VIIRS-VH ALGORITHM THEORETICAL BASIS DOCUMENT VERSION 1.0

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VIIRS-VH ALGORITHM THEORETICAL BASIS DOCUMENT VERSION HISTORY SUMMARY

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ABSTRACT

This document is the Algorithm Theoretical Basis Document (ATBD) for the NPP-VIIRS Vegetation Health Operational Product (VIIRS-VH) System developed by the NOAA/NESDIS Center for Satellite Applications and Research (STAR). The main function of the VIIRS-VH is to produce surface vegetation health indices from observation of the Visible Infrared Imaging Radiometer Suite (VIIRS) for applications in numerical weather and seasonal climate prediction models at the National Centers for Environmental Prediction, Climate Prediction Center (NCEP/CPC) and USDA/WAOB. The VIIRS is currently flying on the Suomi National Polar-orbiting Partnership (NPP) spacecraft and will be eventually onboard the next generation weather and environmental forecasting Joint Polar Satellite System (JPSS). The retrieval algorithm used in VIIRS-VH is the Multi Channel Retrieval (MCR) algorithm, similar to the prototype VH product derived from Advanced Very High Resolution Radiometer (AVHRR) onboard NOAA polar-orbiting satellites. VH will use VIIRS’s visible (VIS: 0.6 \( \mu \text{m} \)), near-infrared (NIR: 0.8 \( \mu \text{m} \)) and thermal (IR: 10.-12 \( \mu \text{m} \)) bands. This document describes the details of the algorithm. To meet the data needs of NCEP and other potential users, the VIIRS-VH was designed as a global weekly composite product. Details of these products are presented in Sections 2 and 3 of this document.

VIIRS-VH system was developed/extended from the VH system for AVHRR (VHP 2.0). It is an update version of VHP.

1 INTRODUCTION

NOAA has developed a new AVHRR-based operational data and products named Vegetation Health Product (VHP). The VIIRS-VH provides continuous operational service from Suomi NPP. It takes advantage of long-term global AVHRR records (34-year), and high resolution (375 m) of VIIRS measurements. It contains data and products from infrared channels, radiances, indices (raw and with suppressed noise), biophysical climatology and, products. Applications include monitoring the environmental and socioeconomic activities (Kogan 1995, 1997). The algorithm was developed by scientists and developers of STAR VHP team led by Dr. Felix Kogan. The Office of Satellite and Product Operations (OSPO) will be responsible for data dissemination.

1.1 Purpose of This Document

The purpose of this document is to describe the VIIRS-VH algorithm in detail for the STAR Suomi-NPP Data Exploitation (NDE) Preliminary Design Review (PDR).

1.2 Who Should Use This Document
The intended users of this document include customers, NDE PDR reviewers, data users and processing system operators of VIIRS-NPP.

1.3 Inside Each Section

This document contains the following sections:

Section 1.0 – Introduction: Section 1 provides the purpose, intended users, and revision history of the ATBD.

Section 2.0 – VIIRS-VH System Overview: Section 2 describes the products generated by the algorithm and the characteristics of the instruments that supply inputs to the algorithm.

Section 3.0 - Algorithm Description: Section 3 describes the algorithm, including a processing overview, input data, physical description, mathematical description, algorithm output, performance estimates, practical considerations, and validation.

Section 4.0 - Assumptions and Limitations: Section 4 states assumptions that were made in determining that the software system architecture as designed will meet the requirements, and states limitations that may impact on the system’s ability to meet requirements.

Section 5.0 - Risk: Section 5 describes algorithm and other risks and actions planned to reduce the risks,

Section 6.0 - Dissemination: Section 6 provides a list of references cited in the document.

1.4 Revision History

The original version (Version 1.0), dated December 24 2013 was produced and is presented at the current PDR (Jan 22, 2014) for review.

Version 1.1 of the VIIRS-VH ATBD, will be produced for the VIIRS-VH Critical Design Review (CDR). Updates will be incorporated into this document as the project progresses.
2 VHP OVERVIEW

2.1 Objectives of Vegetation Health Retrievals

The VIIRS Vegetation Health Product (VIIRS-VH) system was designed to meet the user request # 1105-0004 (NWS/NCEP/CPC) and 1105-0009 (USDA/FAS & WAOB) in the NESDIS Satellite Products and Services Review Board (SPSRB) Request Tracking System.

