRYOSPHERE_SNOW.pl.log	Output	< 1 KB	NDE	ASCII



JPSS RR PS System Level Interfaces

- The system level is where NDE invokes the Processing System
- Each processing unit (sub-system) has a Perl wrapper script that drives the processing algorithms
- The system PCF generated by NDE PGM contains all the input file locations and parameters needed by each processing unit.
- Each Processing System, in turn, produces a PSF file containing information about the system product file status



System Level System Driver Script

- The system driver script is the top level script called by NDE PGM to invoke the production unit processing.
 - » There are no hard coded paths in the scripts. All needed information regarding locations of files will come through the system PCF
 - » All Perl library function calls and system calls have their return values checked and errors trapped so the exits are graceful and informative.
 - » All standard out and standard error is directed to a single log file that can be read by NDE for obtaining any error or warning messages.
 - » The driver script translate the low-level program errors into a highlevel numerical value expected by the PGM (0 = success, 1=failure).
 - » The driver script set up the local environments (i.e. create unit PCFs, symbolic links, etc.) upfront before proceeding to low-level processing.



System Level Script Execution Tree (1/4)

JRR_PREPROCESS_SDR.pl (pre-process driver script)

- > jrr_preprocess_gapfill.pl (do gap filling if required)
- Priority #1
- *mender.py

 viirsmend.py
- jrr_preprocess_cvth52nc.pl (convert data from HDF5 to NetCDF4)
 - *h5augjpss



System Level Script Execution Tree (2/4)

	JRR_PRODUCT_CLOUD_MASK.pl (product driver script)
	 jrr_product_sdr4frmwk.pl (rename the geo-location/SDR files for Framework use) get_sdr_scan_time.exe
Priority #2	 jrr_product_env4frmwk.pl (set up environment for the Framework run) jrr_product_cld_mask.pl (Framework Cfg-Pcf Generator & Cloud Mask Product
	Retrieval)
	 pcf_framework.exe
	o run_wgrib.pl
	JRR_PRODUCT_AEROSOL_VOLASH.pl(product driver script)
	 jrr_product_sdr4frmwk.pl (rename the geo-location/SDR files for Framework use) get_sdr_scan_time.exe
Priority	jrr_product_env4frmwk.pl (set up environment for the Framework run)
#2	jrr_product_aer_volash.pl (Framework Cfg-Pcf Generator & Volcanic Ash Product
	Retrieval)
	 pcf_framework.exe
	o run_wgrib.pl



System Level Script Execution Tree (3/4)

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System Level Script Execution Tree (4/4)

	JRR_PRODUCT_AEROSOL_AODADP.pl (product driver script)
	jrr_product_sdr4frmwk.pl (rename the geo-location/SDR files for Framework use)
Priority	 get_sdr_scan_time.exe jrr_product_env4frmwk.pl (set up environment for the Framework run)
#4	jrr_product_aer_aodadp.pl (Framework Cfg-Pcf Generation & AOD/ ADP Product Retrieval)
	• pcf_framework.exe
	o run_wgrib.pl
Priority #4	JRR_PRODUCT_CRYOSPHERE_ICE.pl (product driver script)
	jrr_product_sdr4frmwk.pl (rename the geo-location/SDR files for Framework use)
	 get_sdr_scan_time.exe jrr_product_env4frmwk.pl (set up environment for the Framework run)
	jrr_product_cryos_ice.pl (Framework Cfg-Pcf Generation & Cryosphere Ice Age/ Ice
	Concentration/ Ice Thickness Product Retrieval)
	 pcf_framework.exe run_wgrib.pl



System Level Process Control File(PCF)

- A system PCF is generated by NDE PGM for each processing unit viz.
 - » JRR_PREPROCESS_SDR.pl.PCF
 - » JRR_PRODUCT_CLOUD_MASK.pl.PCF
 - » JRR_PRODUCT_CLOUD_CLOUDS.pl.PCF
 - » JRR_PRODUCT_AEROSOL_AODADP.pl.PCF
 - » JRR_PRODUCT_AEROSOL_ VOLASH.pl.PCF
 - » JRR_PRODUCT_ CRYOSPHERE_SNOW.pl.PCF
 - » JRR_PRODUCT_ CRYOSPHERE_ICE.pl.PCF

• Contains:

- » Environmental variables required by the unit
- » Contains input VIIRS Granule filenames.
- » Dynamic ancillary & primary input data filenames; name and location for static input data for the current process
- » Ancillary data files and location for framework product generation
- » Path to the executables and scripts



System Level Product Status File(PSF)

- A system PSF is produced from each processing unit run
 - » The System PSFs contains the successfully generated output/ product filenames and location, for that unit.
 - » The PSFs can be used for PS production monitoring purpose.

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- Namely:
 - » JRR_PREPROCESS_SDR.pl.PSF
 » JRR_PRODUCT_CLOUD_MASK.pl.PSF
 » JRR_PRODUCT_CLOUD_CLOUDS.pl.PSF
 » JRR_PRODUCT_AEROSOL_AODADP.pl.PSF
 » JRR_PRODUCT_AEROSOL_VOLASH.pl.PSF
 » JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PSF
 » JRR_PRODUCT_CRYOSPHERE_ICE.pl.PSF



System Level Product Log File

- A system level log file is produced from each processing unit run
 - » The System Log files contains the run status information for unit processing system.
 - » Any errors encountered during processing are notified through log file.

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• Namely:

- » JRR_PREPROCESS_SDR.pl.log
- » JRR_PRODUCT_CLOUD_MASK.pl.log
- » JRR_PRODUCT_CLOUD_CLOUDS.pl.log
- » JRR_PRODUCT_AEROSOL_AODADP.pl.log
- » JRR_PRODUCT_AEROSOL_VOLASH.pl.log
- » JRR_PRODUCT_ CRYOSPHERE_SNOW.pl.log
- » JRR_PRODUCT_ CRYOSPHERE_ICE.pl.log

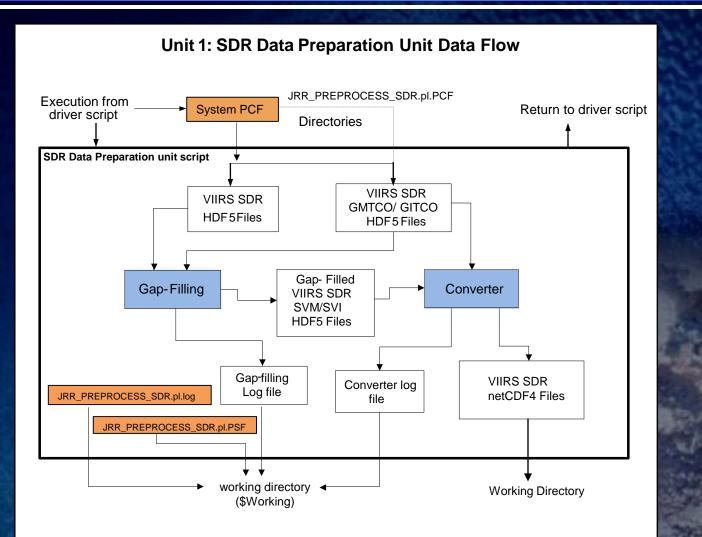


JPSS RR PS Unit Level

Unit 1. SDR Data Preparation 1.1. SDR Gap-filling 1.2. HDF5 to NetCDF4 Conversion



Unit Level Interfaces 1. SDR Data Preparation



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SDR Data Preparation System PCF

System PCF

- A System PCF (Unit level) is passed by the System driver script to the sub-units for preparation of SDR data
- The system PCF contains the input SDR data and other information required by the Gap-Filling and SDR Converter sub-units
- A section of the system PCF (JRR_PREPROCESS_SDR.pl.PCF) is shown below:

PERL_LOC=/usr/bin/perl

OPS_SCRIPT=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts

OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin

gitco=GITCO_npp_d20150402_t1054237_e1055479_b17764_c20150402172259067059_noaa_ops.h5 gmtco=GMTCO_npp_d20150402_t1054237_e1055479_b17764_c20150402171617371175_noaa_ops.h5 svi01=SVI01_npp_d20150402_t1054237_e1055479_b17764_c20150402172912367353_noaa_ops.h5 svi02=SVI02_npp_d20150402_t1054237_e1055479_b17764_c20150402172855756881_noaa_ops.h5 svi03=SVI03_npp_d20150402_t1054237_e1055479_b17764_c20150402174048712352_noaa_ops.h5 svi04=SVI04_npp_d20150402_t1054237_e1055479_b17764_c20150402172950556360_noaa_ops.h5



Sub-unit level interfaces

- A sub-unit level driver script is invoked by the system level script to start the sub-unit processing.
- Information in the system PCF is used to set up the sub-unit configuration, creating symbolic links for system files, etc.
- Gap-Filling python run scripts are called to fill the gaps on the VIIRS SDR files listed in the system PCF
- A log file is saved for the sub-unit process

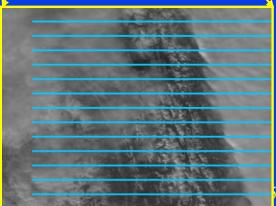


Gaps on SDR granule



SVM01_npp_d20130117_t2059265_e2100506_b06349_c20130118032130407525_noaa_ops.h5

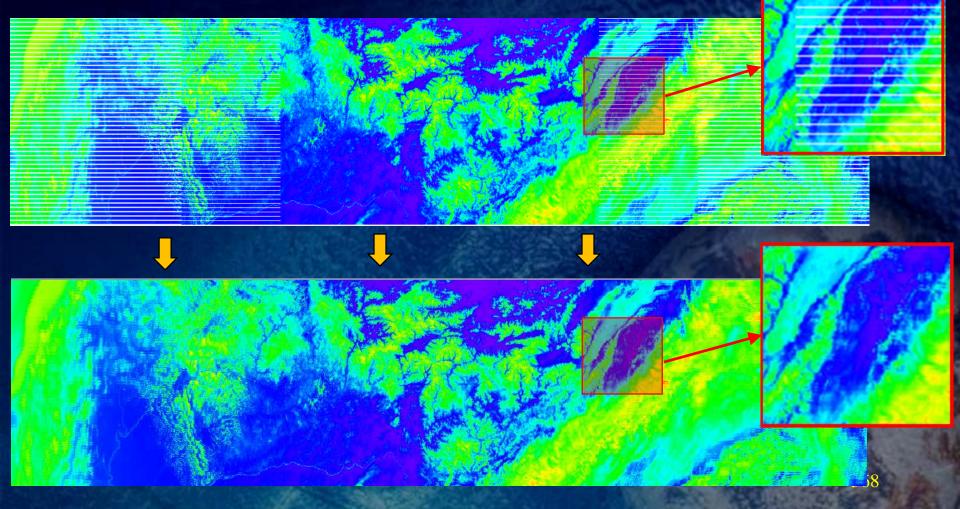
Gaps on the edges of a SDR granule, shows dropped portions of scan to reduce bow-tie effect



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SDR Before & After Gap-Filling





Sub-unit Input/Output Data

File	Input /Output	Data description			
VIIRS SDR M- band files	Input	Total of 16 moderate resolution SDR files for each VIIRS granule. SVM??_npp_d???????_t??????_e?????_b?????_c??????????????????			
VIIRS geolocation (M-band)	Input	Terrain corrected geolocation data file for each Moderate resolution VIIRS granule. GMTCO_npp_d???????_t?????_e?????_b?????_c???????????????????			
VIIRS SDR I-band files	Input	Total of 5 high resolution Imagery bands for each VIIRS granule. SVI??_npp_d???????_t??????_e??????_b?????_c?????????????????			
VIIRS geolocation (I-band)	Input	Terrain corrected geolocation data file for high resolution Imagery channels. GITCO_npp_d???????_t??????_e??????_b?????_c?????????????????			
Unit PCF	Input	Contains the directory setup of input data, scripts, etc.	ASCII		
Gap-filled VIIRS SDR M-band files			HDF5		
Gap-filled VIIRS SDR I-band files			HDF5		
Sub-unit Log file	Output	Contains log for the gap-filling sub-unit 569	ASCII		



SDR Data Preparation 1.2 HDF5 to NetCDF4 Convertor

Sub-unit level interfaces

- Information in the system PCF is used to set up the sub-unit configuration, creating symbolic links for system files, etc.
- The JPSS HDF5 converter is invoked to convert the gap-filled SDR HDF5 files, (SVM01-16 & SVI01-05) along with geolocation (GMTCO/GITCO), into NetCDF4 format
- A log file is saved for each script invoked during the process
- A Preprocessor PSF file containing the filenames of all converted VIIRS SDR/Geolocation files, is generated



SDR Data Preparation 1.2 HDF5 to NetCDF4 Convertor

Sub-unit Input/Output Data

File	Input/ Output	Data description			
Gap-filled VIIRS SDR M-band files	Input	Gap-filled 16 moderate resolution SDR files for each VIIRS granule. SVM??_npp_d???????_t??????_e?????_b?????_c????????????????_noaa_ops.h5			
VIIRS geolocation (M-band)	Input	Terrain corrected geolocation data file for each Moderate resolution VIIRS granule. GMTCO_npp_d??????_t?????_e?????_b????_c????????????????????			
Gap-filled VIIRS Input Gap-filled 5 high resolution Imagery bands for each VIIRS granule. SDR I-band files SVI??_npp_d??????_t?????_e?????_b?????_c??????_c???????????					
VIIRS geolocation (I-band)	ocation Input Terrain corrected geolocation data file for high resolution Imagery channels. GITCO_npp_d??????_t?????_e?????_b????_c????????????????????				
Unit PCF	Input	Contains the directory setup of input data, scripts, etc.			
Gap-filled VIIRS SDR M-band files in NetCDF	DR M-band files Output SVM22 npp d22222222 t2222222 e2222222 b222222 c22222222222222		NetCDF4		
VIIRS geolocation (M-band) in NetCDF converted geolocation data (terrain-corrected) file for each Moderate resolution VIIRS granule. NetCDF Output GMTCO_npp_d??????_t?????_e?????_b?????_c??????c????????????		NetCDF4			
Gap-filled VIIRS SDR I-band files in NetCDF	DR I-band files in Output Stutes and depended & Gap-filled 5 high resolution imagery bands for each VIRS granule.		NetCDF4		
VIIRS geolocation (I-band) in NetCDF			NetCDF4		
Sub unit Log file	Output	Containe log for the gon filling out unit			



SDR Data Preparation Unit PSF and Log

A preprocessor PSF containing the filenames of all converted VIIRS SDR files, is generated

A section of JRR_PREPROCESS_SDR.pl.PSF is given below: **>>**

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479 b17764/GMTCO npp d20150402_t1054237_e1055479_b17764_c20150402171617371175_noaa_ops.nc /data/data092/hxie/dlv/npp dap/nde apr2015/JRR DAP apr2015/working d20150402 t1054237 e105 5479 b17764/SVM01 npp d20150402 t1054237 e1055479 b17764 c20150402172853771802 noaa ops.nc /data/data092/hxie/dlv/npp dap/nde apr2015/JRR DAP apr2015/working d20150402 t1054237 e105 5479_b17764/SVM02_npp_d20150402_t1054237_e1055479_b17764_c20150402172837504244_noaa_ops.nc /data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479 b17764/SVM03 npp d20150402 t1054237 e1055479 b17764 c20150402172859491592 noaa ops.nc

A log file is saved for each script invoked during the process

A section of JRR_PREPROCESS_SDR.pl.log is given below:

JRR_PREPROCESS_SDR.pl is now starting at: 20150716-10:20:35 switch_gapfill: ON Running jrr_preprocess_gapfill.pl - log: jrr preprocess gapfill.pl.log - sublog: mender.log 0m1.452s real 0m0.476s user

- 0m0.813s sys



SDR Data Preparation Unit level Input/Output Data

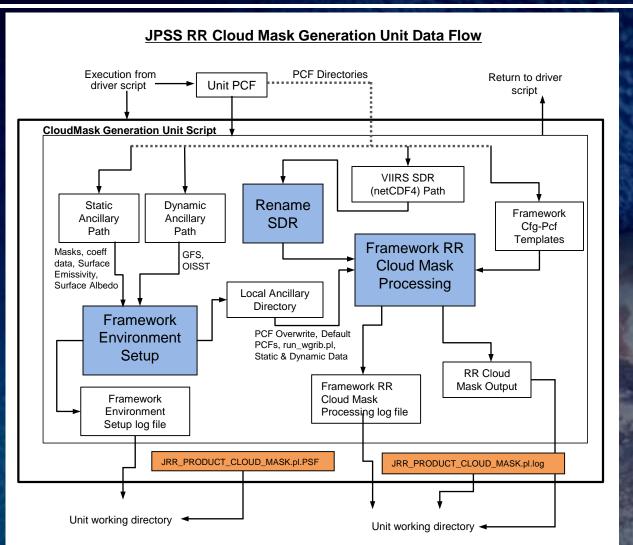
File	Input/ Output	No. of Files	Source	Format
VIIRS SDR M-band files	Input	16	IDPS	HDF5
VIIRS geolocation (M-band)	Input	1	IDPS	HDF5
VIIRS SDR I-band files	Input	5	IDPS	HDF5
VIIRS geolocation (I-band)	Input	1	IDPS	HDF5
Unit PCF	Input	1	NDE	ASCII
Gap-filled VIIRS SDR M-band files in NetCDF	Output	16	JPSS RR PS	NetCDF4
VIIRS geolocation (M-band) in NetCDF	Output	1	JPSS RR PS	NetCDF4
Gap-filled VIIRS SDR I-band files in NetCDF	Output	5	JPSS RR PS	NetCDF4
VIIRS geolocation (I-band) in NetCDF	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII 573



JPSS RR PS Unit Level

Unit 2. Cloud Mask Product Generation 2.1. Rename SDR for Framework 2.2. Framework Environment Setup 2.3. Framework Product Processing







2. Cloud Mask Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for CloudMask Generation
- The system PCF contains information on input SDR data in NetCDF format, static and dynamic ancillary data, location of scripts etc. required by the sub-units

• A section of the system PCF is given below:

OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_CLOUD_MASK_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/PCF_Overwrites DIR_CUSTOMPRODUCTLISTS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRR RPS-OPS/CustomProductLists



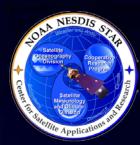
Cloud Mask Product Generation 2.1 Rename SDR for Framework

Sub-unit level interfaces

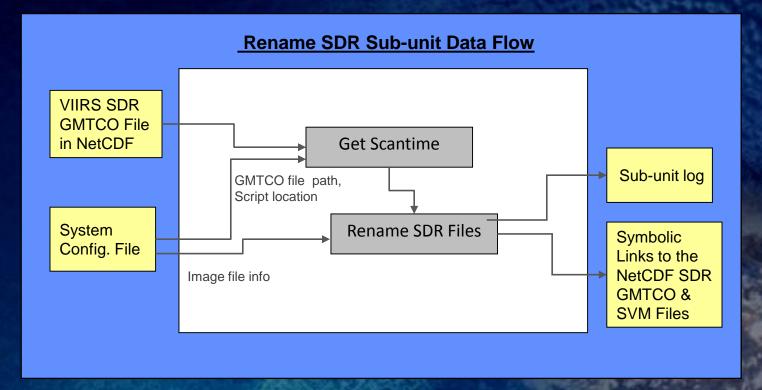
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Cloud Mask Product Generation 2.1 Rename SDR for Framework





Cloud Mask Product Generation 2.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_CLOUD_MASK.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII



Cloud Mask Product Generation 2.2 Framework Environment Setup

Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process



Cloud Mask Product Generation 2.2 Framework Environment Setup

Framework Local Environment Setup Sub-unit Flow Execution from PCF files and driver script directories Framework Environment setup script GFS. VIIRS ancillary, OISST Masks, Surface Run warib.pl Type/ Emissivity/ Static Albedo/ Elevation Dynamic Default Ancillary Ancillary PCFs Setup Setup Framework Ancillary CRTM coeff. Local Cloud mask Ancillary coeff. Directory Algorithm Ancillary Framework Framework PCF Environment Overwrites Setup log

Unit Working directory

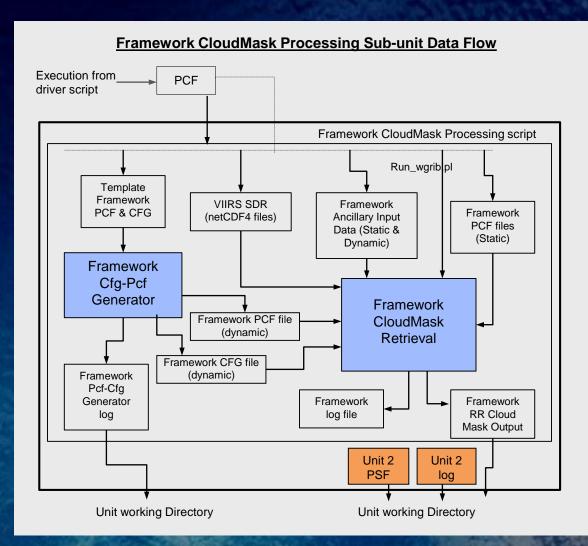


Cloud Mask Product Generation 2.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
System PCF	Input	JRR_PRODUCT_CLOUD_MASK.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII







Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before the CloudMask product retrieval is triggered
- The Framework executable is invoked to process the RR Cloud Mask retrieval systems
- The CloudMask Product Output is renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR M/I-band files	Input	NetCDF converted & Gap-filled VIIRS M/I band SDR files for each granule. SVM{bb}_npp_YYYYMMDD_hhmmss_d??????_t?????.nc, bb={03, 05, 07, 09, 10, 11, 12, 14, 15, 16} SVI{bb}_npp_YYYYMMDD_hhmmss_d??????_t?????.nc, bb={01, 04, 05}	NetCDF4
VIIRS geolocation (M/I-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each M/I res. granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????_t?????.nc GITCO_npp_YYYYMMDD_hhmmss_d??????_t??????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_CLOUD_MASK.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs, etc. for Cloud Mask processing .	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework CloudMask generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run, including land & coast mask, Surface Emissivity, Surface Albedo, Surface Elevation, satellite instrument ancillary data, SDR dummy files etc.	NetCDF4
Static Algorithm ancillary data	Input	Static coefficient file for CloudMask, CRTM coefficients files	NetCDF4/ Binary
Daily OISST	Input	Contains Reynolds OISST daily analysis at 0.25 degree resolution	NetCDF4
GFS data	Input	NCEP GFS model data in grib2 format at 0.5 degree resolution	GRIB2
RR Cloud Mask product output	Output	JPSS RR VIIRS Cloud Mask product output with related flags, metadata, etc. JRR-CloudMask_v1r0_npp_s??????????e?????????????????????????	NetCDF4
Log file	Output	The sub-unit processing log file	ASCII



Cloud Mask Product Generation Unit PSF and Log

- A Unit level PSF containing the filename and location of the successfully generated framework output product file from CloudMask retrieval processing, is created.
 - » A section of JRR_PRODUCT_CLOUD_MASK.pl.PSF is given below:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-CloudMask_v1r0_npp_s201504021054237_e201504021055479_c201507171644170.nc

#END-of-PSF

- A unit log file is saved for each script invoked during the process
 - » A section of JRR_PRODUCT_CLOUD_MASK.pl.log is given below:

JRR_PRODUCT_CLOUD_MASK.pl is now starting at: 20150717-12:42:39

```
Running jrr_product_sdr4frmwk.pl

- log: jrr_product_sdr4frmwk.pl.log

real 0m1.912s

user 0m0.235s

sys 0m0.421s
```

```
running jrr_product_sdr4frmwk.pl: OK
```



Cloud Mask Product Generation Unit Input/Output Data

File	Input/ Output	No. of Files	Source	Format	
Gap-filled VIIRS SDR M band files for channels <i>03, 05, 07, 09, 10, 11,</i> <i>12, 14, 15, 16</i>	Input	10	JPSS RR PS	NetCDF4	
Gap-filled VIIRS SDR I band files for channels 01, 04, 05	Input	3	JPSS RR PS	NetCDF4	
VIIRS geolocation files (M & I bands)	Input	2	JPSS RR PS	NetCDF4	
Daily OISST	Input	1	PDA	NetCDF4	
GFS	Input	2	PDA	GRIB2	
Static Framework ancillary data	Input	-	DAP	NetCDF4	
Static Algorithm ancillary data	Input	-	DAP	NetCDF4/Binary	
Unit PCF	Input	1	NDE	ASCII	
RR Cloud Mask product	Output	1	JPSS RR PS	NetCDF4	
Unit PSF	Output	1	JPSS RR PS	ASCII	
Unit Log file	Output	1	JPSS RR PS	ASCII 587	

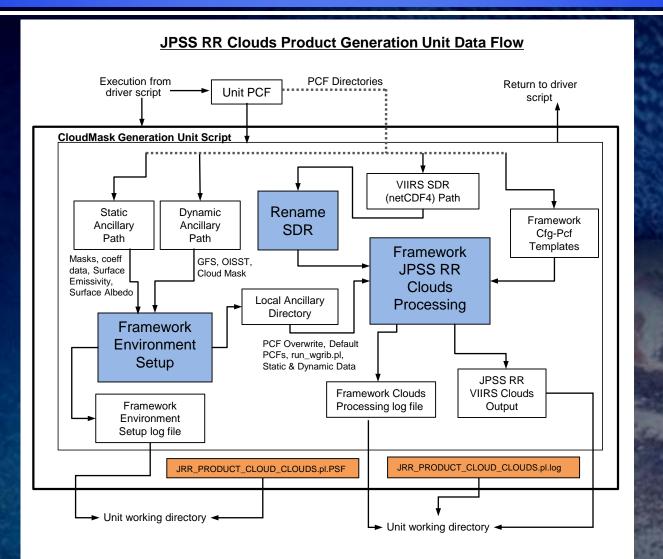


JPSS RR PS Unit Level

Unit 3. Clouds Product Generation 3.1. Rename SDR for Framework 3.2. Framework Environment Setup 3.3. Framework Clouds Product Processing



Unit Level Interfaces 3. Clouds Product Generation



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3. Clouds Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for Clouds Product Generation
- The system PCF contains information on input SDR data in NetCDF format, RR VIIRS Cloud Mask data, static and dynamic ancillary data, location of scripts etc. required by the sub-units
- A section of the system PCF is given below:

SCRIPT_FOR_GFS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts/run_wgrib.pl PERL_LOC=/usr/bin/perl OPS_SCRIPT=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_CLOUD_CLOUDS_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_CLOUD_CLOUDS_TEMPLATE.



Clouds Product Generation 3.1 Rename SDR for Framework

Sub-unit level interfaces

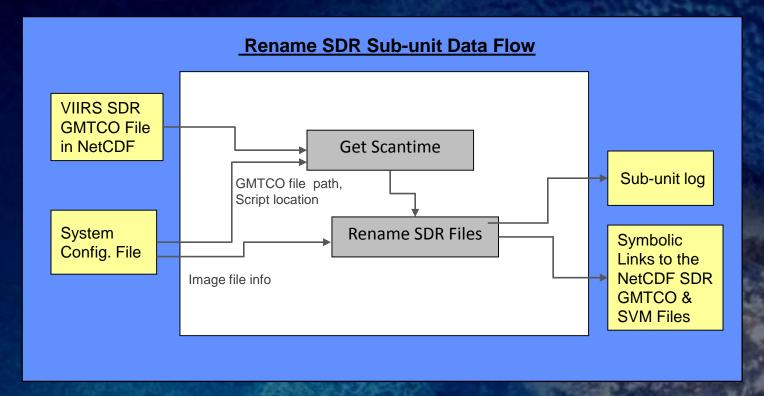
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Clouds Product Generation 3.1 Rename SDR for Framework

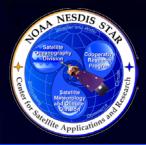




Clouds Product Generation 3.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_CLOUD_CLOUDS.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII



Clouds Product Generation 3.2 Framework Environment Setup

Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process



Clouds Product Generation 3.2 Framework Environment Setup

Framework Local Environment Setup Sub-unit Flow Execution from PCF files and driver script directories Framework Environment setup script GFS. VIIRS ancillary, OISST. RR Masks, Surface Run_wgrib.pl Cloud Mask Type/Emissivity/ Static Elevation Dynamic Default Ancillary Ancillary PCFs Setup Setup Framework Ancillary CRTM coeff., Local Clouds coeff.. Ancillary LUTs Directory Algorithm Ancillary Framework Framework PCF Environment Overwrites Setup log

Unit Working directory

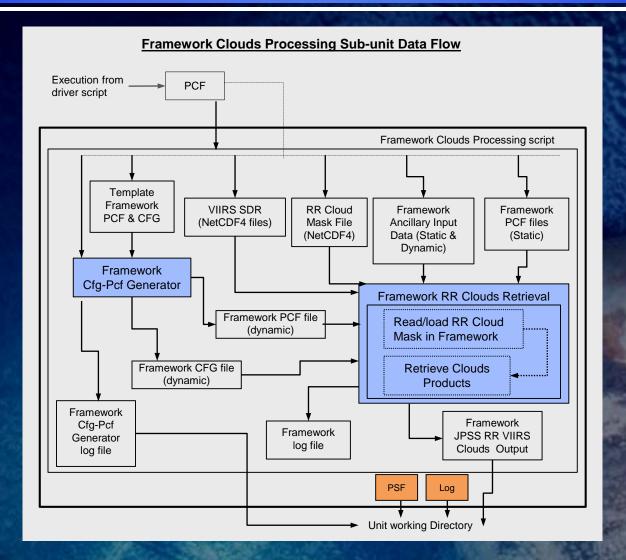


Clouds Product Generation 3.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
System PCF	Input	JRR_PRODUCT_CLOUD_CLOUDS.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII





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Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before the Clouds product retrieval is triggered
- The Framework executable is invoked to process the JPSS RR VIIRS Clouds retrieval systems
- The Clouds Product Output files are renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Sub-unit Input Data

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR M-band files	Input	NetCDF converted & Gap-filled VIIRS M band SDR files for each granule. SVM{bb}_npp_YYYYMMDD_hhmmss_d???????_t??????.nc, bb={05, 11, 12, 14, 15, 16}	NetCDF4
VIIRS geolocation (M-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????_t??????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_CLOUD_CLOUDS.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs including RR Cloud Mask product, etc. required for Clouds processing.	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework Clouds generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run, including land & coast mask, Surface Emissivity, Surface Elevation, Surface Albedo, satellite instrument ancillary data, SDR dummy files, etc.	NetCDF4
Static Algorithm ancillary data	Input	Static coefficient file for DCOMP, NCOMP, CRTM coefficients, etc.	NetCDF4/ Binary
Daily OISST	Input	Contains Reynolds OISST daily analysis at 0.25 degree resolution	NetCDF4
GFS data	Input	NCEP GFS model data in grib2 format at 0.5 degree resolution	GRIB2
RR Cloud Mask	Input	JPSS RR VIIRS Cloud Mask product file	NetCDF4



Sub-unit Output Data

File	Input/ Output	Data description	Format
RR Cloud Phase output file	Output	JPSS RR VIIRS Cloud Phase and Cloud Type product output file. JRR-CloudPhase_v1r0_npp_s?????????????e???????????????????c??????	NetCDF4
RR Cloud Height output file	Output	Contains JPSS RR VIIRS Cloud -top Height/Pressure/Temperature products and related quality flags and metadata JRR-CloudHeight_v1r0_npp_s??????????e?????????????????????????	NetCDF4
RR Daytime Cloud Optical Properties	Output	Contains JPSS RR Daytime Cloud Liquid/Ice Water Path, Cloud Particle Size and Cloud Optical Depth products and related quality information JRR-CloudDCOMP_v1r0_npp_s????????????e???????????????????????	NetCDF4
RR Nighttime Cloud Optical Properties	Output	Contains JPSS RR Nighttime Cloud Liquid/Ice Water Path, Cloud Particle Size and Cloud Optical Depth products and related quality information JRR-CloudNCOMP_v1r0_npp_s???????????e????????????????????????	NetCDF4
Log file	Output	The sub-unit processing log file	ASCII





Clouds Product Generation Unit PSF and Log

- A Unit level PSF containing the filename and location of the successfully generated framework output product file from CloudMask retrieval processing, is created.
 - » A section of JRR_PRODUCT_CLOUD_CLOUDS.pl.PSF is given below:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-CloudPhase_v1r0_npp_s201504021054237_e201504021055479_c201507171652000.nc /data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-

CloudHeight_v1r0_npp_s201504021054237_e201504021055479_c201507171652020.nc /data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-CloudDCOMP_v1r0_npp_s201504021054237_e201504021055479_c201507171652070.nc

A unit log file is saved for each script invoked during the process
 » A section of JRR_PRODUCT_CLOUD_CLOUDS.pl.log is given below:

JRR_PRODUCT_CLOUD_CLOUDS.pl is now starting at: 20150717-16:50:54

```
Running jrr_product_sdr4frmwk.pl

- log: jrr_product_sdr4frmwk.pl.log

real 0m0.849s

user 0m0.235s

sys 0m0.205s
```

running jrr_product_sdr4frmwk.pl: OK



Clouds Product Generation Unit Input/Output Data

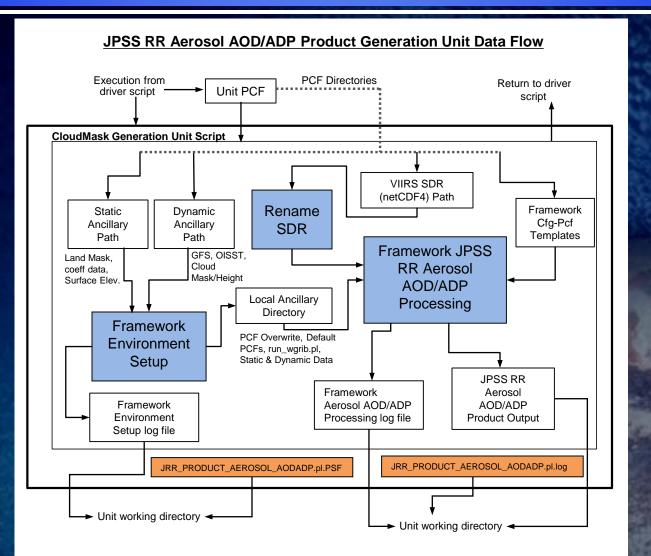
File	Input/ Output	No. of Files	Source	Format
Gap-filled VIIRS SDR M band files for channels 05, 11, 12, 14, 15, 16	Input	6	JPSS RR PS	NetCDF4
VIIRS M band geolocation file	Input	1	JPSS RR PS	NetCDF4
Daily OISST	Input	1	PDA	NetCDF4
GFS	Input	2	PDA	GRIB2
RR Cloud Mask product	Input	1	NDE	NetCDF4
Static Framework ancillary data	Input	-	DAP	NetCDF4
Static Algorithm ancillary data	Input	-	DAP	NetCDF4/Binary
Unit PCF	Input	1	NDE	ASCII
RR Cloud Phase output file (Cloud Phase/Type)	Output	1	JPSS RR PS	NetCDF4
RR Cloud Height output file (Cloud-top Height/Pressure/Temperature, CCL)	Output	1	JPSS RR PS	NetCDF4
RR Daytime Cloud Optical Properties (LWP, IWP, COD, CPS)	Output	1	JPSS RR PS	NetCDF4
RR Nighttime Cloud Optical Properties (LWP, IWP, COD, CPS)	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII



JPSS RR PS Unit Level

Unit 4. Aerosol AOD/ADP Product Generation
4.1. Rename SDR for Framework
4.2. Framework Environment Setup
4.3. Framework Aerosol AOD/ADP Product Processing







4. Aerosol AOD/ADP Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for Clouds Product Generation
- The system PCF contains information on input SDR data in NetCDF format, RR VIIRS Cloud Mask & Cloud Height data, static and dynamic ancillary data, location of scripts etc. required by the subunits

• A section of the system PCF is given below:

SCRIPT_FOR_GFS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts/run_wgrib.pl PERL_LOC=/usr/bin/perl OPS_SCRIPT=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_AEROSOL_AODADP_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/PCF_Overwrites



Aerosol AOD/ADP Product Generation 4.1 Rename SDR for Framework

Sub-unit level interfaces

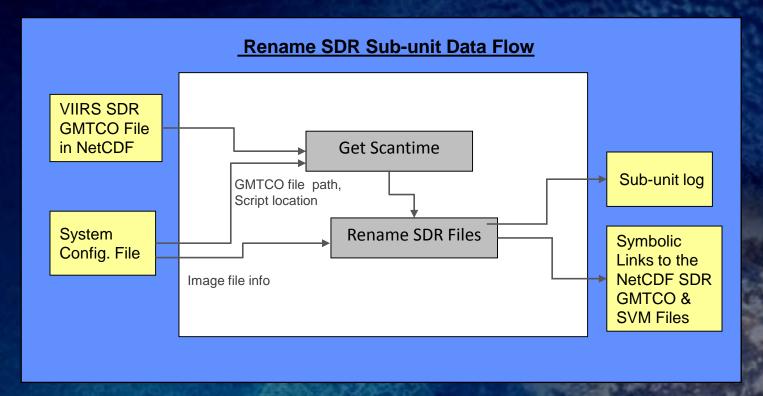
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Aerosol AOD/ADP Product Generation 4.1 Rename SDR for Framework



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Aerosol AOD/ADP Product Generation 4.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_AEROSOL_AODADP.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII



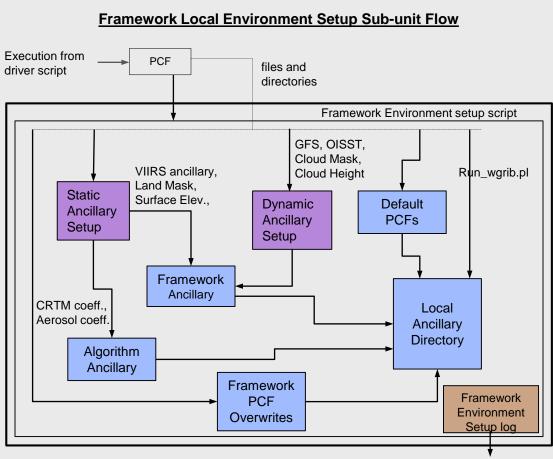
Aerosol AOD/ADP Product Generation 4.2 Framework Environment Setup

Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process



Aerosol AOD/ADP Product Generation 4.2 Framework Environment Setup



Unit Working directory



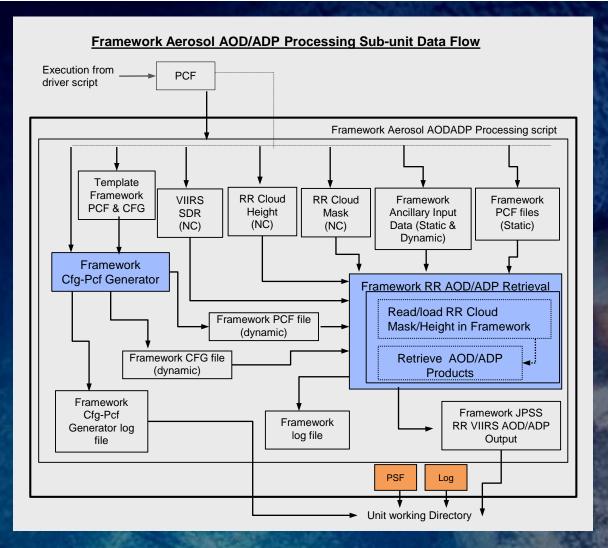
Aerosol AOD/ADP Product Generation 4.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
System PCF	Input	JRR_PRODUCT_AEROSOL_AODADP.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII



Aerosol AOD/ADP Product Generation 4.3 Framework AOD/ADP Processing



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Aerosol AOD/ADP Product Generation 4.3 Framework AOD/ADP Processing

Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before AOD/ADP product retrieval is triggered
- The Framework executable is invoked to process the JPSS RR VIIRS AOD/ADP retrieval systems
- Framework reads the L1b, ancillary data, and the RR the Cloud Mask & Cloud Height product data before processing the RR AOD/ADP algorithms
- The AOD/ADP Product Output is renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Aerosol AOD/ADP Product Generation 4.3 Framework AOD/ADP Processing

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR M-band files	Input	NetCDF converted & Gap-filled VIIRS M/I band SDR files for each granule. SVM{bb}_npp_YYYYMMDD_hhmmss_d??????_t?????.nc, bb={01, 02, 03, 04, 05, 06, 07, 08, 09, 10, 11, 12, 13, 15, 16}	NetCDF4
VIIRS geolocation (M-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????_t??????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_AEROSOL_AODADP.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs including RR Cloud Mask and Cloud Height product files, etc.	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework Aerosol AOD and ADP generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run, including land & coast mask, Surface Emissivity, Surface Elevation, satellite instrument ancillary data, etc.	NetCDF4
Static Algorithm ancillary data	Input	Static coefficient files for AOD, SDR dummy files, etc.	NetCDF4
Daily OISST	Input	Contains Reynolds OISST daily analysis at 0.25 degree resolution	NetCDF4
GFS data	Input	NCEP GFS model data in grib2 format at 0.5 degree resolution	GRIB2
RR Cloud Mask	Input	JPSS RR VIIRS Cloud Mask product file	NetCDF4
RR Cloud Height	Input	JPSS RR VIIRS Cloud Height product file	NetCDF4
JPSS RR VIIRS AOD Product Output	Output	JPSS RR VIIRS Aerosol Product output containing Aerosol Optical Depth and Aerosol Particle Size Parameter JRR-AOD_v1r0_npp_s?????????????e??????????????????????	NetCDF4
JPSS RR VIIRS ADP Product Output	Output	JPSS RR VIIRS Aerosol product output containing Aerosol Detection (Smoke & Dust) product File JRR-ADP_v1r0_npp_s??????????????????????????????????	NetCDF4
Log file	Output	The sub-unit processing log file	ASCII



Aerosol AOD/ADP Product Generation Unit PSF and Log

 A Unit level PSF containing the filename and location of the successfully generated framework output product file from CloudMask retrieval processing, is created.

