



Exploring algorithms for Meteosat-HIRS Inter-Calibration

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Contents

- HIRS v IASI as Inter-Calibration Reference
- Collocation criteria
- Spectral Convolution
 - Empirical Stepwise multiple regression
 - Manual Channel selection
 - Training dataset
 - Regression method
 - Model Errors
- Spatial Convolution
- Regression
- (Results)
- Conclusions



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Use of HIRS v IASI as a Reference

Meteosat Geostationary Imager

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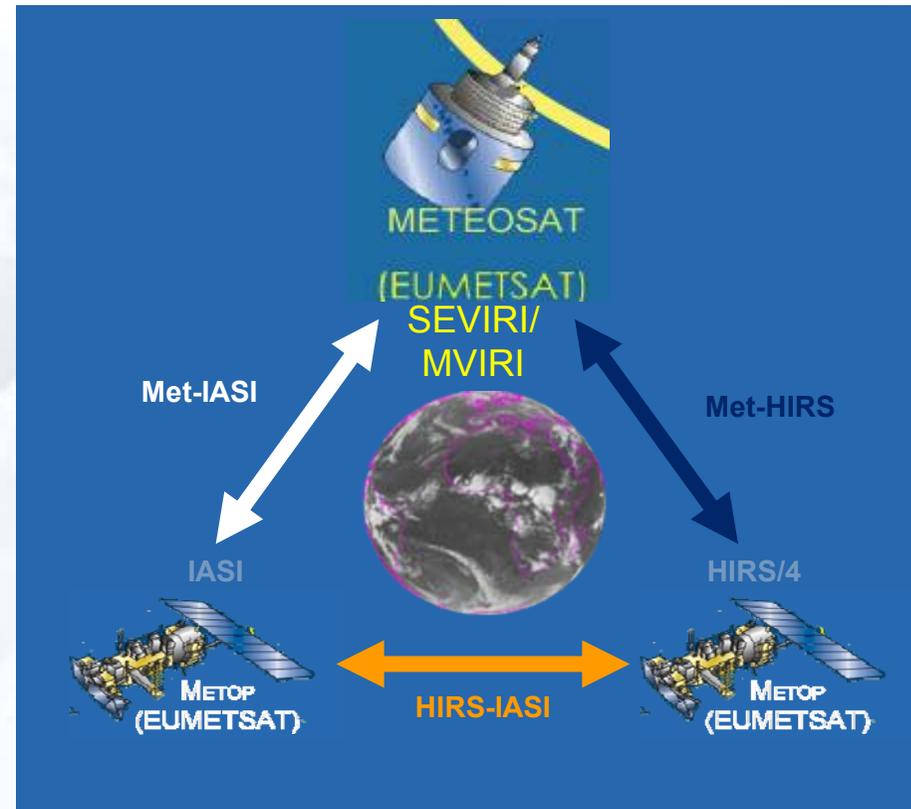
High-resolution InfraRed Sounder, HRIS, on Metop polar-orbiting satellite

Benefits of HIRS as reference:

- Established instrument
 - Operated by NOAA since 1970s
 - Used in climate records
 - Potential reference for archive data
- Includes on-board calibration
- On same platform as IASI
 - Well characterised against IASI
 - Can close inter-calibration triangle

Can cross-check with AIRS and other HIRSs:

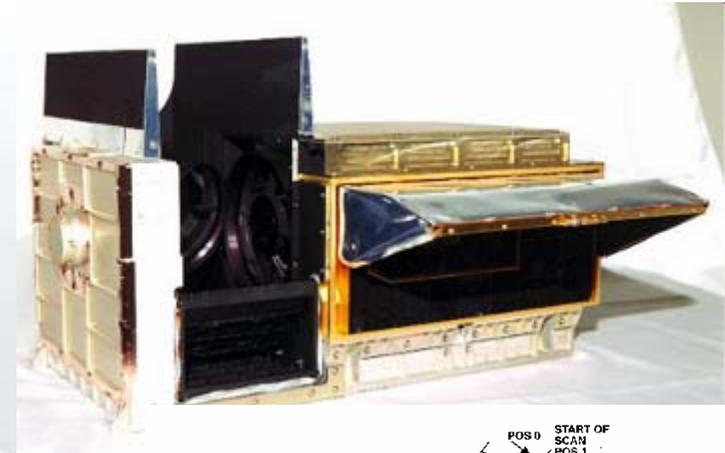
- **Simultaneous Nadir Overpasses: SNOs**
- Inter-calibrating Meteosat-AIRS