One of the most important long-term (34-year) satellite-based data records characterizing land surface, air temperature near the ground and climate was created from the Advanced Very High Resolution Radiometer (AVHRR) flown on the National Oceanic and Atmospheric Administration (NOAA) polar-orbiting satellites. Several global data sets have been developed from the AVHRR records since the early 1980s. They were the NOAA’s Global Vegetation Index (GVI and GVI-2), National Aeronautics and Space Administration (NASA)’s Pathfinder, GIMMS and LTDR (Tarpley et al 1984, James and Kalluri 1994, Kidwell 1997, Tucker et al 2004). These datasets focused only on the Normalized Difference Vegetation Index (NDVI), ignoring infrared measurements, which are very useful for monitoring land, climate and socioeconomics. Therefore, NOAA developed a dataset entitled the Global Vegetation Health Product (VHP). The VHP has advantages over other long-term global data sets, being the longest (34-year), having the highest spatial resolution (4-km), containing, in addition to NDVI, data and products from infrared channels, originally observed reflectance and emission, many indices with suppressed noise, biophysical climatology and more importantly, products used for monitoring environmental and socioeconomic activities (Kogan 1995, 1997).

In October 2011, NOAA/NESDIS launched the new generation of satellites (NPP-JPSS) with the most advanced VIIRS sensor on board which provides much better quality data sets and products including the vegetation health product. In the future, AVHRR is expected to be replaced by VIIRS or it successor. For continuity purpose, it is desirable to have vegetation health product derived from VIIRS using the similar algorithm as VHP from AVHRR. Since VIIRS is different than AVHRR, considerable adjustments are required in order to have continuous and un-interrupted flow of VH data with better quality higher resolution and in the form to enable users to provide timely assessments.

The new program for producing VH from VIIRS is named as “VIIRS-VH”. It was developed from existing operational AVHRR-VH system (VHP 2.0). All function of VHP are retained and/or upgraded. It can produce vegetation health product from either VIIRS or AVHRR with various output resolution.

2.2 Instrument Characteristics
Vegetation Health product (VHP) requires the Normalized Difference Vegetation Index (NDVI) data for estimating the vegetation moisture condition and Brightness Temperature (BT) from infrared bands for estimating the surface thermal condition.

For AVHRR-VHP product, these parameters were retrieved from the AVHRR onboard all NOAA polar-orbiting Satellites. NOAA-19 satellite is currently the operational primary satellite for NOAA weather monitoring.

The AVHRR is a six channel scanning radiometer providing three solar channels in the visible-near infrared region and three thermal infrared channels (Table 2.1). More information on AVHRR is provided at http://www.ncdc.noaa.gov/oa/pod-guide/ncdc/docs/klm/html/c7/sec7-1.htm

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<th>Ch. 3B</th>
<th>Ch. 4</th>
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<td>Spectral Range (μm)</td>
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<td>1.58-1.64</td>
<td>3.55-3.93</td>
<td>10.3-11.3</td>
<td>11.5-12.5</td>
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<td>Resolution (km) *</td>
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<td>1.09</td>
<td>1.09</td>
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AVHRR-VH uses the AVHRR Global Area Coverage (GAC) data, with resolution of 4 km at equator.

The Visible Infrared Imager Radiometer Suite (VIIRS) provides advanced imaging and radiometric capabilities from NPP spacecraft and the next generation JPSS.

VIIRS Visible and near infrared channels (I1 – 0.64μm, I2 - 0.86μm) are used to produce the NDVI and infrared band (I5 – 11.0-12.0 μm) are used to produce BT. Derived indices from NDVI and BT will be used to develop VH product.
NDVI is a combination of VIS and NIR bands. For VIIRS: band I1, RED and band I2, NIR.

\[
NDVI = \frac{\rho_{NIR} - \rho_{RED}}{\rho_{NIR} + \rho_{RED}}
\]  

Brightness temperature from VIIRS image band 5 (AVHRR channel 4) is used to characterize the surface thermal condition.

3 ALGORITHM DESCRIPTION

3.1 Processing Outline

The VIIRS-VH system generates weekly VCI, TCI and VHI through the following steps:
Step 1: Retrieval of VIIRS I1, I2, I5 radiances and solar & satellite geometry angles from the Scientific Data Records (SDR) granules and mapped into geographic grid (GG) or Plate Carree projection.

Step 2: Filing gaps

Step 3: Development of daily map

Step 4: Development of weekly composite map by selecting the pixels with maximum NDVI value from 7-day maps.