» A section of JRR_PRODUCT_AEROSOL_AODADP.pl.PSF is given below:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-AOD_v1r0_npp_s201504021054237_e201504021055479_c201507171724120.nc /data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e105 5479_b17764//JRR-ADP_v1r0_npp_s201504021054237_e201504021055479_c201507171724150.nc

#END-of-PSF

A unit log file is saved for each script invoked during the process

» A section of JRR_PRODUCT_AEROSOL_AODADP.pl.log is given

JRR_PRODUCT_AEROSOL_AODADP.pl is now starting at: 20150717-17:22:58

```
Running jrr_product_sdr4frmwk.pl
- log: jrr_product_sdr4frmwk.pl.log
real 0m0.754s
user 0m0.253s
```

```
sys 0m0.456s
running jrr product sdr4frmwk.pl: OK
```



Aerosol AOD/ADP Product Generation Unit Input/Output Data

File	Input/ Output	No. of Files	Source	Format
Gap-filled VIIRS SDR M band files for channels 01, 02, 03, 04, 05, 06, 07, 08, 09, 10, 11, 12, 13, 15, 16	Input	15	JPSS RR PS	NetCDF4
VIIRS M band geolocation file	Input	1	JPSS RR PS	NetCDF4
Daily OISST	Input	1	PDA	NetCDF4
GFS	Input	2	PDA	GRIB2
RR Cloud Mask product	Input	1	NDE	NetCDF4
RR Cloud Height product output	Input	1	NDE	NetCDF4
Static Framework ancillary data	Input	-	DAP	NetCDF4
Static Algorithm ancillary data	Input	-	DAP	NetCDF4/Binary
Unit PCF	Input	1	NDE	ASCII
RR AOD product output file (AOD/APS)	Output	1	JPSS RR PS	NetCDF4
RR ADP product output (Aerosol detection: Smoke/Dust)	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII 616

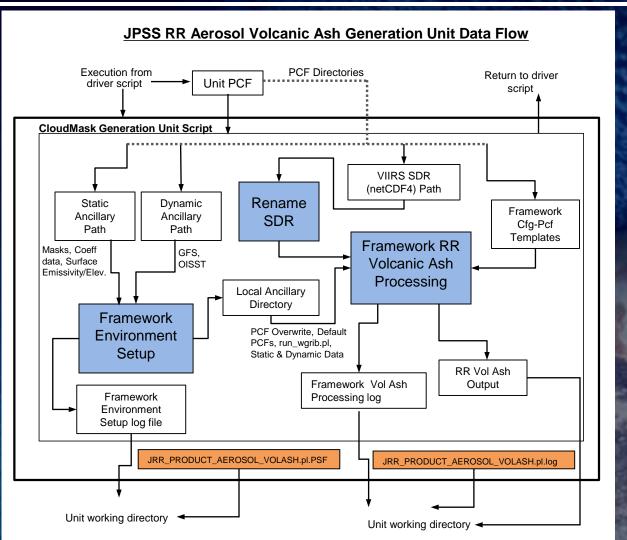


JPSS RR PS Unit Level

Unit 5. Aerosol Volcanic Ash Product Generation

5.1. Rename SDR for Framework5.2. Framework Environment Setup5.3. Framework Product Processing







5. Volcanic Ash Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for Volcanic Ash Generation
- The system PCF contains information on input SDR data in NetCDF format, static and dynamic ancillary data, location of scripts etc. required by the sub-units

• A section of the system PCF is given below:

OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_AEROSOL_VOLASH_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/PCF_Overwrites DIR_CUSTOMPRODUCTLISTS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRR RPS-OPS/CustomProductLists



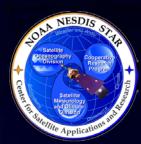
Volcanic Ash Product Generation 5.1 Rename SDR for Framework

Sub-unit level interfaces

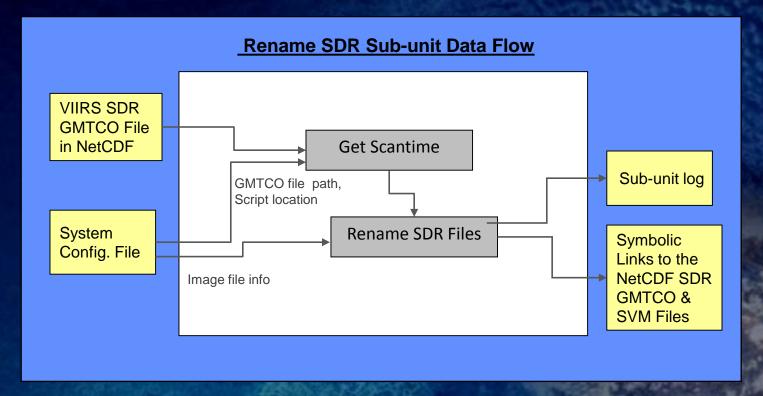
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Volcanic Ash Product Generation 5.1 Rename SDR for Framework





Volcanic Ash Product Generation 5.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_AEROSOL_VOLASH.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII



Volcanic Ash Product Generation 5.2 Framework Environment Setup

Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process





Volcanic Ash Product Generation 5.2 Framework Environment Setup

Framework Local Environment Setup Sub-unit Flow Execution from PCF files and driver script directories Framework Environment setup script GFS. VIIRS ancillary, OISST Land/Volcano Masks, Run warib.pl Surface Emissivity/ Static Elevation Dynamic Default Ancillary Ancillary PCFs Setup Setup Framework Ancillary Local CRTM coeff., Ancillary VolAsh coeff. Directory Algorithm Ancillary Framework Framework PCF Environment Overwrites Setup log

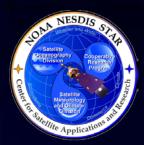
Unit Working directory



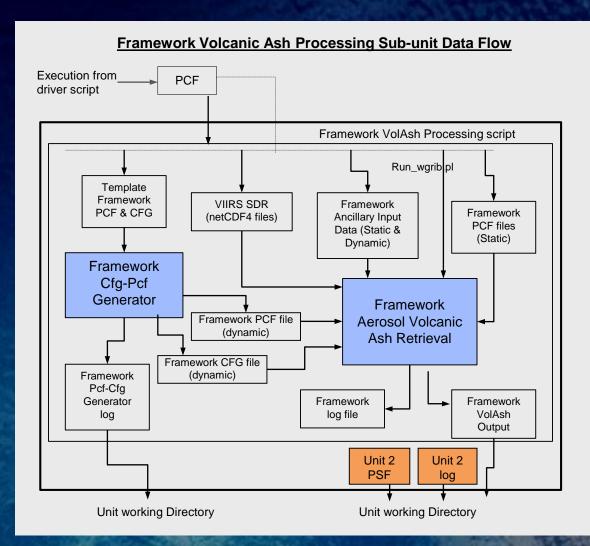
Volcanic Ash Product Generation 5.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
System PCF	Input	JRR_PRODUCT_AEROSOL_VOLASH.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII



Volcanic Ash Product Generation 5.3 Framework VolAsh Processing





Volcanic Ash Product Generation 5.3 Framework VolAsh Processing

Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before Volcanic Ash product retrieval is triggered
- The Framework executable is invoked to process the Volcanic Ash retrieval systems
- The Volcanic Ash Product Output is renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Volcanic Ash Product Generation 5.3 Framework VolAsh Processing

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR M-band files	Input	NetCDF converted & Gap-filled VIIRS M/I band SDR files for each granule. SVM{bb}_npp_YYYYMMDD_hhmmss_d???????_t??????.nc, bb={14, 15, 16}	NetCDF4
VIIRS geolocation (M-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each M res. granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????_t??????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_AEROSOL_VOLASH.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs, etc. for VolAsh processing .	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework VolAsh generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run, including Land Mask, Volcano Mask, Surface Emissivity, Surface Elevation, satellite instrument ancillary data, etc.	NetCDF4
Static Algorithm ancillary data	Input	Static coefficient file for VolAsh, CRTM coefficients, SDR dummy files	NetCDF4/ Binary
Daily OISST	Input	Contains Reynolds OISST daily analysis at 0.25 degree resolution	NetCDF4
GFS data	Input	NCEP GFS model data in grib2 format at 0.5 degree resolution	GRIB2
RR Volcanic Ash product file	Output	JPSS RR VIIRS Volcanic Ash detection –Mass Loading and Height product output with related flags, metadata, etc. JRR-VolcanicAsh_v1r0_npp_s?????????e???????c????????c???????????	
Log file	Output	The sub-unit processing log file	ASCII



Volcanic Ash Product Generation Unit PSF and Log

- A Unit level PSF containing the filename and location of the successfully generated framework output product file from Volcanic Ash retrieval processing, is created.
 - » A section of JRR_PRODUCT_AEROSOL_VOLASH.pl.PSF is given below:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150402_t1054237_e10554 79_b17764//JRR-VolcanicAsh_v1r0_npp_s201504021054237_e201504021055479_c201507171707180.nc

#END-of-PSF

- A unit log file is saved for each script invoked during the process
 - » A section of JRR_PRODUCT_AEROSOL_VOLASH.pl.log is given

JRR_PRODUCT_AEROSOL_VOLASH.pl is now starting at: 20150717-17:06:08

```
Running jrr_product_sdr4frmwk.pl

- log: jrr_product_sdr4frmwk.pl.log

real 0m1.394s

user 0m0.245s

sys 0m0.462s
```

running jrr product sdr4frmwk.pl: OK



Volcanic Ash Product Generation Unit Input/Output Data

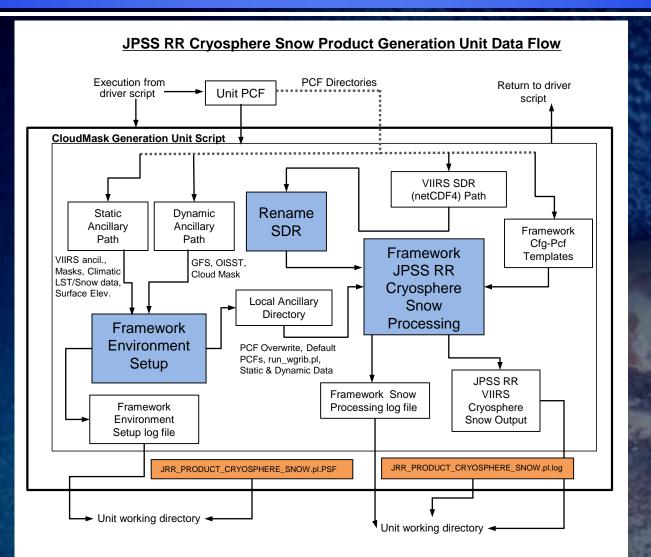
File	Input/ Output	No. of Files	Source	Format
Gap-filled VIIRS SDR M band files for channels <i>14, 15, 16</i>	Input	3	JPSS RR PS	NetCDF4
VIIRS M band geolocation file	Input	1	JPSS RR PS	NetCDF4
Daily OISST	Input	1	PDA	NetCDF4
GFS	Input	2	PDA	GRIB2
Static Framework ancillary data	Input	-	DAP	NetCDF4
Static Algorithm ancillary data	Input	-	DAP	NetCDF4/Binary
Unit PCF	Input	1	NDE	ASCII
RR Volcanic Ash product output file (Mass Loading/Height)	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII



JPSS RR PS Unit Level

Unit 6. Cryosphere Snow Product Generation
6.1. Rename SDR for Framework
6.2. Framework Environment Setup
6.3. Framework Snow Product Processing

Unit Level Interfaces 6. Cryosphere Snow Product Generation





6. Cryosphere Snow Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for Clouds Product Generation
- The system PCF contains information on input SDR data in NetCDF format, RR VIIRS Cloud Mask data, static and dynamic ancillary data, location of scripts etc. required by the sub-units
- A section of the system PCF is given below:

PERL_LOC=/usr/bin/perl OPS_SCRIPT=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_CRYOSPHERE_SNOW_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/PCF_Overwrites DIR_CUSTOMPRODUCTLISTS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/CustomProductLists



Cryosphere Snow Product Generation 6.1 Rename SDR for Framework

Sub-unit level interfaces

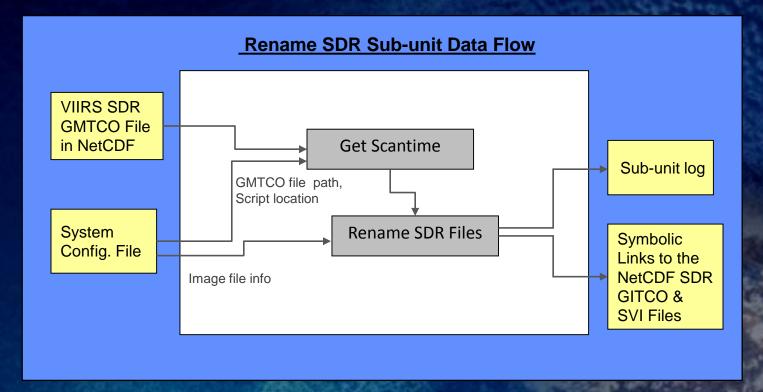
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Cryosphere Snow Product Generation 6.1 Rename SDR for Framework





Cryosphere Snow Product Generation 6.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII



Cryosphere Snow Product Generation 6.2 Framework Environment Setup

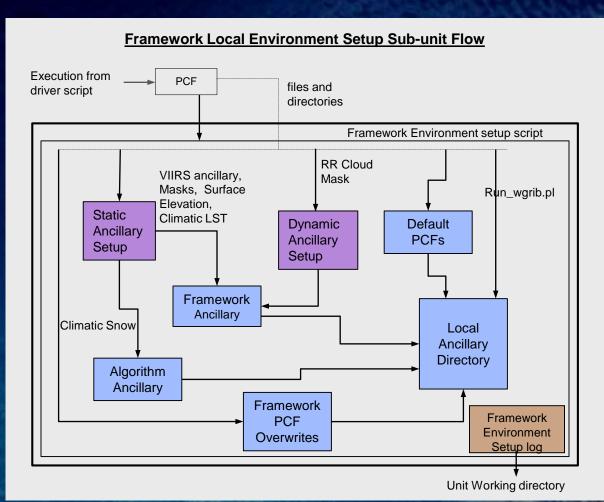
Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process





Cryosphere Snow Product Generation 6.2 Framework Environment Setup





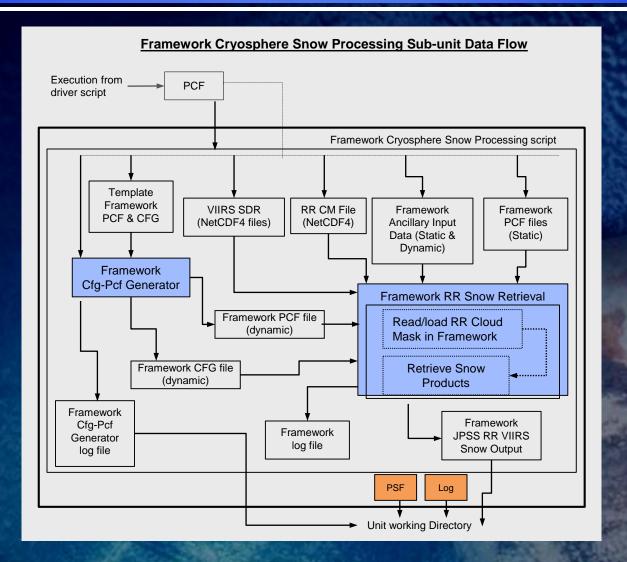
Cryosphere Snow Product Generation 6.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	
System PCF	Input	JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII



Cryosphere Snow Product Generation 6.3 Framework Snow Processing





Cryosphere Snow Product Generation 6.3 Framework Snow Processing

Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before the Snow product retrieval is triggered
- The Framework executable is invoked to process the JPSS RR VIIRS Snow retrieval systems
- Framework reads the L1b, ancillary data, and the RR the Cloud Mask product data before processing the RR Snow algorithms
- The Snow Product Output files for both Binary and Fractional Snow Cover are renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Cryosphere Snow Product Generation 6.3 Framework Clouds Processing

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR I-band files	Input	NetCDF converted & Gap-filled VIIRS I band SDR files for each granule. SVI{bb}_npp_YYYYMMDD_hhmmss_d??????_t?????.nc, bb={01, 02, 03, 04, 05}	NetCDF4
VIIRS geolocation (M/I-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????t?????.nc GITCO_npp_YYYYMMDD_hhmmss_d??????t?????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs including RR Cloud Mask product, etc. required for Snow processing.	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework Snow generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run, including 1km and 250m Land Mask, Surface Elevation, Satellite Instrument Ancillary data, SDR dummy files, Climatic LST etc.	NetCDF4
Static Algorithm ancillary data	Input	Static files for Climatic Snow	NetCDF4
RR Cloud Mask	Input	JPSS RR VIIRS Cloud Mask product file	NetCDF4
RR Binary Snow Cover output file	Output	JPSS RR VIIRS Binary Snow Mask product , NDSI Fractional Snow Cover product, & Reflectance-based Fractional Snow Cover product with associated quality flag and metadata. JRR-SnowCover_v1r0_npp_s??????????????????????????????????	NetCDF4
Log file	Output	The sub-unit processing log file	ASCII



Cryosphere Snow Product Generation Unit PSF and Log

- A Unit level PSF containing the filename and location of the successfully generated framework output product file from Snow retrieval processing, is created.
 - » A section of JRR_PRODUCT_CRYOSPHERE_SNOW.pl.PSF is given:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150511_ t1225439_e1227081_b18318//JRR-SnowCover_v1r0_npp_s201505111225439_e201505111227081_c201508261935540.nc

#END-of-PSF

A unit log file is saved for each script invoked during the process
 » A section of JRR_PRODUCT_CRYOSPHERE_SNOW.pl.log is given:

JRR_PRODUCT_CRYOSPHERE_SNOW.pl is now starting at: 20150826-19:34:51

Running jrr_product_sdr4frmwk.pl - log: jrr_product_sdr4frmwk.pl.log real 0m0.532s user 0m0.243s

sys 0m0.124s
running jrr_product_sdr4frmwk.pl: OK



Cryosphere Snow Product Generation Unit Input/Output Data

File	Input/ Output	No. of Files	Source	Format
Gap-filled VIIRS SDR I band files for channels 01, 02, 03, 04, 05	Input	5	JPSS RR PS	NetCDF4
VIIRS I band geolocation file	Input	1	JPSS RR PS	NetCDF4
VIIRS M band geolocation file	Input	1	JPSS RR PS	NetCDF4
RR Cloud Mask product	Input	1	NDE	NetCDF4
Static Framework ancillary data	Input	-	DAP	NetCDF4
Static Algorithm ancillary data	Input	-	DAP	NetCDF4/Binary
Unit PCF	Input	1	NDE	ASCII
RR Binary Snow Cover output file containing products Binary Snow Mask, NDSI Snow Fraction, and Reflectance based Snow fraction, at 375 m resolution	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII

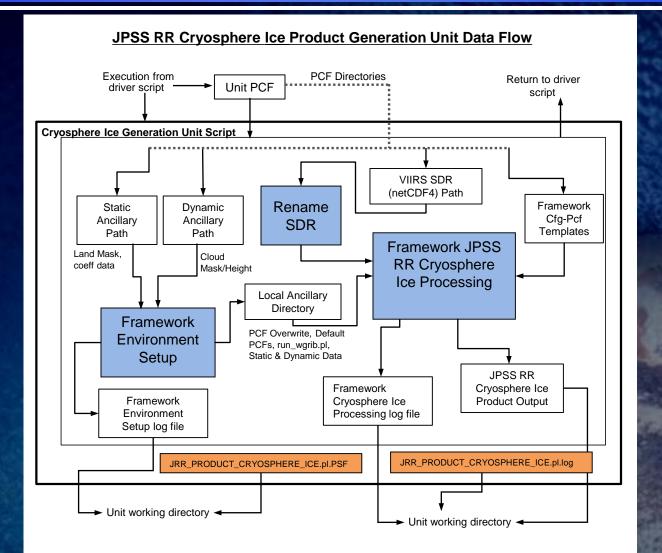


JPSS RR PS Unit Level

Unit 7. Cryosphere Ice Product Generation
7.1. Rename SDR for Framework
7.2. Framework Environment Setup
7.3. Framework Cryosphere Ice Product Processing