Step 5: Calculation of NDVI (from I1 and I2) and BT (from I5)

Step 6: Noise removal from NDVI and BT


Step 8: Adjust no noise NDVI and BT to Climatology

Step 9: Calculate three VH indices: Vegetation Condition Index (VCI), Thermal Condition Index (TCI) and Vegetation Health Index (VHI).

The data flow chart for AVHRR-VH and VIIRS-VH are shown in Figure 3.1 and Figure 3.2 respectively.

![Figure 3-1 Data flow chart of AVHRR-VH](image-url)
3.2 Algorithm Input

3.2.1 Reflectance of visible and near infrared bands

VIIRS visible (I1), near infrared (I2) and infrared (I5) from SDR files are used. They are organized by 6 data types and 1014 granules.

- **SVI01**: reflectance of image band 1
- **SVI02**: reflectance of image band 2
- **SVM03**: reflectance of moderate band 3 (optional)
- **SVI05**: temperature of image band 5.
- **IICMO**: cloud information
- **GITCO**: geo-location file, including the data fields: latitude, longitude, solar and sensor zenith angles.

Other optional data generated by JPSS are also used for developing VH products:

- **VLSTO**: land surface type
- **VIVIO**: EVI at top of canopy
• VSCMO: snow cover bitmap
• VSTYO: vegetation Fraction and surface type

3.2.2 Brightness Temperature (BT)

VIIRS images band (I5 – 10.0-12.0 µm) is used to produce BT.

3.2.3 Ancillary Data

The ancillary data for the VIIRS-VH algorithm include land cover map and climatology map.

3.2.3.1 USGS land sea mask map

USGS land sea mask is in geographic grid (equal lat-lon) of 43200 columns and 21600 rows, with resolution of 30 seconds. It covers full surface of the earth, latitude range: [-90S to 90N], longitude range: [-180, 180]. The first pixel is at [-180, 90N]. Original data is downloaded from USGS web site. It was re-formatted to bit map and saved as HDF file. This file will be used as input when making daily and weekly composite maps.

• landseamaskll.bit.hdf 3MB.

3.2.3.2 High resolution land sea mask derived from high resolution MODIS NDVI.

MODIS 2002 to 2012 16-day composite NDVI was used to generate high resolution land sea mask. MODIS NDVI was first re-projected to 500 m GG, then set the land sea flag as land (1) if a pixel has a valid NDVI value in any composite period in the ten years. When processing raw NDVI and BT (“ND” file) with high resolution (example: 500 m) from VIIRS, it will be used to set land sea flag in QA data set. This dataset was saved in 8x8 tiles.

• modis_landmask/landsea_fromNDVI.G500m_r01c01.hdf

3.2.3.3 Land cover map

The International Geosphere-Biosphere Programme (IGBP) Land Cover map, i.e. Global Land Cover Characteristics Data Base (GLCC) was used. This clutter model provides global coverage at a 30 arc second resolution using 17 clutter categories. Details are available at http://edc2.usgs.gov/glcc/ . The database consists of a single file - gigbp2_0ll.img (933,120,000 bytes). This file can be downloaded in a zipped format from http://edcftp.cr.usgs.gov/pub/data/glcc/globe/latlon/gigbp2_0ll.img.gz.
3.2.3.4 Climatology of NDVI and BT

AVHRR NDVI and BT climatology (maximum, minimum, mean and standard deviation) maps were generated from 30 year no noise weekly NDVI and BT.

3.2.3.5 Combined climatology derived from AVHRR and MODIS

Combined climatology was derived from 30-year 4 km AVHRR and 10-year MODIS data.

3.2.3.6 Calibration parameters

For VIIRS, reflectance factors were provided in VIIRS SDR file, which are used to calculate calibrated reflectance.
3.3 Theoretical Description of VHP and VH Method

After noise removal (see Figure 3.4), weather-driven differences in NDVI and BT between the years become apparent: lower NDVI and higher BT in dry years and opposite in normal and wet years. This principle of comparing NDVI and BT for a particular year with their dry-wet range calculated from 30-year observations was laid down in the VH algorithm development and were based on the three laws: Law-of-Minimum, Law –of –Tolerance and Carrying Capacity. The absolute maximum and minimum of NDVI and BT during 1981-2005 were calculated for each of the 52 weeks and for each pixel. They were then used as the criteria to estimate the upper (favorable weather) and the lower (unfavorable weather) limits of the ecosystem resources. Further, for estimation of weather impacts on vegetation condition, NDVI and BT values for a particular time (year and week) were normalized relative to the absolute max/min interval. Following this procedure, NDVI and BT were rescaled based on equations (3.1-3.3). They were named the Vegetation Condition Index (VCI), Temperature Condition Index (TCI) and Vegetation Health Index (VHI). These indices are designed to characterize moisture (VCI), thermal (TCI) and total vegetation health (VHI) conditions in response to weather impacts

\[
VCI = 100 \times \frac{NDVI - NDVI_{min}}{NDVI_{max} - NDVI_{min}} \quad (3.1)
\]
\[
TCI = 100 \times \frac{BT_{max} - BT}{BT_{max} - BT_{min}} \quad (3.2)
\]
\[
VHI = a \times VCI + (1 - a) \times TCI \quad (3.3)
\]

where NDVI, NDVI_{max}, and NDVI_{min} (BT, BT_{max}, and BT_{min}) are the noise reduced (smoothed) weekly NDVI (BT), their multi-year absolute maximum, and minimum, respectively. The VCI, TCI and VHI approximate the weather component in NDVI, BT and their combination values. They fluctuate from 0 to 100, reflecting changes in vegetation conditions from extremely bad to optimal. The weighting factor \(a\) in equation 3.3 was determined by experience, currently, \(a=0.5\).

The quality flags were stored in Quality Assurance (QA) dataset in VH file records if the pixel is over desert, on coastal line, with continues clouds or snow or ice).
3.3.1 Daily map

A daily map is created by projecting satellite observation of a specific day to a predefined grid. This grid is named by “the Global Vegetation Indices” (GVI in the VHP algorithm nomenclature). The area spans from latitude 75.024° N (north) to -55.152° S (south) and from longitude -180° W (west) to 180° E (east). Geographic projection is “Plate Carree” (the sizes of all grid cells are the same degrees in both directions). Further we called this grid as “GVI grid” in VH documents.

3.3.1.1 Variables of VH daily map

Daily map for VH product contains following variables:

- Radiance in VIS, NIR and IR bands
- NDVI and BT
- Sensor and solar zenith and azimuth angles,
- Packed cloud information (serve as quality flags)

3.3.1.2 Two steps procedure for making daily from orbit maps
• First: Make orbit map (an orbit map is part of a daily map; it is composited from the data of an orbit). In order to avoid the overlay of two ends of an orbit any orbit is divided into 2 parts, which are processed separately.
• For orbit map, the pixel closest to the center of a grid cell is normally selected; orbit map will be stored temporary in the memory.
• Fill the internal gaps on an orbit map from the neighboring pixels.
• Second: Merge the orbit maps (about 28 orbit maps/day) to the daily map by comparing the orbit maps and selecting the most nadir pixel.

The Figure 3.5 shows that these steps successfully avoids bad data at swath edge (with larger sensor zenith angle), especially for high latitudes. The top panel shows a VIIRS one day RGB color image (band 2, 2 and 1 for red, green and blue guns) composited from orbit maps. Percentage of gaps filled for a selected region is less than 40% for most of area (left bottom). The maximum sensor zenith angle becomes smaller when latitude increasing (right-bottom).
3.3.1.3 Daily map from VIIRS

VIIRS-VH requires the following 6 types of data: SVI01, SVI02 (reflectance of image band 1 and 2), SVI05 (temperature of image band 5), GITCO (geo-location file, including the data fields: latitude, longitude, solar and sensor zenith angles) and IICMO (cloud information). Each granule contains 1.4 minutes VIIRS observation. There are about 1014 granules per day. The minimum input VIIRS SDR granules data is about 1 TB.

Figure 3.6 shows the concept of algorithm of making VIIRS daily map.

![Making VIIRS Daily Map: Algorithm](image)

Figure 3-6 Concept of the algorithm of making VIIRS daily map.

3.3.2 Weekly Composite Map

Daily maps are aggregated to a seven-day composite map using Maximum Value Composite (MVC) method by saving data of the day with the largest NDVI. The MVC procedure is applied to each pixel. Once a day is derived, all associated variables of this pixel will be copied to the daily map. This ensures that all variables of a given pixel were observed at the same time. The compositing period starts from the first day of a year. The “week” number refers to the sequential 7-day number (“week 1” always covers the period from day 1 to 7 of a year). The VHP weekly composite map contains the same variables as the daily maps. It also contains data fields recording the selected day and the number of days with valid data. This information can be used for evaluation of data quality.

“ValidDaysForCH1”: the number of days with valid data of reflectance at visible band

“cell_jday”: the day of year of the selected pixel.
“packed_cloud_mask” contains the “packed cloud mask” information of selected pixel.