Unit Level Interfaces 7. Cryosphere Ice Product Generation





7. Cryosphere Ice Product Generation

System PCF

- A System PCF(Unit level) is passed by the System driver script to the sub-units for Cryosphere Ice Product Generation
- The system PCF contains information on input SDR data in NetCDF format, RR VIIRS Cloud Mask & Cloud Height data, static and dynamic ancillary data, location of scripts etc. required by the subunits

A section of the system PCF is given below:

PERL_LOC=/usr/bin/perl

OPS_SCRIPT=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/scripts OPS_BIN=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/bin PCF_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_SDR_Template.pcf CFG_TEMPLATE=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/templates/NPP_VIIRS_CRYOSPHERE_ICE_Template.cfg DIR_DEFAULT_PCF=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/Default_PCF DIR_PCF_OVERWRITES=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/PCF_Overwrites DIR_CUSTOMPRODUCTLISTS=/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/JRRPS-OPS/CustomProductLists



Cryosphere Ice Product Generation 7.1 Rename SDR for Framework

Sub-unit level interfaces

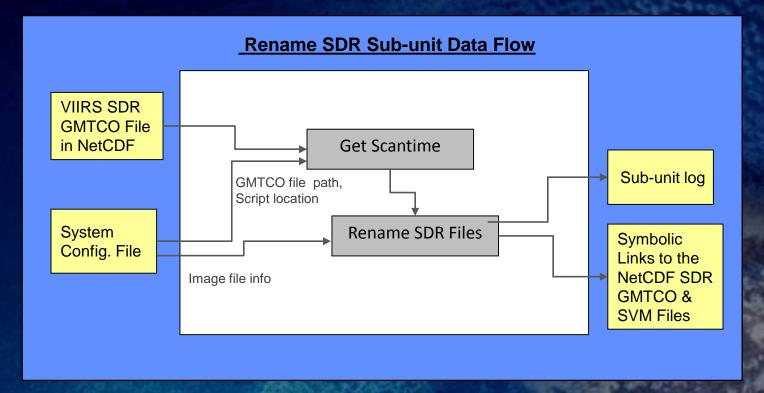
- Information in the system PCF is used to set up the sub-unit configuration
- The granule scantime obtained from the Geolocation file, by execution of get_sdr_scan_time.exe, is used to coin filenames comprehensible to framework
- Symbolic links are established with respective input NetCDF4 SDR files
- A sub-unit log file is saved for the process
- The general convention for renaming is as below:

Input Files:

Symbolic Link names, for framework: G?TCO_npp_{scantime}_d???????_t?????.nc SV???_npp_{scantime}_d???????_t?????.nc where, scantime format is YYYYMMDD_hhmmss



Cryosphere Ice Product Generation 7.1 Rename SDR for Framework



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Cryosphere Ice Product Generation 7.1 Rename SDR for Framework

Sub-unit Input/Output Data

File	Input/ Output	Data description	
VIIRS granule geolocation file	Input	VIIRS granule terrain corrected geolocation data. GMTCO_npp_d???????_t??????_e??????_b?????_c?????????????????	NetCDF4
System PCF	Input	Contains directories and setup of input data, scripts, etc. JRR_PRODUCT_CRYOSPHERE_ICE.pl.PCF	ASCII
Log file	Output	Contains log for the sub-unit	ASCII

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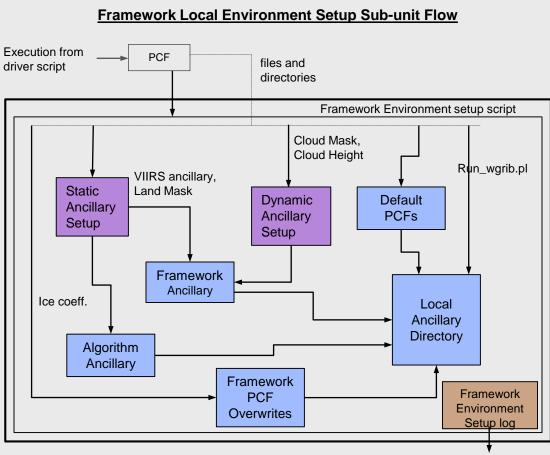
Cryosphere Ice Product Generation 7.2 Framework Environment Setup

Sub-unit level interfaces

- The Framework Environment Setup script make use of the system PCF to set up the local environment
- Creates directories for algorithm_ancillary, framework_ancillary and their subdirectories
- Establish symbolic links to AIT Framework Default_PCF, PCF_Overwrites, and ancillary data
- A sub-unit log file is saved for the process



Cryosphere Ice Product Generation 7.2 Framework Environment Setup



Unit Working directory

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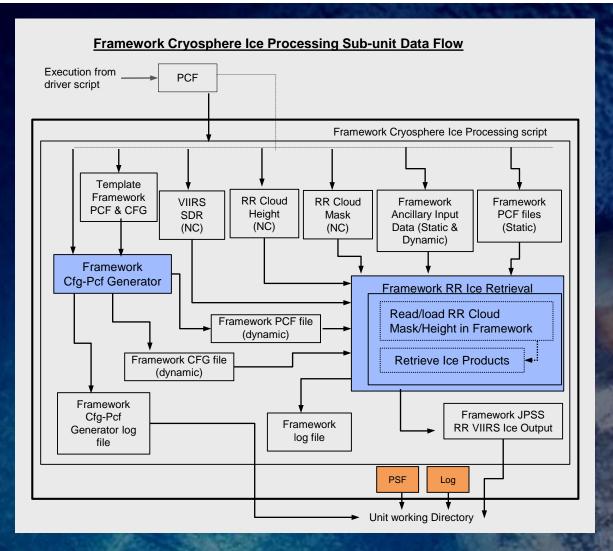
Cryosphere Ice Product Generation 7.2 Framework Environment Setup

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
System PCF	Input	JRR_PRODUCT_CRYOSPHERE_ICE.pl.PCF Contains the setup of working directory, directory settings, filename & path for static ancillary, filenames of dynamic ancillary, location and name of each gap-filled and converted input SDR files for the granule, etc.	ASCII
Log file	Output	The sub-unit processing log	ASCII



Cryosphere Ice Product Generation 7.3 Framework Ice Processing



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Cryosphere Ice Product Generation 7.3 Framework Ice Processing

Sub-unit Level Interfaces

- The Framework PCFs and CFG are generated from the template files before the Cryosphere Ice product retrieval is triggered
- The Framework executable is invoked to process the JPSS RR VIIRS Ice retrieval systems
- Framework reads the L1b, ancillary data, and the RR the Cloud Mask & Cloud Height product data before processing the RR Ice algorithms
- The Ice Product Output files are renamed with the granule starttime, endtime and createtime to meet NDE requirement
- A sub-unit log file is saved for the process



Cryosphere Ice Product Generation 7.3 Framework Ice Processing

Sub-unit Input/Output Data

File	Input/ Output	Data description	Format
Gap-filled VIIRS SDR M-band files	Input	NetCDF converted & Gap-filled VIIRS M/I band SDR files for each granule. SVM{bb}_npp_YYYYMMDD_hhmmss_d??????_t??????.nc, bb={03, 04, 05, 07, 10, 15, 16}	NetCDF4
VIIRS geolocation (M-band)	Input	NetCDF converted VIIRS geolocation data (terrain-corrected) file for each granule. GMTCO_npp_YYYYMMDD_hhmmss_d??????_t??????.nc	NetCDF4
System PCF	Input	JRR_PRODUCT_CRYOSPHERE_ICE.pl.PCF Contains the setup of working directory, directory settings, location and name of granule SDR files, primary /ancillary inputs including RR Cloud Mask and Cloud Height product files, etc.	ASCII
Framework PCF/CFG templates	Input	Template files used to generate overwritten PCFs and CFGs for framework Cryosphere Ice generation	ASCII
Static Framework ancillary data	Input	Static data for framework product run such as Land mask	NetCDF4
Static Algorithm ancillary data	Input	Static coefficient files for Ice, SDR dummy files, etc.	NetCDF4
RR Cloud Mask	Input	JPSS RR VIIRS Cloud Mask product file	NetCDF4
RR Cloud Height	Input	JPSS RR VIIRS Cloud Height product file	NetCDF4
JPSS RR VIIRS Cryosphere Ice Concentration Product File	Output	Contains Cryosphere Ice Concentration a& Ice Surface Temperature product output with related meta data and quality flags JRR-IceConcentration_v1r0_npp_s??????????e????????????????????c????????	NetCDF4
JPSS RR VIIRS Ice Age Product File	Output	Contains Cryosphere Ice Age & Ice Thickness product outputs with related meta data and quality flags JRR-IceAge_v1r0_npp_s??????????e?????????????????????????	NetCDF4
Log file	Output	The sub-unit processing log file	ASCII



Cryosphere Ice Product Generation Unit PSF and Log

 A Unit level PSF containing the filename and location of the successfully generated framework output product file from CloudMask retrieval processing, is created.

» A section of JRR_PRODUCT_CRYOSPHERE_ICE.pl.PSF is given below:

/data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150511_t2240157_e224 1381_b18324//JRR-

IceConcentration_v1r0_npp_s201505112240157_e201505112241381_c201507171818100.nc /data/data092/hxie/dlv/npp_dap/nde_apr2015/JRR_DAP_apr2015/working_d20150511_t2240157_e224 1381_b18324//JRR-IceAge_v1r0_npp_s201505112240157_e201505112241381_c201507171818110.nc

A unit log file is saved for each script invoked during the process

» A section of JRR_PRODUCT_CRYOSPHERE_ICE.pl.log is given

JRR_PRODUCT_CRYOSPHERE_ICE.pl is now starting at: 20150717-18:17:59

Running jrr_product_sdr4frmwk.pl - log: jrr_product_sdr4frmwk.pl.log real 0m0.652s user 0m0.232s

```
sys 0m0.119s
```

```
running jrr_product_sdr4frmwk.pl: OK
```



Cryosphere Ice Product Generation Unit Input/Output Data

File	Input/ Output	No. of Files	Source	Format
Gap-filled VIIRS SDR M band files for channels 03, 04, 05, 07, 10, 15, 16	Input	7	JPSS RR PS	NetCDF4
VIIRS M band geolocation file	Input	1	JPSS RR PS	NetCDF4
RR Cloud Mask product	Input	1	NDE	NetCDF4
RR Cloud Height product file	Input	1	NDE	NetCDF4
Static Framework ancillary data	Input	-	DAP	NetCDF4
Static Algorithm ancillary data	Input	-	DAP	NetCDF4
Unit PCF	Input	1	NDE	ASCII
JPSS RR VIIRS Cryosphere Ice Concentration /Cover Product File	Output	1	JPSS RR PS	NetCDF4
JPSS RR VIIRS Ice Age/Thickness Product File	Output	1	JPSS RR PS	NetCDF4
Unit PSF	Output	1	JPSS RR PS	ASCII
Unit Log file	Output	1	JPSS RR PS	ASCII



JPSS RR PS Software Architecture

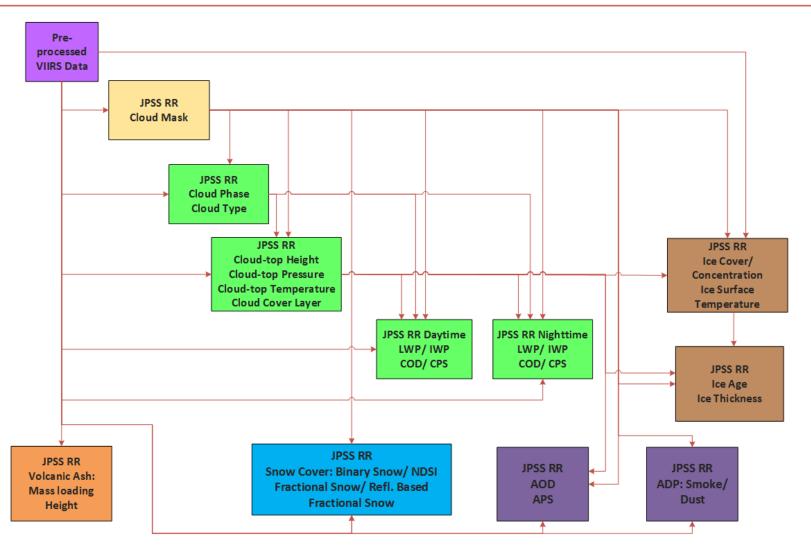
Outline

- JPSS RR PS System Overview
- JPSS RR PS Detailed Design
- JPSS RR PS Algorithm Software
- AIT Framework
- Transition to Operations



JPSS RR PS Algorithm Product Precedence

JPSS RR Product Precedence



Sub-system, Algorithm & Product Categorization

- Cloud Mask Product Generation Unit
 - » Cloud Mask Algorithm Cloud Mask Product
- Clouds Product Generation Unit
 - » Cloud Phase Algorithm Cloud Phase/Type Products
 - » Cloud Height Algorithm Cloud-top Height/Temperature/Pressure Products
 - » DCOMP Algorithm Daytime LWP, IWP, COD, and CPS Products
 - » NCOMP Algorithm Nighttime LWP, IWP, COD, and CPS Products
- Aerosol AOD/ADP Product Generation Unit
 - » AOD Algorithm AOD, APSP Products
 - » ADP Algorithm Smoke/Dust Aerosol Detection Products
- Aerosol VolAsh Product Generation Unit
 - » Volcanic Ash Algorithm Volcanic Ash Mass Loading and Height Products

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- Cryosphere Ice Product Generation Unit
 - » Ice Concentration Algorithm Ice Concentration/Cover, IST Products
 - » Ice Age Algorithm Ice Age/Thickness Products
- Cryosphere Snow Product Generation Unit
 - » Snow Cover Algorithm Binary/Fractional Snow Cover Product s



JPSS RR PS Algorithm Software

Cloud Mask Product Generation Unit

- » Cloud Mask Algorithm
 - Cloud Mask Product





Cloud Mask Algorithm Software Description

• Design Languages – Fortran 90

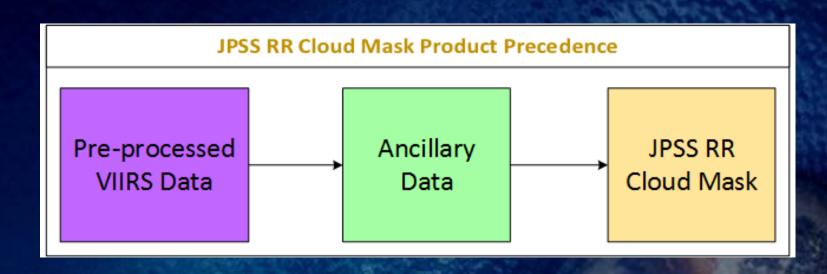
SLOC

- » Executable code 3356
- » With Comments 4042





Cloud Mask Algorithm Product Precedence







Cloud Mask Algorithm Output

- Algorithm employs VIIRS Mbands M03, M05, M07, M09, M10, M11, M12, M14, M15, M16 and Ibands I01, I04, I05
- Cloud Mask is derived whenever detectable clouds are present.

Name	Туре	Description	Dimension
cloud_mask	Product	Cloud Mask product: 4 level cloud mask 0-cloudy; 1-prob. cloudy; 2-prob. clear; 3-clear	grid (xsize, xsize)
cloud_probability	Output	Cloud probability floating point value 0 -1	grid (xsize, ysize)
clear_sky_mask	Product	Binary clear sky mask product: 2 level clear sky mask 0- clear; 1-cloudy	grid (xsize, ysize)
cloud_mask_packed	Output	Packed cloud mask product: 8 byte array containing the individual test & flag output bits.	grid (xsize, ysize, PkedCnst)
Smoke_Mask	Output	Smoke contamination mask	grid (xsize, xsize)
Fire_Mask	Output	Cloud probability floating point value 0 -1	grid (xsize, ysize)
Dust_Mask	Output	Binary clear sky mask product: 2 level clear sky mask 0- clear; 1-cloudy	grid (xsize, ysize)
CloudMaskQualFlag	Output	Cloud mask Quality control flags	grid (xsize, ysize)



Cloud Mask Algorithm Output Product Details

4-level cloud mask output values

Value	Description
Clear	Pixels that passed no test for cloud and failed a test for spatial heterogeneity
Probably Clear	Pixels that passed no test for cloud but passed tests for spatial heterogeneity
Probably Cloudy	Pixels that passed a test for cloud and passed a test for cloud edges
Cloudy	Pixels that passed a test for cloud and failed a test for cloud edges

Binary cloud mask output values

Value	Description	
Clear	Pixel is clear	
Cloudy	Pixel is cloudy	

4-level cloud mask test output

values

Value	Description		
Clear	Test was failed strongly		
Probably Clear	Test was failed weakly		
Probably Cloudy	Test was passed weakly		
Cloudy	Test was passed strongly.		



Cloud Mask Algorithm Output Product Quality Flags

Individual test and flag output bits

		marriadar toot ana			
Ancillary Data Flags			Cloud Tests		
Byte	Bit	Description	Byte	Bit	Description
1	1	Cloud mask attempted flag	3	5-6	TGCT – Thermal Gross Contrast Test
1	2	daytime visible tests attempted	3	7-8	RTCT – Relative Thermal Contrast Test
1	3	Daytime spatial uniformity tests attempted	4	1-2	TUT – Thermal (11 um BT) Uniformity Test
1	4	4 um daytime tests attempted	4	3-4	ETROP – Emissivity at Tropopause Test
1	5	4 um nighttime tests attempted	4	5-6	FMFT – (11um - 12um) Test
1	6	Solar contamination	4	7-8	(11um - 6.7um) Test
1	7	Coast / no coast	5	1-2	(11um - 6.7um) Covariance Test
1	8	Mountain/ No Mountain Flag	5	3-4	(11um - 8.5um) Covariance Test
2	1	Forward scattering	5	5-6	EMISS4 – 4um emissivity test
2	2	Cold scene 4 um	5	7-8	EMISS4 Day – 4um emissivity test
2	3	Cold scene btd	6	1-2	EMISS4 Night – 4um emissivity test
2	4	Glint flag	6	3-4	(11um – 4um) night test
2	5	Smoke contaminated flag (not currently filled)	6	5-6	RGCT – reflectance Gross Contrast Test
2	6	Dust contaminated flag (not currently filled)	6	7-8	RUT – Reflectance (0.63 um) uniformity Test
2	7	Shadow contaminated flag (not currently filled)	7	1-2	RVCT – Relative Visible Contrast Test
2	8	Fire contaminated flag (not currently filled)	7	3-4	RRCT – Reflectance Ratio Test
3	1-3	Surface type used for thresholds	7	5-6	Near-IR Cirrus Test (CIRREF)
3	4	Blank	7	7-8	Near IR Snow Test (NIRREF)



Cloud Mask Algorithm Output Product Quality Flags

Individual test and flag output bits

Ancillary Data Flags			Cloud Tests			
			Cloud Tests			
Byte	Bit	Description	Byte	Bit	Description	
	0	Cloud Mask Attempted Flag		0-1	BTD11_12 – 11 and 12 mm Split-Window Test	
	1	Daytime Visible Tests Attempted		2-3	BTD11_6.7 – 11 and 6.7 mm Thermal Contrast	
	2	Daytime Spatial Uniformity Tests Attempted	3	2-3	Test	
0	3	4 mm Daytime Tests Attempted	3	4-5	BTD11_6.7 – 11 and 6.7 mm Thermal Covariance Test	
·	4	4 mm Nighttime Tests Attempted			BTD11_8.5 – 11 and 8.5 mm Thermal Contrast	
	5	Solar Contamination Flag		6-7	Test	
	6	Coast / No Coast Flag		0-1	EMISS4 – 4 mm Emissivity Test	
	7	Mountain / No Mountain Flag	4	2-3	EMISS4 _Day – Daytime 4 mm Emissivity Test	
	0	Smoke Contamination Flag		4-5	EMISS4 _Night – Nighttime 4 mm Emissivity Test	
	1	Dust Contamination Flag		6-7	BTD4_11 - Night 4 and 11 mm Thermal Contrast	
	2	Shadow Contamination Flag	2		Test	
1	3	Fire Contamination Flag		0-1	Ref0.63 – 0.63 mm Reflectance Test	
	4-6	Surface Type Used for Thresholds (Deep Ocean, Shallow Water, Land, Snow, Arctic,	5	2-3	Ref0.63STD – 0.63 mm Reflectance Uniformity Test	
	_	Antarctic + Greenland, Desert		4-5	RVCT – Relative Visible Contrast Test	
	7	Spare		6-7	Ref_Ratio – Reflectance Ratio Test	
	0-1	BT11 – 11 μm Thermal Test		0-1	NDSI – NDSI Test	
2	2-3	RTCT – Relative Thermal Contrast Test	6	• •		
2	4-5	BT11STD – 11mm Thermal Uniformity Test	6	2-3	Ref1.38 – 1.38 mm Reflectance Test	
	6-7	ETROP – Emissivity at Tropopause Test	20	4-7	SPARE	



Cloud Mask Algorithm Product Quality Control Flags

Cloud Mask Quality Control Codes QC Flag Definition 0 Good Invalid pixel due to space view 1 2 Invalid pixel due to being outside of sensor zenith range Invalid earth pixel due to bad data (bad or missing 11mm BT or bad/missing clear sky 3 11 mm BT) 4 Reduced quality Cloud mask (bad 3.9mm pixel) 5 Reduced quality 0.64mm tests 6 Reduced quality due to other bad channels (excluding 0.64, 3.9, or 11 mm)



Cloud Mask Algorithm Product Monitoring Metadata

	Cloud Mask Algorithm Product Monitoring Metadata
Variable Name	Definition
TerminatorPixPercent	Percent of terminator pixels - Number_of_pixels_with_solar_zenith_angle_between_87_and_93_degrees/ Total_number_of_attempted_retrievals
Cloudy	Percent of Pixels that passed a test for cloud and failed a test for cloud edge
ProbCloudy	Percent of Pixels that passed a test for cloud and passed a test for cloud edge
ProbClear	Percent of Pixels that passed no test for cloud but passed tests for spatial heterogenity
Clear	Percent of Pixels that passed no test for cloud and failed a test for spatial heterogenity
MinClrSkyOBS_RTM	Minimum observation - RTM calculation Brightness Temperature for clear-sky Good pixels for IR channels
MaxClrSkyOBS_RTM	Maximum observation - RTM calculation Brightness Temperature for clear-sky Good pixels for IR channels
MeanClrSkyOBS_RTM	Mean observation - RTM calculation Brightness Temperature for clear-sky Good pixels for IR channels
StdDevClrSkyOBS_RTM	Standard deviation of observation - RTM calculation Brightness Temperature for clear-sky Good pixels for IR channels
MinAllSkyOBS_RTM	Minimum observation - RTM calculation Brightness Temperature for all-sky Good pixels for IR channels
MaxAllSkyOBS_RTM	Maximum observation - RTM calculation Brightness Temperature for all-sky Good pixels for IR channels
MeanAllSkyOBS_RTM	Mean observation - RTM calculation Brightness Temperature for all-sky Good pixels for IR channels
StdDevAllSkyOBS_RTM	Standard deviation of observation - RTM calculation Brightness Temperature for all-sky Good pixels for IR channels



Cloud Mask Algorithm Test Environment & Timing Info.

- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~130 seconds to generate RR Cloud Mask product output on a single granule (using combination of M & I bands) at 750 m resolution, with a segment size of 120 in framework



Cloud Mask Algorithm Timing Information

Unit	Time (seconds)
VIIRS_SDR_MULTIRES	49.99
LAND_MASK_NASA_1KM	0.17
OISST_DAILY_QTRDEG	1.91
NWP_GFS	22.17
SFC_ELEV_GLOBE_1KM	0.53
SFC_EMISS_SEEBOR	0.4
CRTM	33.42
COAST_MASK_NASA_1KM	0.1
SFC_TYPE_AVHRR_1KM	0.13
DESERT_MASK_CALCLTED	0.04
SNOW_MASK_NWP	0.12
GOESR_ABI_CHN7_EMISS	0.15
SFC_ALBEDO	0.41
NPP_BAYES_CLOUD_MASK	16.89
Total	126.43

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Cloud Mask Algorithm Validation Datasets

Apr 10-25, 2014
Jul 10-25, 2014
Oct 10-25, 2014
Jan 01-31, 2015



JPSS RR PS Algorithm Software

Clouds Product Generation Unit

- » Cloud Phase Algorithm
 - Cloud Phase Product
 - Cloud Type Product
- » Cloud Height Algorithm
 - Cloud-top Height
 - Cloud-top Temperature
 - Cloud-top Pressure
- » DCOMP Algorithm
 - Daytime LWP/ IWP/ COD/ CPS Products
- » NCOMP Algorithm
 - Nighttime LWP/ IWP/ COD/ CPS Products



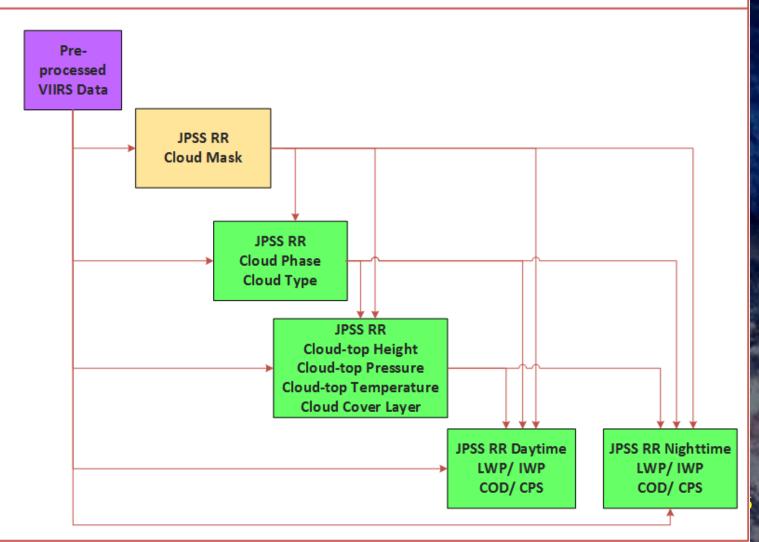
Clouds Algorithm Software Description

- Design Language Fortran 90
- SLOC
 - » Executable code
 - Cloud Phase 3464
 - Cloud Height 5077
 - DCOMP 4734
 - NCOMP 4685
 - » With Comments
 - Cloud Phase 4645
 - Cloud Height 6072
 - DCOMP 5848
 NCOMP 5394



Clouds Algorithm Product Precedence

JPSS RR Clouds Product Precedence





Cloud Phase Algorithm Output

Cloud Phase Algorithm use VIIRS Mbands M14, M15, and M16
Products: Cloud Phase, Cloud Type

Name	Туре	Description	Dimension
CloudPhase	Product	Cloud Phase Category Output	grid (xsize, xsize)
CloudType	Product	Cloud Type Category Output	grid (xsize, ysize)
CloudTypePacked	Output	Cloud Type Diagnostic Flag	grid (xsize, ysize)
CloudPhaseFlag	Output	Overall Cloud Phase and Type Quality Flag	grid (xsize, ysize, 1)



Cloud Phase Algorithm Product Details

Cloud Phase Category	Description	Value
Clear	Clear cloud mask output	0
Liquid Water	Cloud top temperature > 273 K	1
Supercooled Water	Cloud top temperature < 273 K	2
Mixed Phase	Mainly a water signal, but may contain some ice	3
Ice	All ice phased clouds (cloud top)	4
Cloud Type Category	Description	Value

Cloud Type Category	Description	Value
Clear	Clear cloud mask output	0
Spare	Spare category	1
Liquid Water	Liquid water with cloud top temperature > 273 K	2
Supercooled Water	Liquid water with cloud top temperature < 273 K	3
Mixed Phase	Mainly a water signal, but may contain some ice	4
Thick Ice	Ice cloud that is opaque in the infrared	5
Thin Ice	An approximate optical depth threshold is used to distinguish between thin and thick ice clouds	6
Multilayered Ice	Mainly ice cloud overlapping a lower, distinct, cloud layer	7



Cloud Phase Algorithm Quality Flags

Bit(s)	QF Description	Bit Interpretation
1	Overall cloud phase/type product quality flag - the overall	0 = high quality
	quality will be set to "low quality" if any of the more specific	1 = low quality
	quality flags listed below are set to "low quality"	
2	L1b quality flag – this will be set to "low quality" if any of	0 = high quality spectral data
	the spectral data used in the algorithm is of low quality, based	1 = low quality spectral data
	on L1b calibration flags	
3	Beta quality flag – this will be set to "low quality" if β -	0 = high quality beta calculation
	stropo(12/11μm), β sopaque(12/11μm), β stropo(8.5/11μm), or β-	1 = low quality beta calculation
	sopaque $(8.5/11 \mu m)$ fall outside of the $0.1 - 10.0$ range	
4	Ice cloud quality flag – this will be set to "low quality" if the	0 = ice cloud determination based on
	cloud phase was determined to be ice and the $\varepsilon_{stropo}(11 \mu m) <$	strong radiative signal
	0.05	1 = ice cloud determination based on
		weak radiative signal (low quality)
5	Surface emissivity quality flag – this will be set to "low	0 = surface emissivity does NOT
	quality" if the result of the Low Surface Emissivity (LSE)	significantly impact product quality
	Test is TRUE and the result of the Overall Opaque Cloud	1 = surface emissivity significantly
	(OOC) Test is FALSE	impacts product quality (low quality)
6	Satellite zenith angle quality flag – this will be set to "low	0 = satellite zenith angle does NOT
	quality" if the cosine of the satellite zenith angle is less than	significantly impact product quality
	0.15 (~82 degrees)	1 = satellite zenith angle significantly
		impacts product quality (low quality)



Cloud Phase Algorithm Product Monitoring Metadata

Cloud Phase Algorithm Product Monitoring Metadata			
Variable Name	Definition		
TerminatorPixPercent	Percent of terminator pixels - Number_of_pixels_with_solar_zenith_angle_between_87_and_93_degrees/ Total_number_of_attempted_retrievals		
LiquidWaterPct	Percent of pixels with Warm Liquid Water category (excluding Clear)		
SuperCooledLiquidWaterPct	Percent of pixels with SuperCooled Liquid Water category (excluding Clear)		
MixedPhasePct	Percent of pixels with Mixed Phase category (excluding Clear)		
IcePct	Percent of pixels with All ice topped clouds (excluding Clear):		
NumberofLowQuality	Overall Cloud Phase/Type quality flags: Low Quality Cloud Phase/Type retrievals		
NumberofHighQuality	Overall Cloud Phase/Type quality flags: High Quality Cloud Phase/Type retrievals		



Cloud Height Algorithm Output

• Cloud Height Algorithm use VIIRS Mbands M14, M15, and M16

Name	Туре	Description	Dimension
CldTopTemp	Product	Cloud top temperature in Kelvin	grid (xsize, ysize)
CldTopPres	Product	Cloud top pressure in hPa	grid (xsize, ysize)
CldTopHght	Product	Cloud top height in meters	grid (xsize, ysize)
CloudLayer	output	Classifies low cloud, mid cloud and high cloud	grid (xsize, ysize)
InverFlag	output	Inversion Flag	grid (xsize, ysize)
Shadow_Mask	output	Cloud shadow mask	grid (xsize, ysize)
CldHgtFlag	output	Cloud Height Processing Flag	grid (xsize, ysize, 3)
CldPackedFlag	output	Cloud Height Diagnostic Flag	grid (xsize, ysize, 1)
CloudHgtQF	output	Cloud Height Quality Flag	grid (xsize, ysize)
TcError	output	Cloud top temperature uncertainty	grid (xsize, ysize)
PcError	output	Cloud top pressure uncertainty product	grid (xsize,ysize)
ZcError	output	Cloud top height uncertainty product	grid (xsize,ysize)
Cost	output	Final cost function value from optimal estimation	grid (xsize, ysize)



Cloud Height Algorithm Product Quality Flags

Cloud Height Quality Control Codes QC_Flag Definition Good 0 Invalid pixel due to space view 1 2 Invalid pixel due to being outside of sensor zenith range Invalid earth pixel due to bad data (bad or missing 11mm BT or bad/missing clear sky 11 3 mm BT) Invalid due to cloud mask being clear or probably clear 4 Invalid due to missing cloud type 5 Failed retrieval 6



Cloud Height Algorithm Product Monitoring Metadata

Cloud Height Algorithm Product Monitoring Metadata			
Variable Name	Definition		
TerminatorPixPercent	Percent of terminator pixels - Number_of_pixels_with_solar_zenith_angle_between_87_and_93_deg/ Total_number_of_attempted_retrievals		
ValidRetrPct	Valid, good quality converge retrieval		
InvalidRetrSpaceViewPct	Percentage of invalid pixel due to space view		
InvalidRetrSatZenPct	Percent of invalid pixel due to being outside of sensor zenith range		
InvalidRetrBadDataPct	Percent of invalid earth pixel due to bad or missing 11 um BT or bad/missing clear sky 11 um BT		
InvalidRetrCldMaskPct	Percentage of invalid pixels due to cloud mask being clear or probably clear		
InvalidRetrMissCldTypePct	Percentage of invalid pixels due to missing cloud type		
InvalidRetrFailedPct	Percentage of failed retrieval		
MinCldTopTemp	Minimum Cloud Top Temperature for QA = 0 and $180 \le T \le 340$ pixels (K)		
MaxCldTopTemp	Maximum Cloud Top Temperature for QA = 0 and $180 \le T \le 340$ pixels (K)		
MeanCldTopTemp	Mean Cloud Top Temperature for QA = 0 and $180 \le T \le 340$ pixels (K)		
StdDevCldTopTemp	Standard Deviation of Cloud Top Temperature for QA = 0 and $180 \le T \le 340$ pixels (K)		
MinCldTopPres	Minimum Cloud Top Pressure for QA = 0 and $0 \le P \le 1100$ pixels (hPa)		
MaxCldTopPres	Maximum Cloud Top Pressure for $QA = 0$ and $0 \le P \le 1100$ pixels (hPa)		
MeanCldTopPres	Mean Cloud Top Pressure for $QA = 0$ and $0 \le P \le 1100$ pixels (hPa)		
StdDevCldTopPres	Standard deviation of Cloud Top Pressure for $QA = 0$ and $0 \le P \le 1100$ pixels (hPa)		
MinCldTopHeight	Minimum Cloud Top Height (H) for $QA = 0$ and $-300 \le H \le 20000$ pixels (m)		
MaxCldTopHeight	Maximum Cloud Top Height (H) for $QA = 0$ and $-300 \le H \le 20000$ pixels (m)		
MeanCldTopHeight	Mean Cloud Top Height (H) for $QA = 0$ and $-300 \le H \le 20000$ pixels (m)		
StdDevCldTopHeight	Standard Deviation of Cloud Top Height (H) for $QA = 0$ and $-300 \le H \le 20000$ pixels (m)		



DCOMP Algorithm Output Product

- DCOMP Algorithm use VIIRS Mbands M05, M07, M10, M11, and M12
- Daytime COMP Products:

Name	Туре	Description	Dimension
Cloud Optical Thickness value	product	Retrieved cloud visible optical depth (dimensionless) for each cloudy pixel	grid (xsize, ysize)
Cloud Particle Size value	product	Retrieved cloud effective particle size (microns) value for each cloudy pixel	grid (xsize, ysize)
Cloud Liquid Water Path value	product	For Water Clouds. Retrieved LWP value for each water pixel (g/m^2)	grid (xsize, ysize)
Cloud Ice Water Path value	product	For Ice Clouds. Retrieved IWP value for each ice pixel (g/m^2)	grid (xsize, ysize)
Quality_Flag	output	quality flag	grid (xsize, ysize)



DCOMP Algorithm Output Product Quality Flags

*DCOMP Quality Control Codes			
QC_Flag	Definition		
0	Valid, Quality may be degraded due to snow or sea-ice		
1	Valid, Quality may be degraded due to twilight conditions		
2	Valid, but degraded quality due to twilight conditions (solar zenith between 65 and 82 degree)		
3	Invalid due to cloud-free condition		
4	Invalid pixel due to being outside of observation range		
5	Invalid pixel due to missing input data		
6	Invalid pixel, DCOMP attempted but failed retrieval		



NCOMP Algorithm Output Product

- NCOMP Algorithm use VIIRS Mbands M12, M14, M15, and M16
- Nighttime COMP Products:

Name	Туре	Description	Dimension
Cloud Optical Thickness value	product	Retrieved cloud visible optical depth (dimensionless) for each cloudy pixel	grid (xsize, ysize)
Cloud Particle Size value	product	Retrieved cloud effective particle size (microns) value for each cloudy pixel	grid (xsize, ysize)
Cloud Liquid Water Path value	product	For Water Clouds. Retrieved LWP value for each water pixel (g/m^2)	grid (xsize, ysize)
Cloud Ice Water Path value	product	For Ice Clouds. Retrieved IWP value for each ice pixel (g/m^2)	grid (xsize, ysize)
Quality_Flag	output	quality flag	grid (xsize, ysize)
Processing_Flag	output	processing flag	grid (xsize, ysize, 14)



NCOMP Algorithm Output Product Quality Flags

NCOMP Cont	NCOMP Control Codes			
Bit	Quality Flag Name	Cause and effect		
Angle restricti	on flags			
1	QC_CYCLE_VZA	Viewing Zenith Angle >= 72.0		
2	QC_CYCLE	Solar Zenith Angle < 82.0		
Ancillary Data	Flags			
3	QC_CYCLE_NOCLOUD	Cloud Type indicates it is not a cloud		
4	QC_CYCLE_CLOUDTYPE	Cloud Type has an unknown value		
5	QC_CYCLE_TCLOUD	Cloud Temperature is < 0.0		
No Retrieval I	Flags			
6	QC_MINERR_WATER_0	No retrieval: Minimum error model for water = 0		
7	QC_MINERR_ICE_0	No retrieval: Minimum error model for ice = 0		
Valid Retrieva	n Flags			
8	QC_TWILIGHT_	82.0 <= Solar Zenith Angle < 90.0		
9	QC_CTWATER_NCOMPICE	Cloud Type = water, NCOMP preferred phase = ice		
10	QC_CTICE_NCOMPWATER	Cloud Type = ice, NCOMP preferred phase = water		
11	QC_CTMIX_NCOMPWATER	Cloud Type = mixed, NCOMP preferred phase = water		
12	QC_CTMIX_NCOMPICE	Cloud Type = mixed, NCOMP preferred phase = ice		
13	QCNCOMPWATER	Cloud Type = supercooled, NCOMP preferred phase = water		
14	QCNCOMPICE	Cloud Type = supercooled, NCOMP preferred phase = ice		



Clouds Algorithm Test Environment/ Timing Info.

- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~100 s (daytime) and ~260 s (nighttime), to generate all RR Clouds Algorithm product outputs on a single granule at 750 m resolution, with a segment size of 120 in framework



NCOMP/*DCOMP Algorithms Product Monitoring Metadata

COMP Algorithm Product Monitoring Metadata

Variable Name	Definition	
TerminatorPixPercent	Percent of terminator pixels - Number_of_pixels_with_solar_zenith_angle_between_87_and_93_deg/	
	lotal_number_of_attempted_retrievals	
ValidRetrPct	Valid, good quality converge retrieval in percentage	
ValidDegradedSnowPct	Not valid, quality may be degraded due to snow or sea ice surface in percentage	
ValidDegradedTwilightPct	Not valid, degraded quality due to twilight conditions (solar zenith between 65 and 82 degree) in %	
InvalidCloudFreePct	Invalid due to cloud-free condition in %	
InvlidOutsideRangePct	Invalid pixel due to being outside of observation range in %	
InvalidMissPct	Invalid pixel due to missing input data in %	
InvalidFaliedPct	Invalid pixel, DCOMP/NCOMP attempted but failed retrieval in %	
NitCat00Pct	Percent of Nighttime retrievals with Space Mask	
NitCat01Pct	Percent of Nighttime retrievals with Viewing Zenith Angle > 65.0	
NitCat02Pct	Percent of Nighttime retrievals with Solar Zenith Angle < 82.0	
NitCat03Pct	Percent of Nighttime retrievals with Cloud Type indicates it is not a cloud	
NitCat04Pct	Percent of Nighttime retrievals with Cloud Type has an unknown value	
NitCat05Pct	Percent of Nighttime retrievals with Cloud Temperature is < 0.0	
NitCat06Pct	Percent of Nighttime retrievals with No retrieval: Minimum error model for water = 0	
NitCat07Pct	Percent of Nighttime retrievals with No retrieval: Minimum error model for ice = 0	
MinOpticalDepth	Minimum COD for 0 ≤ COD≤ 100 daytime/nighttime pixels . Valid range: [0.0, 100.0]	
MaxOpticalDepth	Maximum COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
MeanOpticalDepth	Mean COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
StdDevOpticalDepth	Standard Deviation of COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
MinParticleSize	Minimum CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
MaxParticleSize	Maximum CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
MeanParticleSize	Mean CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
StdDevParticleSize	Standard Deviation of CPS for 0 ≤ CPS ≤ 100 davtime/nighttime pixels : unit: um: valid range: [0.0, 100.0]	



NCOMP/*DCOMP Algorithms Product Monitoring Metadata

COMP Algorithm Product Monitoring Metadata

Variable Name	Definition	
TerminatorPixPercent	Percent of terminator pixels - Number_of_pixels_with_solar_zenith_angle_between_87_and_93_deg/ Total_number_of_attempted_retrievals	
ValidRetrPct	Valid, good quality converge retrieval in percentage	
ValidDegradedSnowPct	Not valid, quality may be degraded due to snow or sea ice surface in percentage	
ValidDegradedTwilightPct	Not valid, degraded quality due to twilight conditions (solar zenith between 65 and 82 degree) in %	
InvalidCloudFreePct	Invalid due to cloud-free condition in %	
InvlidOutsideRangePct	Invalid pixel due to being outside of observation range in %	
InvalidMissPct	Invalid pixel due to missing input data in %	
InvalidFaliedPct	Invalid pixel, DCOMP/NCOMP attempted but failed retrieval in %	
NitCat00Pct	Percent of retrievals with Space Mask	
NitCat01Pct	Percent of retrievals with Viewing Zenith Angle > 65.0	
NitCat02Pct	Percent of retrievals with Solar Zenith Angle < 82.0	
NitCat03Pct	Percent of retrievals with Cloud Type indicates it is not a cloud	
NitCat04Pct	Percent of retrievals with Cloud Type has an unknown value	
NitCat05Pct	Percent of retrievals with Cloud Temperature is < 0.0	
NitCat06Pct	Percent of retrievals with No retrieval: Minimum error model for water = 0	
NitCat07Pct	Percent of retrievals with No retrieval: Minimum error model for ice = 0	
MinOpticalDepth	Minimum COD for 0 ≤ COD≤ 100 daytime/nighttime pixels . Valid range: [0.0, 100.0]	
MaxOpticalDepth	Maximum COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
MeanOpticalDepth	Mean COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
StdDevOpticalDepth	Standard Deviation of COD for 0 ≤ COD≤ 100 daytime/nighttime pixels. Valid range: [0.0, 100.0]	
MinParticleSize	Minimum CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
MaxParticleSize	Maximum CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
MeanParticleSize	Mean CPS for $0 \le CPS \le 100$ daytime/nighttime pixels ; unit: μ m; valid range: [0.0, 100.0]	
StdDevParticleSize	Standard Deviation of CPS for $0 \le CPS \le 100$ davtime/nighttime pixels : unit: um: valid range: [0.0, 100.0]	



Clouds Algorithm Timing Information

Unit	Time (s)	Unit	Time (s)
VIIRS_SDR_MULTIRES	8.72	VIIRS_SDR_MULTIRES	9.54
LAND_MASK_NASA_1KM	0.09	LAND_MASK_NASA_1KM	0.15
OISST_DAILY_QTRDEG	1.16	OISST_DAILY_QTRDEG	1.36
NWP_GFS	21.37	NWP_GFS	19.31
SFC_ELEV_GLOBE_1KM	0.34	SFC_ELEV_GLOBE_1KM	0.46
SFC_EMISS_SEEBOR	0.3	SFC_EMISS_SEEBOR	0.33
CRTM	31.57	CRTM	22.14
COAST_MASK_NASA_1KM	0.09	COAST_MASK_NASA_1KM	0.14
SFC_TYPE_AVHRR_1KM	0.08	SFC_TYPE_AVHRR_1KM	0.16
DESERT_MASK_CALCLTED	0	DESERT_MASK_CALCLTED	0
SNOW_MASK_NWP	0.11	SNOW_MASK_NWP	0.15
GOESR_ABI_CHN7_EMISS	0.12	GOESR_ABI_CHN7_EMISS	0.17
SFC_ALBEDO	0.21	SFC_ALBEDO	0.34
NPP_BAYES_CLOUD_MASK	1.47	NPP_BAYES_CLOUD_MASK	2.22
NPP_VIIRS_CLD_PHASE	6.63	NPP_VIIRS_CLD_PHASE	10.9
NPP_VIIRS_CLD_HEIGHT	14.76	NPP_VIIRS_CLD_HEIGHT	35.85
AWG_CLOUD_MICRO_DAY	11.31	NPP_VIIRS_CLD_NCOMP	153.03
Total	98.33	Total	256.25



Clouds Algorithm Validation Datasets

Apr 10-25, 2014
Jul 10-25, 2014
Oct 10-25, 2014
Jan 01-31, 2015



JPSS RR PS Algorithm Software

Aerosol VolAsh Product Generation Unit

- » Volcanic Ash Algorithm
 - Volcanic Ash Mass Loading Product
 - Volcanic Ash Height Product



Volcanic Ash Algorithm Software Description

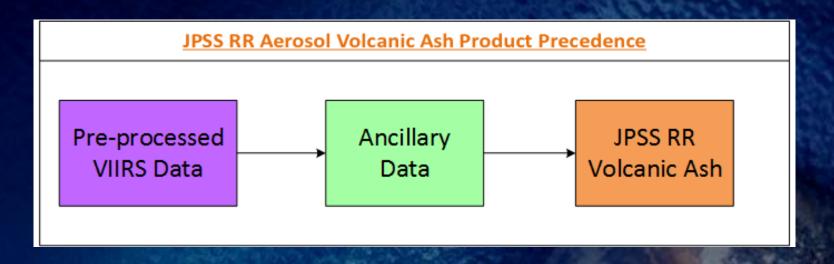
• Design Languages – Fortran 90

SLOC

- » Executable code 6404
- » With Comments 8664



Volcanic Ash Algorithm Product Precedence





Volcanic Ash Algorithm Output

- Algorithm employs VIIRS Mbands M14, M15, and M16
- Clear; for AOT greater than 0.15
- Products: Volcanic Ash Mass Detection and Height

Name	Туре	Description	Dimension
AshTopHeight	product	Ash top height (m)	grid (xsize, ysize)
AshMassLoading	product	Ash mass loading (ton/km2 or g/m2)	grid (xsize, ysize)
AshConfidence	output	Ash Confidence for Single layered Ash	grid (xsize, ysize)
AshConfidenceMulti	output	Ash Confidence for Multi layered Ash	grid (xsize, ysize)
AshDetectionQPI	output	Ash Detection Product Quality Information	grid (xsize, ysize, 6)
AshDetectionQF	output	Ash Detection Quality Flag	grid (xsize, ysize, 2)
AshTopTemp	output	Ash Top Temperature (K)	grid (xsize, ysize)
AshTopPress	output	Ash Top Pressure (hPa)	grid (xsize, ysize)
AshTopHeight	output	Ash Top Height (m)	grid (xsize, ysize)

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Volcanic Ash Algorithm Output (cont.)

Name	Туре	Description	Dimension
AshEmiss	output	Ash Emissivity at 11um	grid (xsize, ysize)
AshEffRad	output	Ash Effective Particle Size (microns)	grid (xsize, ysize)
AshOD_VIS	output	Ash visible optical depth	grid (xsize, ysize)
AshOD_IR	output	Ash infrared optical depth	grid (xsize, ysize)
AshBeta	output	Beta value for 11 and 12 microns	grid (xsize, ysize)
AshTempErr	output	Estimated error in ash temperature (K)	grid (xsize, ysize)
AshPressErr	output	Estimated error in ash pressure (hPa)	grid (xsize, ysize)
AshHgtErr	output	Estimated error in Ash Height (m)	grid (xsize, ysize)
Ash_QF	output	Ash Retrieval Quality Flag	grid (xsize, ysize, 2)
Ash_PQI	output	Ash Retrieval Product Quality Information	grid (xsize, ysize, 1)



Volcanic Ash Algorithm Output Product Quality Flags

Volcanic Ash Retrieval Quality Control Codes					
Byte	Bit	Name	Values		
1	1-2	Retrieval Status	0 - Successful 1 - Failed 2 - Not Attempted		
1	3-4 T _{cld} QF 0 – High Quality 1 – Medium Quality 2 – Low Quality				
1	5-6	ε _{cld} QF	0 – High Quality 1 – Medium Quality 2 – Low Quality		
1	7-8	β(12/11μm) QF	0 – High Quality 1 – Medium Quality 2 – Low Quality		
2	1-4	Ash Particle Size	$\begin{array}{ll} 0 - < 2 \ \mu m \\ 1 - \ge 2 - < 3 \ \mu m \\ 2 - \ge 3 - < 4 \ \mu m \\ 3 - \ge 4 - < 5 \ \mu m \\ 4 - \ge 5 - < 6 \ \mu m \\ 5 - \ge 6 - < 7 \ \mu m \\ 6 - \ge 7 - < 8 \ \mu m \\ 7 - \ge 8 - < 9 \ \mu m \\ 8 - \ge 9 - < 10 \ \mu m \\ 9 - \ge 10 \ \mu m \\ 10 - \text{ invalid} \end{array}$		



Volcanic Ash Algorithm Product Monitoring Metadata

Volcanic Ash Algorithm Product Monitoring Metadata

Variable Name	Definition
TotMassVolAsh	Total Ash Mass Loading for Overall High Quality pixels (unit: tons/km2)
MassLoadingMax	Maximum Ash Mass Loading for Overall High Quality pixels (unit: tons/km2)
MassLoadingMin	Minimum Ash Mass Loading for Overall High Quality pixels (unit: tons/km2)
MassLoadingMean	Mean Ash Mass Loading for Overall High Quality pixels (unit: tons/km2)
MassLoadingStdDev	Standard Deviation of Ash Mass Loading for Overall High Quality pixels (unit: tons/km2)
AshCldHgtMax	Maximum Ash Cloud Height for Overall High Quality pixels (unit: Meter)
AshCldHgtMin	Minimum Ash Cloud Height for Overall High Quality pixels (unit: Meter)
AshCldHgtMean	Mean Ash Cloud Height for Overall High Quality pixels (unit: Meter)
AshCldHgtStdDev	Standard Deviation of Ash Cloud Height for Overall High Quality pixels (unit: Meter)
DetQF_OverallPerc	Percent of retrievals with ash detection QA bits set to High Quality
RetQF_OverallPerc	Percent of retrievals with ash retrieval QA bits set to Successful/High Quality



Volcanic Ash Algorithm Test Environment & Timing Info.

- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~92 seconds to generate RR Volcanic Ash product output on a single granule at 750 m resolution, with a segment size of 120 in framework



Volcanic Ash Algorithm Timing Information

Unit	Time (seconds)
VIIRS_SDR_MULTIRES	11.06
LAND_MASK_NASA_1KM	0.12
OISST_DAILY_QTRDEG	1.47
NWP_GFS	21.43
SFC_ELEV_GLOBE_1KM	0.58
SFC_EMISS_SEEBOR	0.45
CRTM	33.18
COAST_MASK_NASA_1KM	0.11
SNOW_MASK_NWP	0.11
SFC_TYPE_AVHRR_1KM	0.15
VOLCANO_SMITH_1KM	0.15
NPP_VOLCANIC_ASH	22.83
Total	91.64



Volcanic Ash Algorithm Validation Datasets (1/2)

• A total of 81 special cases for Volcanic Ash validation.

• The VIIRS granule time tags are given as below:

2013270 0137 08 d20130927 t0136337 e0137579 b09927 2013270 0959 17 d20130927 t0958421 e1000063 b09932 2013270 1000 42 d20130927 t1000075 e1001317 b09932 2013270 2015 14 d20130927 t2014393 e2016034 b09938 2014271_0224_36_d20140928_t0224016_e0225258_b15120 2014271 0226 02 d20140928 t0225270 e0226512 b15120 2014271 0227 27 d20140928 t0226524 e0228166 b15120 2014271 0228 52 d20140928 t0228178 e0229420 b15120 2014271 0233 09 d20140928 t0232340 e0233582 b15120 2014327_0139_11_d20141123_t0138365_e0140007_b15914 2014329 0240 55 d20141125 t0240200 e0241442 b15943 2015047 0323 28 d20150216 t0322539 e0324181 b17121 2015056 0748 27 d20150225 t0747526 e0749168 b17251 2015056 1858 26 d20150225 t1857516 e1859158 b17258 2015056_1859_52_d20150225_t1859170_e1900412_b17258 2015075 1506 57 d20150316 t1506220 e1507462 b17525 2015113 0504 33 d20150423 t0503582 e0505224 b18058 2015113 0505 58 d20150423 t0505236 e0506478 b18058 2015113 0507 24 d20150423 t0506490 e0508114 b18058 2015113 0508 47 d20150423 t0508126 e0509368 b18058 2015113 0510 13 d20150423 t0509380 e0511022 b18058 2015113 0511 38 d20150423 t0511034 e0512276 b18058 2015113 0513 03 d20150423 t0512288 e0513530 b18058 2015113 0514 29 d20150423 t0513542 e0515184 b18058 2015113_0645_31_d20150423_t0644566_e0646208_b18059 2015113 0646 57 d20150423 t0646220 e0647462 b18059 2015113 0648 22 d20150423 t0647474 e0649116 b18059 2015113 0649 47 d20150423 t0649128 e0650370 b18059 2015113 0651 13 d20150423 t0650382 e0652024 b18059 2015113_0652_38_d20150423_t0652036_e0653278_b18059 2015113 0654 04 d20150423 t0653290 e0654532 b18059 2015113 0655 29 d20150423 t0654544 e0656186 b18059 2015113 1729 55 d20150423 t1729201 e1730443 b18065 2015113 1731 20 d20150423 t1730455 e1732097 b18065 2015113_1732_45_d20150423_t1732109_e1733351_b18065 2015113 1734 11 d20150423 t1733363 e1735005 b18065 2015113 1735 36 d20150423 t1735017 e1736259 b18065 2015113 1737 02 d20150423 t1736271 e1737513 b18065 2015113 1738 27 d20150423 t1737525 e1739167 b18065 2015113 1739 52 d20150423 t1739179 e1740421 b18065



Volcanic Ash Algorithm Validation Datasets (2/2)

• The VIIRS granule time tags are given as below:

2015113 1909 29 d20150423 t1908549 e1910191 b18066 2015113 1910 55 d20150423 t1910203 e1911445 b18066 2015113 1912 20 d20150423 t1911457 e1913099 b18066 2015113_1913_46_d20150423_t1913111_e1914353_b18066 2015113 1915 11 d20150423 t1914365 e1916007 b18066 2015113 1916 36 d20150423 t1916019 e1917261 b18066 2015113 1918 02 d20150423 t1917273 e1918515 b18066 2015113 1919 27 d20150423 t1918527 e1920169 b18066 2015114_0444_12_d20150424_t0443371_e0445013_b18072 2015114 0445 37 d20150424 t0445025 e0446267 b18072 2015114 0447 02 d20150424 t0446279 e0447521 b18072 2015114 0448 28 d20150424 t0447533 e0449175 b18072 2015114 0449 53 d20150424 t0449187 e0450429 b18072 2015114_0451_19_d20150424_t0450441_e0452083_b18072 2015114 0452 44 d20150424 t0452095 e0453337 b18072 2015114 0454 09 d20150424 t0453349 e0454591 b18072 2015114 0455 35 d20150424 t0455003 e0456245 b18072 2015114 0625 12 d20150424 t0624373 e0626015 b18073 2015114 0626 37 d20150424 t0626027 e0627269 b18073 2015114 0628 03 d20150424 t0627281 e0628523 b18073

2015114 0629 28 d20150424 t0628535 e0630159 b18073 2015114 0630 52 d20150424 t0630171 e0631413 b18073 2015114 0632 17 d20150424 t0631425 e0633067 b18073 2015114 0633 42 d20150424 t0633079 e0634321 b18073 2015114 0635 08 d20150424 t0634334 e0635575 b18073 2015114 1709 35 d20150424 t1709008 e1710250 b18079 2015114 1711 01 d20150424 t1710262 e1711504 b18079 2015114 1712 26 d20150424 t1711516 e1713158 b18079 2015114_1713_52_d20150424_t1713170_e1714412_b18079 2015114 1715 17 d20150424 t1714424 e1716048 b18079 2015114 1716 41 d20150424 t1716060 e1717302 b18079 2015114 1718 06 d20150424 t1717315 e1718556 b18079 2015114 1719 31 d20150424 t1718569 e1720210 b18079 2015114_1850_34_d20150424_t1849592_e1851234_b18080 2015114 1851 59 d20150424 t1851246 e1852488 b18080 2015114 1853 25 d20150424 t1852500 e1854142 b18080 2015114 1854 50 d20150424 t1854154 e1855396 b18080 2015114 1856 15 d20150424 t1855408 e1857050 b18080 2015114_1857_41_d20150424_t1857062_e1858304_b18080 2015114 1859 06 d20150424 t1858316 e1859558 b18080 2015114 1900 32 d20150424 t1859570 e1901212 b18080



JPSS RR PS Algorithm Software

 Aerosol AOD/ADP Product Generation Unit » AOD Algorithm Aerosol Optical Depth Product Aerosol particle Size Product » ADP Algorithm Aerosol Smoke Detection Aerosol Dust detection



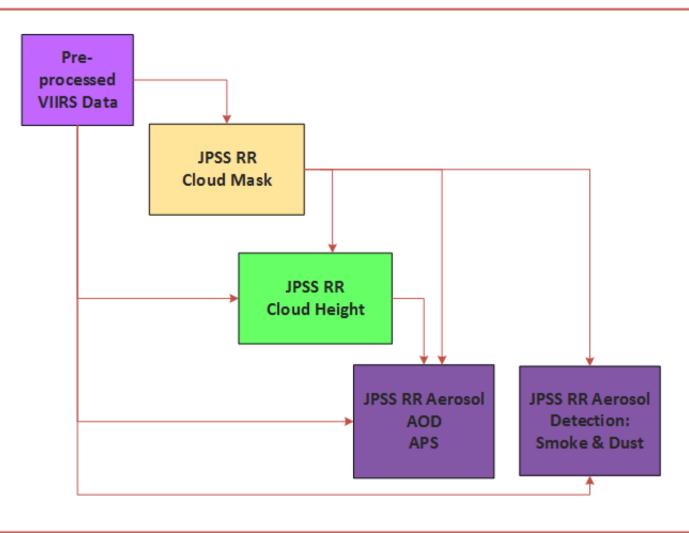
AOD/ADP Algorithm Software Description

 Design Language – C/C++ SLOC » Executable code - AOD - 4719 – ADP – 2602 » With Comments - AOD - 10078 – ADP – 5678



AOD/ADP Algorithm Product Precedence

JPSS RR Aerosol AOD/ADP Product Precedence



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AOD Algorithm Output

- Algorithm employs VIIRS Mbands M01 M11, M15, and M16
- Clear, daytime only
- Products: AOD and APS

Name	Туре	Description	Dimension
AOD at 550nm	product	Retrieved aerosol optical depth at 550 nm	granule (xsize, ysize)
AOD in VIIRS channels	product	Retrieved aerosol optical depth in VIIRS bands M1-M11	granule (xsize, ysize)
Aerosol type ID	output	Aerosol model selected from prescribed models during the retrieval; one for land and two (fine- mode and coarse mode) for ocean	granule (xsize, ysize)
Fine-mode weight (ocean only)	output	Fraction of fine-mode particle AOD to total AOD retrieved at 550nm over ocean	granule (xsize, ysize)
Aerosol Particle size	product	Ångström Exponents (proxy for particle size) calculated from AOD at two pairs of wavelengths (0.48,0.86 µm and 0.86, 2.25 µm)	granule (xsize, ysize)
Suspended Matter	output	Suspended Matter for both ocean and land	granule (xsize, ysize)



AOD Algorithm Output (cont.)