Figure 3.7 shows every day and the weekly composite NDVI images.

3.3.3 Calibration for reflectance

VIIRS has on board calibration; these parameters are available in the VIIRS SDR file as “reflectance_factors”. Reflectance of visible and near infrared are calculated as:

\[
\text{Reflectance} = \text{factor}[0] \times \text{SI} + \text{factor}[1]
\]

Where,

- factors are “reflectance_factors” with two elements (slope and intercept)
- SI is the “scaled integer” stored in VIIRS SDR files.

3.3.4 High frequency noise

Noise in AVHRR data creates fundamental constraints to the remote sensing of the Earth. The noise sources are physical, geometrical, mechanical, mapping, environmental, random etc; some of them long-term, some short-term and some both (Kogan et al 1996, Rao and Chen 1993, 1999, Cracknell 1997, Kidwell 1997). Currently, a complete physically based correction for all effects over various land surfaces, which is able to eliminate high, medium and low frequency noise, is not available (Kogan, 1995). High frequency noise created by clouds, variable transparency of the atmosphere (water vapor, dust, chemicals etc), surface
anisotropy, geometry of the sun and sensor, position of satellite, methods of data processing, random noise (including human errors) distort considerably reflectance/emission of both NDVI and BT creating difficulties for satellite data application.

3.3.5 Noise removal

The vegetation-oriented method for a comprehensive noise reduction stems from a statistical approximation of the vegetation and temperature annual time series. The three goals are pursued (a) single out the seasonal cycle; (b) suppress high frequency noise, and (c) enhance medium and low frequency variations related to large-scale and persistent weather fluctuations. This technique considers smoothing the weekly time series with a combination of a compound median filter and the least squares technique (Kogan et al. 1993). Numerous tests showed that this smoothing eliminated completely the high frequency outliers, including random, approximated accurately the annual NDVI and BT cycles, and, more importantly, singled out medium-to-low frequency weather-related fluctuations (valleys and hills in the NDVI and BT time series) during the annual cycle (Kogan, 1995).

Figure 3.8 shows the NDVI and smoothed NDVI derived from AVHRR and VIIRS. Time series smoothing technique successfully removed the noise in time series of NDVI. It also confirms that there is bias between NDVI from these two instruments.
3.3.6 Adjusting VIIRS data to AVHRR equivalent.

One of the most important parts of the VHP is development of indices approximated weather impact on vegetation condition or health. Since Suomi NPP VIIRS data are available for 1.5-year, the data aggregated are not sufficient for development of VIIRS climatology. Therefore, the algorithm considers using 34-year AVHRR climatology for VIIRS VH approximation. However there are some problems to address.

3.3.6.1 NDVI
Similar to AVHRR instrument, VIIRS has VIS, NIR and IR bands. However, VIIRS bands have different the central wave number and band width: VIIRS band NIR is narrow (similar to MODIS) and shifted to lower waves (Figure 3.9). As the result, NDVI derived from VIIRS usually is much higher than NDVI from AVHRR (Figure 3.10). Therefore, a proper scaling is required for using AVHRR climatology.

![Normalized spectral response functions of VIS and NIR bands](image)
Figure 3.10 shows correlation (R=0.944) between VIIRS and AVHRR no noise NDVI, some statistics and regression during 2012-2013. The correlation is very high, VIIRS NDVI is much higher than AVHRR and the linear relationship over 1.5-year period is quite stable. This suggests to use regression analysis to convert VIIRS NDVI can be adjusted to AVHRR climatology. Figure 3.12 shows the result of adjustment by linear regression.
Figure 3-11 Relationship between VIIRS/NDVI and AVHRR/NDVI

\[ Y = a + b \times X \]

- mean(a) = -0.0379579
- mean(b) = 0.702535

Ncomploc=4506572
CC = 0.9440
RMSE = 0.0450302

Data used: 2012 week 35 to 2013 week 34

lon=[-130.00, 180.00] lat=[-40.00, 40.00]
3.3.6.1 BT

Similar to NDVI analysis is shown for BT in Figure 3.13. VIIRS/BT and AVHRR/BT correlation is very high (0.946), linear relationship is stable over time, but there is slight bias between the two instruments’ BT. Currently we are determining if VIIRS/BT should be adjusted to AVHRR/BT climatology.
Figure 3-13  Normalized spectral response functions of thermal bands.

- VIIRS M15 is very close to AVHRR channel 4.
- VIIRS I5 is very broad, needs correction with band around 12 micrometers (M16) to correlate with AVHRR Channel 4.
Figure 3-14 Relationship between VIIRS/BT and AVHRR/BT.

Regression Coefficients

\[ Y = a + b \times X \]

- \( a = -8.31729 \)
- \( b = 1.03424 \)

- Mean \( a = -8.95758 \)
- Mean \( b = 1.03811 \)

- Mean CC = 0.948182
- Mean RMSE = 3.45461

Data used: 2012 week 36 to 2013 week 47

lon=[-180.00, 180.00] lat=[-40.00, 40.00]
Climatology (multi-year maximum, minimum, mean and standard deviation) of both NDVI and BT are critical for derivation of VH indices. The 4 km climatology developed from 30-year AVHRR and 10-year MODIS NDVI and BT.

The following algorithm was used:

- Remap MODIS NDVI from Sunisodual projection to geographic projection (Latitude-Longitude);
- Develop MODIS NDVI climatology in geographic projection from 10 years’ MODIS data.
- Develop data statistics and do correlation and regression analysis.
- Converted MODIS/NDVI climatology to AVHRR/NDVI.

Similar procedure was used development of BT climatology

Figure 3.16 compares the two versions of NDVI climatology for two locations. They are similar.
3.4 VIIRS-VH Algorithm Output

The outputs of VIIRS-VH system include:

1. Three vegetation indices (VCI, TCI, VHI) on 4km GG are stored in a NetCDF file. There is one accompanying data set for quality assurance (QA) stored in the same file. QA flags indicate if there are potential issues on VH products when VH indices are calculated normally.
2. Images of VCI, TCI, VHI in 16km resolution, stored in PNG file format. Desert or snow/ice areas are masked as grey color to indicate no meaningful retrieval of VH product.
3. Vegetation indices data in Geo-TIFF.
4. Metadata: Metadata will be saved as file attributes in each NetCDF file. They are also saved in META data file in XML format together with additional statistic information which is useful to monitor the VHP product data quality and processing status.

3.5 Performance Estimates

By using the climatology data and comprehensive digital filters, the VIIRS-VH system can produce weekly vegetation health indices from VIIRS SDR granules data globally (from 55° S to 75° N).
3.5.1 Test Data Sets
The AVHRR-VHP dataset will be used as test data if needed.

3.5.2 Numerical Computation Considerations
The whole algorithm is composed of many straightforward calculations. There is no special requirement on numerical computation.

3.5.3 Programming and Procedural Considerations
For VIIRS-VH, the input VIIRS SDR data are up to 1TB per day. The code must be efficiently to process data with appropriate latency:

- The software will divide the output data into multiple tiles.
- The software creates a list of input granules. Calculate the position of granules by reading only the four corner points. Find file name for each data type for a given granule; if files are duplicated, keep the one for the latest time.
- Calculating no noise NDVI and BT, update them for the last 8 weeks.

In real time mode: VIIRS-VH code will runs every day to create daily map and once per week to create weekly MVC composite and VH indices.

For VIIRS-VH system two executable will be developed by C++ code:

- “viirs_gvi.exe”
  produce daily map and weekly composite from VIIRS SDR granules

- “vh.exe”
  Produce ND, SM and VH files from weekly composite

3.5.4 Quality Assessment and Diagnostics
Unit testing and system testing will include quality assessment with historical in situ observations.

3.5.5 Exception Handling
The expected exceptions, and a description of how they are identified, trapped, and handled, will be provided in a future version of this document.
3.6 Sample Results

VHI from VIIRS

![VHI from VIIRS](image)

Winter 2013 week 1

Summer 2013 week 27

Figure 3-17 Vegetation Health maps produced by the VIIRS-VH algorithm

3.7 Validation

Validation of VIIRS-VP will be fulfilled by comparing with VHP product.

4 ASSUMPTIONS AND LIMITATIONS

4.1 Assumptions

- Vegetation changes slow over time without large jumps. No noise NDVI is changing similarly. Abnormal jumps in NDVI time series will be considered as noise and be removed.
• The time latency of the VIIRS-VH products is up to 6 hours after the end of each 7-day period. This time will be sufficient to process large amount of VIIRS SDR data.

4.2 Limitations

• The VIIRS-VH will calculate VH indices for all land including non vegetated areas. Such areas will be flagged.

• The VIIRS VH system will produce VH indices for the global land (55° S to 75° N).

5 RISKS

If VIIRS sensor or satellite fail, NOAA-19 will be used. If both sensor/satellite fail, it is possible to produce similar products from MetOp.

6 LIST OF REFERENCES


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