Name	Туре	Description	Dimension
CoarseMdIldx	output	Retrieved coarse aerosol model index over ocean (best solution)	granule (xsize, ysize)
FineMdIldx	output	Retrieved fine aerosol model index over ocean (best solution)	granule (xsize, ysize)
SfcRefl	output	land surface reflectance at 0.47, 0.64 and 2.26 micron	granule (xsize, ysize, 11)
AerMdl	output	Aerosol model: 0-oceanic, 1-dust, 2-generic, 3- urban, 4-heavy smoke	granule (xsize, ysize)
QCPath	output	Flags indicating critical path	granule (xsize, ysize)
QCAOD	output	Flags indicating AOD quality	granule (xsize, ysize)
QCFlag	output	Flags indicating retrieval quality	granule (xsize, ysize)
QC flags	output	Input Quality control flags for each pixel indicating: input reflectance data quality, input ancillary data quality, input geometry quality	granule (xsize, ysize) 708



AOD Algorithm Output Product Quality Flags

Aerosol Optical Depth Quality Control Codes				
Byte	Bits	Quality Flag Name	Meaning	
	0	QC_INPUT_LON	0: valid longitude (-180 - 180°)	
	0		1: out-of-range longitude	
	1	QC_INPUT_LAT	0: valid latitude (-90 - 90°)	
	•		1: out-of-range latitude	
	2	QC_INPUT_ELEV	0: valid elevation (-2 – 10 km)	
1: Input	2		1: out-of-range elevation	
Geometry	3	QC_INPUT_SOLZEN	0: valid solar zenith (0 - 90°)	
Quality Flag	,		1: out-of-range solar zenith	
Quality Liag	4	QC_INPUT_SATZEN	0: valid satellite zenith (0 - 90°)	
	•		1: out-of-range satellite zenith	
	5	QC_INPUT_SOLAZI	0: valid solar azimuth (0 - 180°)	
	-		1: out-of-range solar azimuth	
	6	QC_INPUT_SATAZI	0: valid satellite azimuth (0 - 180°)	
			1: out-of-range satellite azimuth	
	0		00: constant TPW data (2.0 cm)	
	1	QC_INPUT_TPW	01: valid TPW data from ABI retrieval (0-20 cm) 10:	
			valid TPW data from model (0-20 cm)	
	2		00: constant ozone data (0.35 atm-cm) 01: valid ozone data from ABI retrieval (0.0 – 0.7 atm-cm)	
	3	QC_INPUT_OZONE		
2: Input	-	QC_INPUTPRES	10: valid ozone data from model (0.0 – 0.7 atm-cm) 0: valid model surface pressure (500 – 1500 mb)	
Ancillary Data	4		1: constant surface pressure (1013 mb)	
Flag	6	QC_INPUT_HGT QC_INPUT_WSP	0: valid model surface height (-2 – 10 km)	
Ŭ			1: constant surface height (0 km)	
			0: valid model surface wind speed (0 – 100 m/s)	
			1: constant surface wind speed (6 m/s)	
		QC_INPUT_WDR	0: model surface wind direction (0° - 360°)	
			1: fixed surface wind direction (90°)	
	0		0: valid ABI reflectance in band 1 $(0 - 1)$	
3: Input Reflectance Data Flag		QC_INPUT_REFL_CH1	1: out-of-range ABI reflectance in band 1	
	1	QC_INPUT_REFL_CH2	0: valid ABI reflectance in band 2 $(0 - 1)$	
			1: out-of-range ABI reflectance in band 2	
	2	QC_INPUT_REFL_CH3	0: valid ABI reflectance in band 3 $(0 - 1)$	
			1: out-of-range ABI reflectance in band 3	
	3	QC_INPUT_REFL_CH5	0: valid ABI reflectance in band 5 $(0 - 1)$	
			1: out-of-range ABI reflectance in band 5	
			0: valid ABI reflectance in band 6 $(0 - 1)$	
	4	QC_INPUT_REFL_CH6	4. out of renge ADI reflectores in band C	

AOD Algorithm Output Product Quality Flags (cont.)

Aerosol Optical Depth Quality Control Codes			
Byte	Bits	Quality Flag Name	Meaning
	0	QC_CLOUD_MASK	0: clear sky
	0		1: cloudy sky
	1	QC_RET_SCENE	0: over-land algorithm is used
			1: over-water algorithm is used
	2	QC_LAND_TYPE	0: vegetation
4: Critical			1: soil
Path Flag	3	QC_LAND_BRISFC	0: dark surface
			1: bright surface
	4	QC_LAND_SNOW	0: no snow contamination
			1: with snow contamination
	5	QCWATER_GLINT	0: no sunglint contamination
			1: with sunglint contamination
5: AOD Product Quality Flag	0	QC_RET	0: AOD is retrieved
			1: AOD is not retrieved
	1	QC_RET_EXTRP	0: interpolation within LUT AOD range
			1: extrapolation of AOD used
	2	QC_OUT_SPEC	0: within F&PS specification range
			1: out of F&PS specification range
	3	QC_LOWSON	0: solar zenith angle not larger than 80°
			1: solar zenith angle larger than 80°
	4	QC_LOWSAT 0: local zenith angle not larger than 60° 1: local zenith angle larger than 60°	0: local zenith angle not larger than 60°
			1: local zenith angle larger than 60°



AOD Algorithm Product Monitoring Metadata

AOD Algorithm Product Monitoring Metadata

Variable Name	Definition
MeanAOT	Mean AOT at 550 nm
HighQualityPct	Percent of high quality retrievals
RetrievalPct	Percent of AOD retrievals



ADP Algorithm Output

- Algorithm employs VIIRS Mbands M01 M13, M15, and M16
- Clear, daytime only
- Products: Aerosol Detection- Smoke & Dust

Name	Туре	Description	Dimension
Smoke Flag	output	Detected smoke binary flag (1/0 - yes/no)	granule (xsize, ysize)
Dust Flag	output	Detected dust binary flag (1/0 – yes/no)	granule (xsize, ysize)
Aerosol	output	Detected Aerosol binary flag(1/0 – yes/no)	granule (xsize, ysize)
DAII	output	Dust Aerosol Index	granule (xsize, ysize)
NDAI	output	Non-Dust Aerosol Index	granule (xsize, ysize)
ADP QC Flags	output	Retrieval and diagonostic Quality Flags	granule (xsize, ysize)



ADP Algorithm Output Product Quality Flags

Aerosol Detection Quality Flags

Byte/Bit Quality flag name Meaning		leaning		
		1bit: 0 (default)	1	
		2bit: 00 (default)	01	11
0	QC_SMOKE_DETECTION	Determined (good)	not Determined(bad)	
1	QC_DUST_DETECTION	Determined(good)	not Determined(bad)	
2-3	QC_SMOKE_CONFIDENCE	Low	Medium	High
4-5	QC_DUST_CONFIDENCE	Low	Medium	High
6	SPARE			
7	SPARE			



ADP Algorithm Product Monitoring Metadata

ADP Algorithm Product Monitoring Metadata

Variable Name	Definition
NumOfGoodDustRetrieval	Number of good dust retrievals
NumOfGoodSmokeRetrieval	Number of good smoke retrievals
TotalPixel	Total number of attempted retrievals
SmokePct	Percent of retrievals with Good (determined) smoke retrievals
NoSmokePct	Percent of retrievals with Bad (not determined) smoke retrieval
DustPct	Percent of retrievals with Good (determined) dust retrievals
NoDustPct	Percent of retrievals with Bad (not determined) dust retrieval
SmokeConfidLowPct	Percent of retrievals with Low Confidence Smoke Detection
SmokeConfidMediumPct	Percent of retrievals with Medium Confidence Smoke Detection
SmokeConfidHighPct	Percent of retrievals with High Confidence Smoke Detection
DustConfidLowPct	Percent of retrievals with Low Confidence Dust Detection
DustConfidMediumPct	Percent of retrievals with Medium Confidence Dust Detection
DustConfidHighPct	Percent of retrievals with High Confidence Dust Detection



AOD/ADP Algorithm Test Environment & Timing Info.

- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~162 seconds to generate RR AOD/ADP product outputs on a single granule at 750 m resolution, with a segment size of 120 in framework



AOD/ADP Algorithm Timing Information

Unit	Time (seconds)
VIIRS_SDR_MULTIRES	9.67
LAND_MASK_NASA_1KM	0.09
NWP_GFS	18.53
SFC_ELEV_GLOBE_1KM	0.34
SFC_TYPE_AVHRR_1KM	0.08
DESERT_MASK_CALCLTED	0.01
OISST_DAILY_QTRDEG	1.06
SNOW_MASK_NWP	0.11
NPP_BAYES_CLOUD_MASK	1.58
NPP_VIIRS_CLD_HEIGHT	4.56
AWG_AER_AOD	121.19
NPP_VIIRS_AERADP	4.48
Total	161.7



AOD/ADP Algorithm Validation Datasets

Apr 10-25, 2014
Jul 10-25, 2014
Oct 10-25, 2014
Jan 01-31, 2015



JPSS RR PS Algorithm Software

Cryosphere Snow Product Generation Unit

 Snow Cover Algorithm
 Binary Snow Mask Product
 Reflectance based Snow Fraction
 (RR Product)
 NDSI Snow Fraction Product
 (Primary Product)



Snow Algorithm Software Description

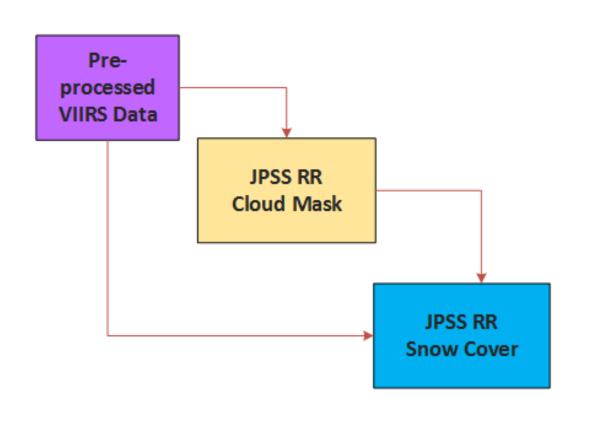
Design Language – Fortran90

SLOC
 » Executable code
 – Snow Cover – 2048
 » With Comments
 – Snow Cover – 2429



Snow Algorithms Product Precedence

JPSS RR Cryosphere Snow Product Precedence





Snow Cover Algorithm Output

- Algorithm uses VIIRS bands (Iband) 101, 102, 103, 104, 105 \mathbf{O}
- \bullet
- Clear, daytime only Products: Snow Mask, Reflectance based Snow Fraction, and \bigcirc **NDSI Snow Fraction**

Name	Туре	Description	Dimension
Snow Mask	Product	Pixel level output: Binary Snow Mask product	granule (xsize, ysize)
Reflectance based Snow Fraction	RR Product	Pixel level output: Snow Fraction RR product	granule (xsize, ysize)
NDSI Snow Fraction	Primary Product	Pixel level output: Snow Fraction operational product	granule (xsize, ysize)
Quality Flags for Snow Mask/ Reflectance based Snow Fraction	Output	Pixel level output: quality flag for Snow Cover/Fraction retrieval	granule (xsize, ysize)
Quality Flags for NDSI Snow Fraction	Output	Pixel level output: quality flag for NDSI Snow fraction	granule (xsize, ysize)



Snow Cover Algorithm Output Product Quality Flags

Snow Cover (Binary/ Fractional) Retrieval Quality Control Codes		
Flag Description	Flag Value	
Good Retrieval	0	
water pixel flag	105	
cloudy pixel flag	110	
rejected snow pixel (snow climatology) flag	111	
rejected snow pixel (temperature climatology)	112	
rejected snow pixel (spatial consistency) flag	113	
rejected snow pixel (temperature uniformity) flag	114	
rejected snow pixel spare	115	
unclassified pixel flag value	120	
dark (insufficient daylight) pixel flag	121	
undetermined pixel flag	122	
VIIRS bad pixel data flag	124	
No VIIRS coverage pixel flag value (fill value)	125	



Snow Cover Algorithm Product Monitoring Metadata

Snow Cover Algorithm Product Monitoring Metadata

Variable Name	Definition
NumTotalPix	Total number of pixels on which retrieval attempted
NumClearPix	Number of pixels which are cloud free
NumConfSnowPix	Number of confidently snow pixels
NumRejSnowPix	Number of rejected snow pixels based on various tests (snow climatology, temperature climatology, spatial consistency, and temperature uniformity)



- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~75 seconds to generate RR Snow product outputs on a single granule at 375 m resolution, with a segment size of 120, in framework



Snow Algorithm Timing Information

Unit	Time (seconds)
VIIRS_SDR_MULTIRES	36.5
LAND_MASK_NASA_1KM	0.3
NWP_GFS	17.08
SFC_ELEV_GLOBE_1KM	2.26
CLIMATIC_LST_ISCCP	0.04
NPP_BAYES_CLOUD_MASK	1.62
NPP_VIIRS_SNOW_COVER	18.02
Total	75.82



Snow Algorithm Validation Datasets

Apr 10-25, 2014
Jul 10-25, 2014
Oct 10-25, 2014
Jan 01-31, 2015



JPSS RR PS Algorithm Software

Cryosphere Ice Product Generation Unit

 Ice Concentration Algorithm
 Ice Concentration/Cover Product
 Ice Surface Temperature Product

 Ice Age Algorithm

 Ice Age Product
 Ice Thickness



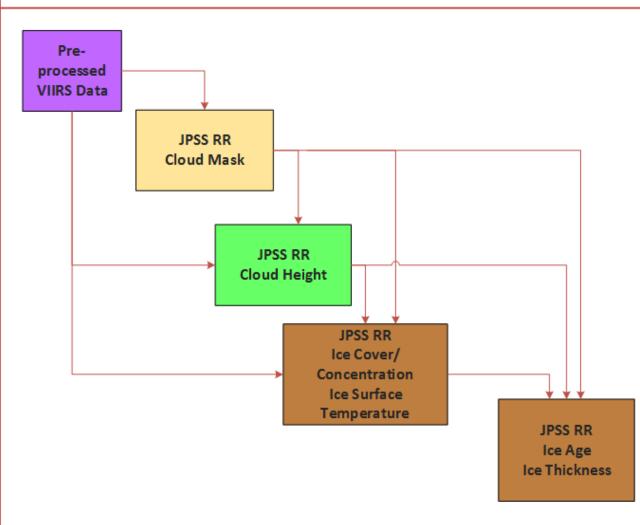
Ice Algorithm Software Description

- Design Language Fortran90
- SLOC
 - » Executable code
 - Ice Concentration 2585
 - Ice Age 3379
 - » With Comments
 - Ice Concentration 3099
 - Ice Age 3727



Ice Algorithms Product Precedence

JPSS RR Cryosphere Ice Product Precedence





Ice Concentration Algorithm Output

- Algorithm uses VIIRS Mbands 03, 04, 05, 07, 10, 15, 16
- Products: Ice Concentration/Cover and IST

Name	Туре	Description	Dimension
Ice cover	output	Output contains ice extent map for each pixel with water surface type	Scan grid (xsize, ysize)
Ice concentration	product	Output contains ice concentration for each pixel identified as ice	Scan grid (xsize, ysize)
Ice surface skin temperature	product	Output contains ice surface skin temperature for each pixel identified as ice	Scan grid (xsize, ysize)
QC flags	output	Quality Control Flags for every pixel	Scan grid (xsize, ysize)



Ice Concentration Algorithm Output Product Quality Flags

	Ice Concentration Retrieval Quality Flags			
Bit 0	Bit 1	Definition		
0	0	Valid retreival; Normal or optimal		
0	1	Retreival; Uncertrain or sub-optimal		
1	0	Non-retrievable		
1	1	Bad data		



Ice Concentration Algorithm Product Monitoring Metadata

Ice Concentration Algorithm Product Monitoring Metadata

Variable Name	Definition
TotWaterPixs	Total number of pixels with water surface
TotIceRetrvIs	Total number of valid ice cover and concentration retrievals (normal + uncertain)
IceRetrPct	Total percentage of valid ice cover and concentration retrievals of all pixels with water surface
TotIceTermnt	Total pixels numbers of terminator pixels (Non-retrievable and Bad data)
IceTermntPct	percentage of terminator pixels (Non-retrievable and Bad data)
TotDaytimePixs	Pixel number of daytime ice cover and concentration valid retrievals
TotNighttimePixs	Pixel number of nighttime ice cover and concentration valid retrievals
MeanIceConc	Mean of valid ice concentration retrievals
MaxIceConc	Maximum of valid ice concentration retrievals
MinIceConc	Minimum of valid ice concentration retrievals
STDIceConc	Standard deviation of valid ice concentration retrievals
Tot_QACat01	Number of QA flags with Normal or Optimal values
Tot_QACat02	Number of QA flags with Uncertain or Suboptimal values
Tot_QACat03	Number of QA flags with Non-retrievable values
Tot_QACat04	Number of QA flags with Bad data values



Ice Age Algorithm Output

- No VIIRS data
- Products: Ice Age/Thickness

Name	Туре	Description	Dimension
Ice Thickness	Product	Automated sea and lake ice thickness	granule (xsize, ysize)
Ice age	Product	Automated sea and lake ice age	granule (xsize, ysize)
QC	Output	granule level output: ice retrieval quality	granule (xsize, ysize)
Product Quality	Output	Product qualiity information	granule (xsize, ysize)



Ice Age Algorithm Output Product Quality Flags

	Ice Age Retrieval Quality Flags			
Bit 0	Bit 1	Definition		
0	0	Valid retrieval; Normal or optimal		
0	1	Retrieval; Uncertain or sub-optimal		
1	0	Bad data		
1	1	Non-retrievable		



Ice Age Algorithm Product Monitoring Metadata

Ice Age Algorithm Product Monitoring Metadata

Variable Name	Definition
Tot_QACat01	Number of QA flag values with Good or Optimal retrievals
Tot_QACat02	Number of QA flag values with Uncertain or Suboptimal retrievals
Tot_QACat03	Number of QA flag values with Bad or missing retrievals
Tot_QACat04	Number of QA flag values with Non-retrievable retrievals
TotWaterPixs	Number of pixels with water surface
TotRetrPixs	Number of valid ice thickness and age retrievals (good + uncertain)
TermntPixPct	Percentage of terminator pixels (Non-retrievable and Bad)
TotDaytimePixs	Number of valid daytime ice thickness and age valid retrievals
TotNighttimePixs	Number of valid nighttime ice thickness and age valid retrievals
MeanIceThk	Mean valid ice thickness retrievals
MaxIceThk	Maximum of valid ice thickness retrievals
MinIceThk	Minimum of valid ice thickness retrievals
STDIceThk	Standard Deviation of valid ice thickness retrievals

Ice Algorithm Test Environment & Timing Info.

- The algorithm was tested on a Linux machine (3.2 GHz 12 dual core CPUs with 32 GB memory/CPU, 2TB disk space).
 - » Intel compiler was used
 - » Algorithm was compiled as 64 bit

 It takes ~30 seconds to generate RR Ice products on a single granule at 750 m resolution, with a segment size of 120 in framework



Ice Algorithm Timing Information

Unit	Time (seconds)
VIIRS_SDR_MULTIRES	10.03
LAND_MASK_NASA_1KM	0.19
NPP_BAYES_CLOUD_MASK	1.62
NPP_VIIRS_CLD_HEIGHT	4.67
AWG_ICE_CONC	11.83
AWG_CRYOS_ICE_AGE	0.73
Total	29.07



Ice Algorithm Validation Datasets

Apr 10-25, 2014
Jul 10-25, 2014
Oct 10-25, 2014
Jan 01-31, 2015



- All JPSS RR product output files contain information on NDE required metadata
 - » Collection Level Metadata
 - static with respect to each NUP*.
 - » Granule Level Metadata
 - granule dependent and thus are dynamic with respect to the observation
 - » Swath Geographic Metadata
 - satellite's native geolocated observation



Collection level Metadata

Attribute Name	Data Type	Value/Description
Conventions	string	"CF-1.5"
Metadata_Conventions	string	"CF-1.5, Unidata Dataset Discovery v1.0"
standard_name_vocabulary	string	"CF Standard Name Table (version 17, 24 March 2011)"
project	string	"S-NPP Data Exploitation"
institution	string	"DOC/NOAA/NESDIS/NDE->S-NPP Data Exploitation, NESDIS, NOAA, U.S. Department of Commerce"
naming_authority	string	"gov.noaa.nesdis.nde"
satellite_name	string	"NPP"
instrument_name	string	"VIIRS"
title	string	Set to the NUP product short name
summary	string	Brief description of the product
history	string	Provides the algorithm name and version used to producte the NUP
processing_level	string	"NOAA Level 2"
references	string	Published or web-based references describing the data or methods used to produce the product



• Granule Level Metadata

Attribute Name	Data Type	Description
id	string	Each product team can implement a unique identifier, approved by NEDSIS data center representative.
Metadata_Link	string	This attribute lists the unique NUP product file name
start_orbit_number	int	This attribute is a sequential whole number set by the S-NPP/JPSS Ground System in the xDR metadata. Orbits are incremented on the northward equatorial node
end_orbit_number	int	This attribute is a sequential whole number set by the S-NPP/JPSS Ground System in the xDR metadata. Orbits are incremented on the northward equatorial node
day_night_data_flag	string	This attribute should be set to "day", "night", or "both" depending on sunlight conditions for observation
ascend_descend_data_flag	int	This attribute indicates whether the satellite is moving northward or southward. The center time of an observation is used. This attribute should be set to 0 (ascending or northward) or 1 (descending or southward)
time_coverage_start	string	This attribute is set to the UTC start time of an observation as "YYYY-MM- DDThh:mm:ssZ", where YYYY is the four digit year, MM is the two digit month, DD is the two digit day, hh is the UTC hour, mm is the UTC minute, and ss is the UTC second
time_coverage_end	string	This attribute is set to the UTC end time of an observation as "YYYY-MM- DDThh:mm:ssZ", where YYYY is the four digit year, MM is the two digit month, DD is the two digit day, hh is the UTC hour, mm is the UTC minute, and ss is the UTC second
date_created	string	This attribute is set to the UTC time the NUP file was created by NDE as "YYYY-MM- DDThh:mm:ssZ", where YYYY is the four digit year, MM is the two digit month, DD is the two digit day, hh is the UTC hour, mm is the UTC minute, and ss is the UTC second



• Swath Geographic Metadata

Attribute Name	Data Type	Description
cdm_data_type	string	This attribute describes the geographic category the NUP data represents. This should be "swath" for native 2-D satellite swath data
geospatial_first_scanline_first_fov_lat	float	These attributes describes the four point geolocated latitude and longitude (polygon) that describes the geographic context for the NUP observation. Latitudes values include -90 (south) to 90 (north) degrees and Longitude values include -180 (west) to 180 (east).
geospatial_first_scanline_last_fov_lat	float	
geospatial_last_scanline_first_fov_lat	float	
geospatial_last_scanline_last_fov_lat	float	
geospatial_first_scanline_first_fov_lon	float	
geospatial_first_scanline_last_fov_lon	float	
geospatial_last_scanline_first_fov_lon	float	
geospatial_last_scanline_last_fov_lon	float	
geospatial_lat_units	string	This attribute should be "degrees_north"
geospatial_lon_units	string	This attribute should be "degrees_east"
geospatial_bounds	string	This attribute describes a closed polygon of N (N>3) latitude and longitude vertices. The last latitude/longitude pair must be identical to the first pair. Latitudes values include -90 (south) to 90 (north) degrees and Longitude values include -180 (west) to 180 (east). This should be "POLYGON((lon1 lat1, lon2 lat2,,lonN latN, lon1 lat1))



JPSS RR PS Software Architecture

Outline

- JPSS RR PS System Overview
- JPSS RR PS Detailed Design
- JPSS RR PS Algorithm Software
- AIT Framework
- Transition to Operations

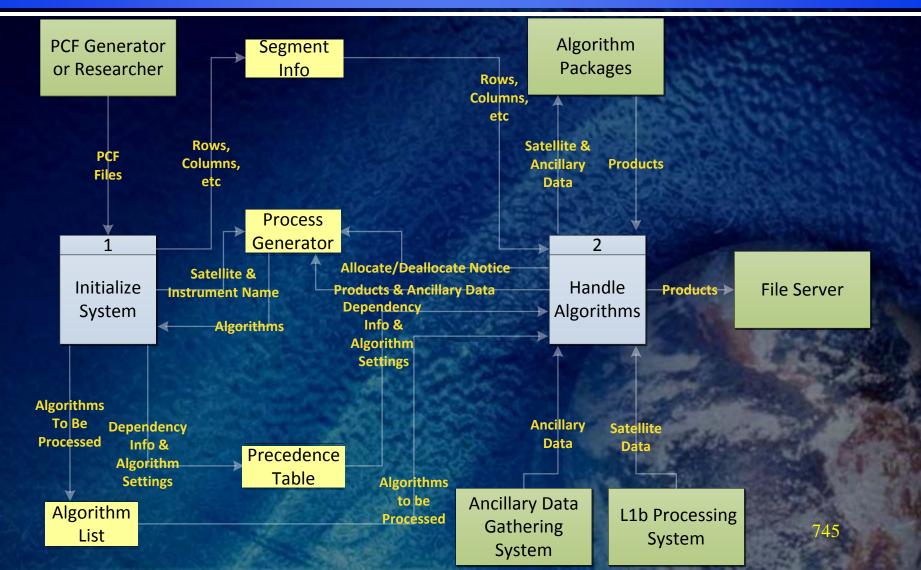


JPSS RR PS

- AIT Framework provides an integrated processing environment for Cloud, Aerosol, and Cryosphere product retrieval processing.
- The following nine slides show the AIT framework unit detailed design, diagram, and data flow.

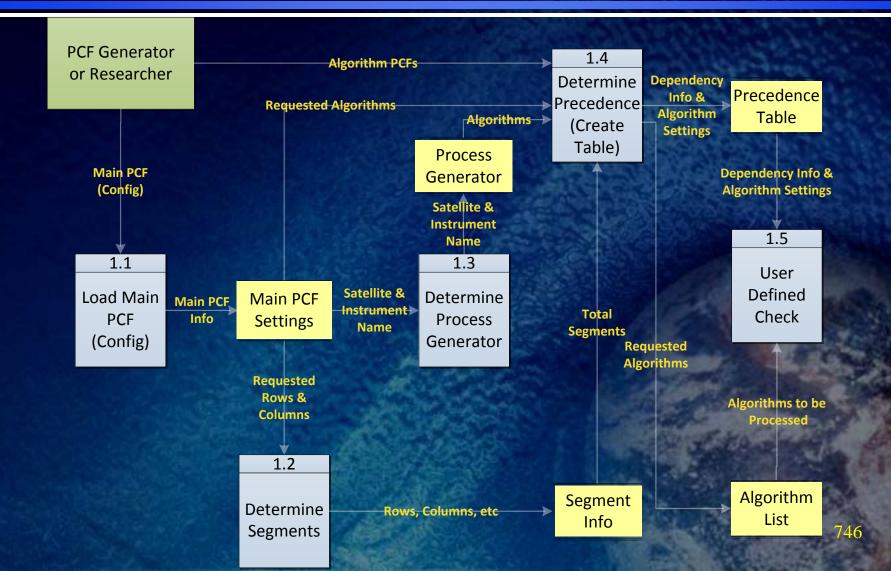


Framework System Level



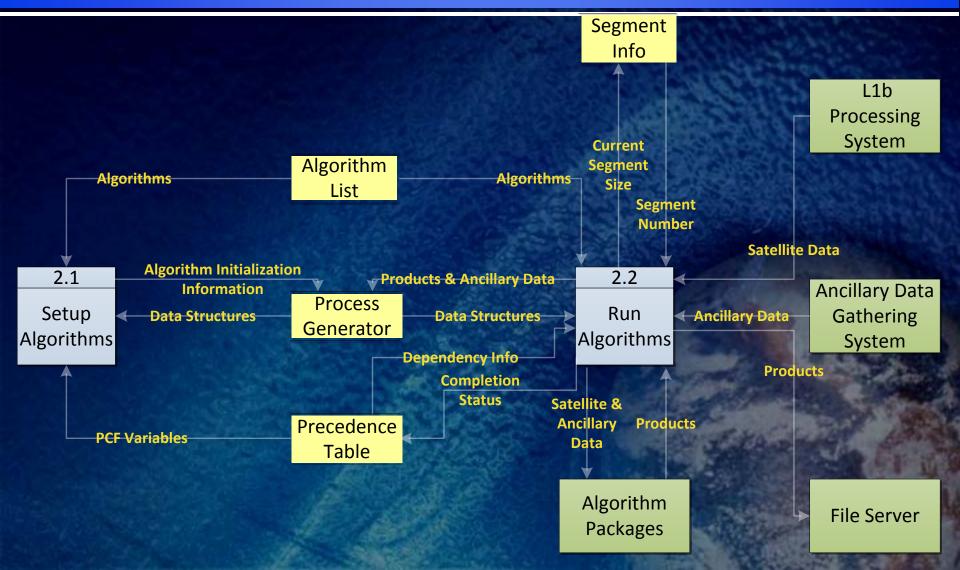


Framework Unit Level 1 Initialize System





Framework Unit Level 2 Handle Algorithms







Production Control Files (PCF)

Data

- » Radiance data
- » Common ancillary data
- » Specific algorithm data





PCF Files

- Production Control Files (PCF) contain the information required to run an algorithm
 - » Algorithm dependencies to determine product precedence
 - » Algorithm specific variables such as flags and thresholds
 - » Framework loads the contents of the PCF file when the algorithm has been flagged to run in the configuration file or if it is needed by something that has been flagged to run in the configuration file.



Table ofDynamicAncillary Data

Ancillary Data	Description	Filename	Size
CRTM	Community Radiative Transfer Model	N/A	N/A
NWP_GFS	NCEP GFS model data in grib2 format – 0.5x0.5 degree (720x361), 26 levels	gfs.tHHz.pgrbfhh	55 – 56MB
OISST_DAILY_QTRDEG	NCEP EMC Reynolds OISST daily analysis, 0.25 degree resolution	avhrr-only-v2.YYYYMMDD.nc	8MB
SNOW_MASK_NWP	Snow/Ice mask, calculated from snow surface variable in the GFS Grib2 file	N/A	N/A



Table ofStatic Ancillary Data

Ancillary Data	Description	Filename	Size
COAST_MASK_NASA_1KM	Global 1km land/water used for MODIS collection 5	coast_mask_1km.nc	890 MB
DESERT_MASK_CALCLTED	Desert mask calculated using LAND_MASK_NASA_1KM and SFC_TYPE_AVHRR_1KM	N/A	N/A
LAND_MASK_NASA_1KM	Global 1km land/water used for MODIS collection 5	lw_geo_2001001_v03m.nc	890 MB
LAND_MASK_NASA_250M	Global 250 m land/water used for MODIS collection 6	MOD44W.A2000055.h??v??. .005.nc	TBD
SFC_ELEV_GLOBE_1KM	Digital surface elevation at 1km resolution	GLOBE_1km_digelev.nc	1843 MB
SFC_TYPE_AVHRR_1KM	Surface type mask based on AVHRR at 1km resolution	gl-latlong-1km-landcover.nc	890 MB
SFC_EMISS_SEEBOR	Surface emissivity at 5km resolution, climatology monthly	global_emiss_intABI_2005DDD.nc	693 MB x 12
GOESR_ABI_CHN7_EMISS	Channel 3.9 um pseudo emissivity	N/A	N/A
SFC_ALBEDO	composites for 0.659µm, 1.64µm and	AlbMap.WS.c004.v2.0.YYYY.DDD. 0.659_x4.nc AlbMap.WS.c004.v2.0.YYYY.DDD. 1.64_x4.nc	28MB x 23 x3
CLIMATIC_LST_ISCCP	Monthly-averaged mean surface temperatures over the globe at 2.5 degree resolution	climatic_lst_month_MM.nc	47MBx12

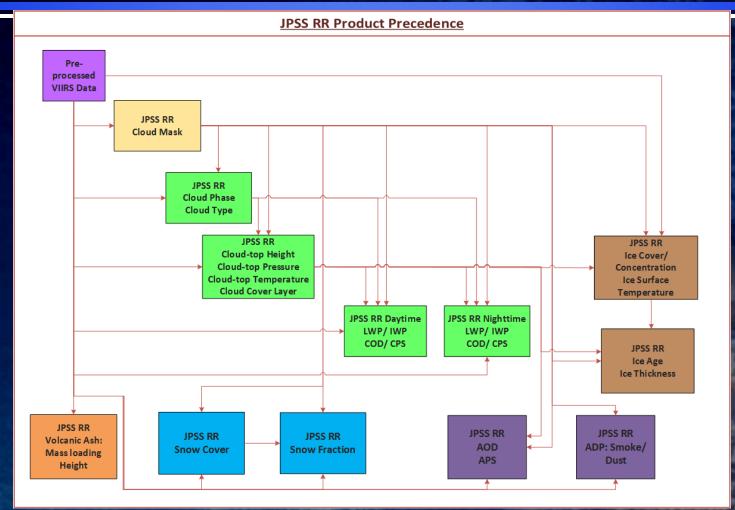


CRTM Inputs

Filename	Description	Size
CloudCoeff.bin	Cloud coefficient data for CRTM	1.6MB
AerosolCoeff.bin	Aerosol coefficient data for CRTM	5.5MB
EmisCoeff.bin	Emissivity coefficient data for CRTM	1.9MB
viirs_npp.SpcCoeff.bin	Space coefficient data of NPP VIIRS-M for CRTM	472B
viirs_npp.TauCoeff.bin	Tau coefficient data of NPP VIIRS-M for CRTM	104KB



Framework Product Precedence



All VIIRS products listed within product precedence are products created within 753 the NDE JPSS Risk Reduction project



JPSS RR PS Software Architecture

Outline

- JPSS RR PS System Overview
- JPSS RR PS Detailed Design
- JPSS RR PS Algorithm Software
- AIT Framework
- Transition to Operations



JPSS RR PS Error Handling

- All return values and exit status from executables, script functions, unit driver scripts, and system calls from scripts are checked
- All errors or noteworthy conditions are trapped. Three common error codes are used in AIT framework product processing to categorize the severity levels:
 - » 0 = NOTICE
 - » 1 = WARNING
 - » 2 = FATAL

Messages are labeled and produced based on the error codes and are directed to log files.



- The SDR processing status file contains information about the VIIRS SDR data preparation. It can be used for tracking the Preprocessor unit on generation of gap-filled SDR data files.
- The unit PSFs provide information about the successfully generated product files from each unit run. The files can be made available to NDE monitoring system for tracking the processing steps and checking the availability of the product files.
- The product files contain algorithm specified metadata. Depending on the requirements, detailed product attributes, such as categorized QA flags and product statistic reports, are provided in the output files. The metadata can be extracted and used as input to the product quality monitoring tool at NDE.

JPSS RR PS System Design Assumptions

- The JPSS RR PS design assumes the NDE PGM will run JPSS RR PS Units in a single working directory that is unique to that run.
- The system PCF will be made available to the system driver script locally in the working directory at run time.
- The NDE DHS must be able to run multiple instances of these units to process concurrently available input data.
- The JPSS RR PS relies on NDE on the data availability of the input data sets, as well as the dynamic ancillary data, such as GFS data, OISST, etc.
- The NDE DHS will perform all file management for JPSS RR PS outside of the working directories where the JPSS RR PS Units run.



JPSS RR PS Transition to NDE

- JPSS RR PS has been fully tested in STAR development environment. The product processing time meets the latency requirements (<30 min). It is ready to run in NDE operational environment.
- All JPSS RR final products will be generated by JPSS RR PS in NDE DHS and will be distributed to NDE DDS
- Detailed information about the unit and subunit level data flow are documented in the JPSS RR PS System Maintenance Manual (SMM) in the DAP delivery
- The final JPSS RR PS package will be:
 - » Delivered to NDE2.0
 - » Integrated into the NDE DHS by the NDE team
 - » NDE will run JPSS RR PS in production mode at NSOF



Summary

- The software architecture design and interfaces of each component in JPSS RR PS have been presented.
- The system data flow of each processing unit has been presented.
- The error handling and product generation information that can be used for JPSS RR product processing monitoring have been presented.



Outline

- Introduction
- Risks and Actions
- Requirements
- Algorithm Readiness
- Software Architecture
- Delivered Algorithm Package
- Risks Summary
- Summary and Conclusions



Delivered Algorithm Package Presented by Walter Wolf





JPSS RR PS DAP

- The JPSS RR PS DAP will be contained in a single tar file that has been compressed using gzip. It has the following name: JRR_DAP_201512.tar.gz
- It will be delivered to SADIE on 18 Dec 2015
- Note that the DAP file name complies with the DAP naming convention identified on page 7 of the DAP Standards.
- When ungzip'd and untar'd, there are 4 main subdirectories and a README file produced in the current working directory:
 - » SOURCE/ All Fortran 77/90, C/C++ code
 - » JPSS RPS_OPS/ All scripts and static system files
 - » DATA/ All sample/test data
 - » DOC/- All SPSRB and NDE documentation
 - » REL-2.0.2.JCSDA_CRTM_gm.tar CRTM 2.0.2 package

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» README - the README file for JPSS RR PS



DAP Checklist

Required DAP Item	Location in DAP		
Science algorithm & HDF to NetCDF conversion source code, including make files and build scripts.	./SOURCE/AIT_framework/ ./SOURCE/extrcat_scan_time/ ./SOURCE/h5augjpss-1.0.0/		
Test plans, test description, test procedures, and detailed performance testing results	./DOC/		
Test input data, ancillary data(static and dynamic), and expected output data.	./DATA/static_input/ ./DATA/supplement_d20150511_t0919230_e0920472_b18316/ ./DATA/supplement_d20150511_t1225439_e1227081_b18318/ ./DATA/supplement_d20150511_t2240157_e2241381_b18324/ ./DATA/working_d20150402_t1054237_e1055479_b17764/ ./DATA/working_d20150511_t0919230_e0920472_b18316/ ./DATA/working_d20150511_t1225439_e1227081_b18318/ ./DATA/working_d20150511_t2240157_e2241381_b18324/ ./DATA/working_output_d20150402_t1054237_e1055479_b17764/ ./DATA/working_output_d20150511_t0919230_e0920472_b18316/ ./DATA/working_output_d20150511_t0919230_e0920472_b18316/ ./DATA/working_output_d20150511_t1225439_e1227081_b18318/ ./DATA/working_output_d20150511_t12240157_e2241381_b18324/		
Processing Scripts	./JRRPS-OPS/scripts/		
Template files for framework algorithm PCFs and processing configuration files.	./JRR-OPS/PCF_Overwrites/ ./JRR-OPS/templates/		
Executables for running Framework, NetCDF conversion , and SDR scan time extraction.	JRRPS-OPS/bin/		
Framework Production Control Files associated with the science algorithms.	JRRPS-OPS/Default_PCF/		
List of algorithms specific to NPP VIIRS (a subset of framework Master List, which includes algorithms for other satellite/instrument pair as well).	JRRPS-OPS/CustomProductLists/		



DAP Checklist

Required DAP Item	Location in Delivered DAP	
Production rule-set definitions.	./DOC/JRRPS_Production_Rules.docx	
Production Control File and Product Status File content and descriptions	./DOC/JRRPS_PCF-PSF.docx	
Quality monitoring information (quality flags, quality flag values).	Section 6 of ./DOC/JRRPS_SMM_1.0.docx	
Product file specifications – layout, content, and size.	Section 7 of ./DOC/JRRPS_SMM_1.0.docx Section 1 of ./DOC/JRRPS_EUM_1.0.docx	
Data flow diagrams.	Section 7 of ./DOC/JRRPS_SMM_1.0.docx	
List of exit codes and their associated messages.	Section 6 of ./DOC/JRRPS_SMM_1.0.docx	
List of expected compiler warnings	Section 4 of ./DOC/JRRPS_SMM_1.0.docx	
Estimates of resources required for execution.	Section 2 of ./DOC/JRRPS_SMM_1.0.docx	
Algorithm Theoretical Basis Documents (ATBDs) or reference to where the ATBDs can be obtained.	./DOC/Algorithm_Theoretical_Basis_Document_???.docx	
Delivery Memo.	./DOC/Delivery_Memo (To be sent via email at time of delivery to NDE)	
README text file.	./README	



JPSS RR PS Source Code

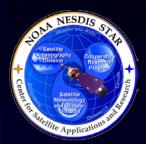
JPSS RR PS Code Area	Language	Number of Files	Number of Lines
AIT Framework (including JPSS RR algorithm code)	Fortran 90	496	235368
AIT Framework(including JPSS RR algorithm code)	C/C++	879	235908
VIIRS SDR gap-filling*	Python	2	332
VIIRS SDR data conversion* (H5 to NetCDF4)	С	7	1804
Unit scripts and utilities	Perl	20	5767
Makefiles, compile scripts*	Make	190	7961



JPSS RR PS Documentation

- The JPSS RR PS DAP will contains the following documents:
 - » Delivery Memo (also included in email notification)
 - » README
 - » JPSSRRPS_SMM_1.0.docx
 - » JPSSRRPS_EUM_1.0.docx
 - » Algorithm_Theoretical_Basis_Document_???.docx
 - » JPSSRRPS_Production_Rules.docx
- The SMM, EUM, and ATBD contain unfinished sections that need to be completed by Integration Programmers (NDE) and the PAL (OSPO).
 - » The document objects for sections have been highlighted in yellow

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JPSS RR Algorithm Readiness Summary

- The JPSS RR PS software has been tested; the results have been presented.
- The DAP contents have been verified.
- DAP has been delivered to NDE.
- JPSS RR PS developers will work with NDE to address any issues that arise during integration and NDE system testing.



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Risks Summary Presented by Walter Wolf





Cryosphere CDR Risks and Actions

- CDR Risk 8: Use SAR imagery to validate ice types and age
- Risk Assessment: Low
- Mitigation:
 - » Working on getting SAR imagery
 - » Algorithm does meet the requirements
 - » Will perform more validation when SAR data is acquired
- Status: Open



ARR Overall Risks and Actions

- ARR Risk 2: Address the recommended code updates for final DAP, as cited in OSPO Software Review
- Risk Assessment: Low
- Mitigation:
 - » Address remaining 'recommended updates' for final DAP in Apr 2016
- Status: Open



ARR Overall Risks and Actions

- ARR Risk 3: The product monitoring metadata variables for DCOMP algorithm will undergo revision.
- Risk Assessment: Medium
- Mitigation:
 - » Fine tune DCOMP metadata variables
 - » Update OSPO product monitoring team about the changes.
- Status: Open



Risk and Actions Summary

There is currently three risks identified

• They remains open until final DAP



Outline

- Introduction
- Risks and Actions
- Requirements
- Algorithm Readiness
- Software Architecture
- Delivered Algorithm Package
- Risks Summary
- Summary and Conclusions



Summary and Conclusions

Presented by

Walter Wolf





Review Objectives Have Been Addressed

- Risks and Actions have been reviewed
- Requirements have been reviewed
- Algorithm Readiness has been reviewed
- Software Architecture has been reviewed
- Open Risks and Actions have been reviewed



Current Status

- Development on the JPSS RR Processing System has been completed
- The JPSS RR documents have been completed
- The Final JPSS RR Processing System DAP will be delivered to NDE via SADIE on December 18th



Next Steps

Updated DAP delivery to NDE2.0 in April 2016
Operational Readiness Review



Open Discussion

The review is now open for free discussion