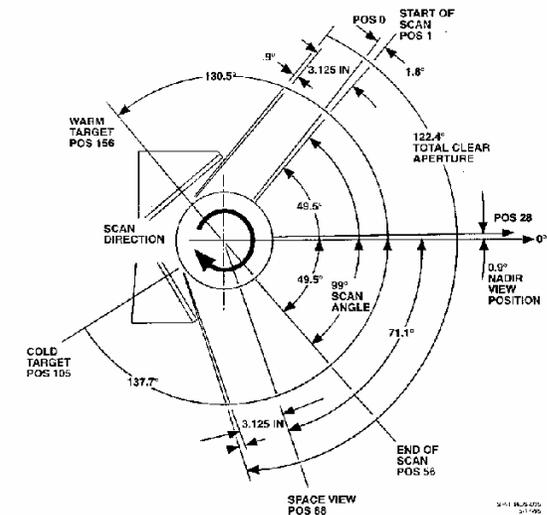


Introduction to Metop/HIRS/4

High-resolution Infrared Radiation Sounder on Metop/A in Sun-synchronous polar-orbit



19 Infrared Channels	3.8 – 15 μm
IFOV size at Nadir	10km (20km on HIRS/3)
Sampling at Nadir	26 km
Scan Rate	6.4 sec
Swath	$\pm 49.5^\circ / 56$ pixels (± 1092 km)
Blackbody cal.	Every 256 sec

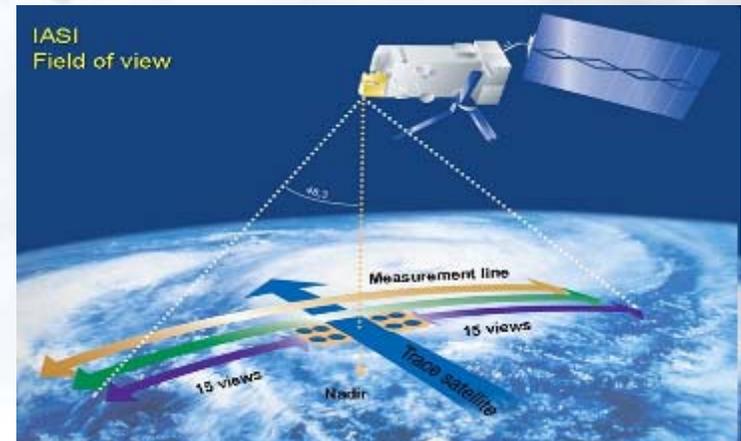
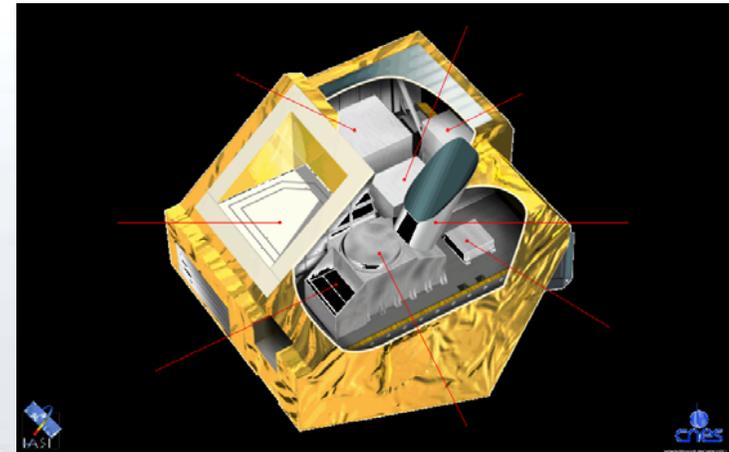




Introduction to Metop/IASI

Infrared Atmospheric Sounding Interferometer
on Metop/A in Sun-synchronous polar-orbit

Spectral Range	645-2760 cm^{-1} (3-15 μm)
Spectral Sampling	0.25 cm^{-1}
IFOV size at Nadir	12 km
Sampling at Nadir	18 km
Scan Rate	8 sec
Swath	$\pm 48.98^\circ$ (± 1066 km)





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Data Processing Chain

1. Collocation

- Finding observations coincident in space and time

2. Transformation

- To allow direct comparison
- Spatial averaging
- Spectral averaging

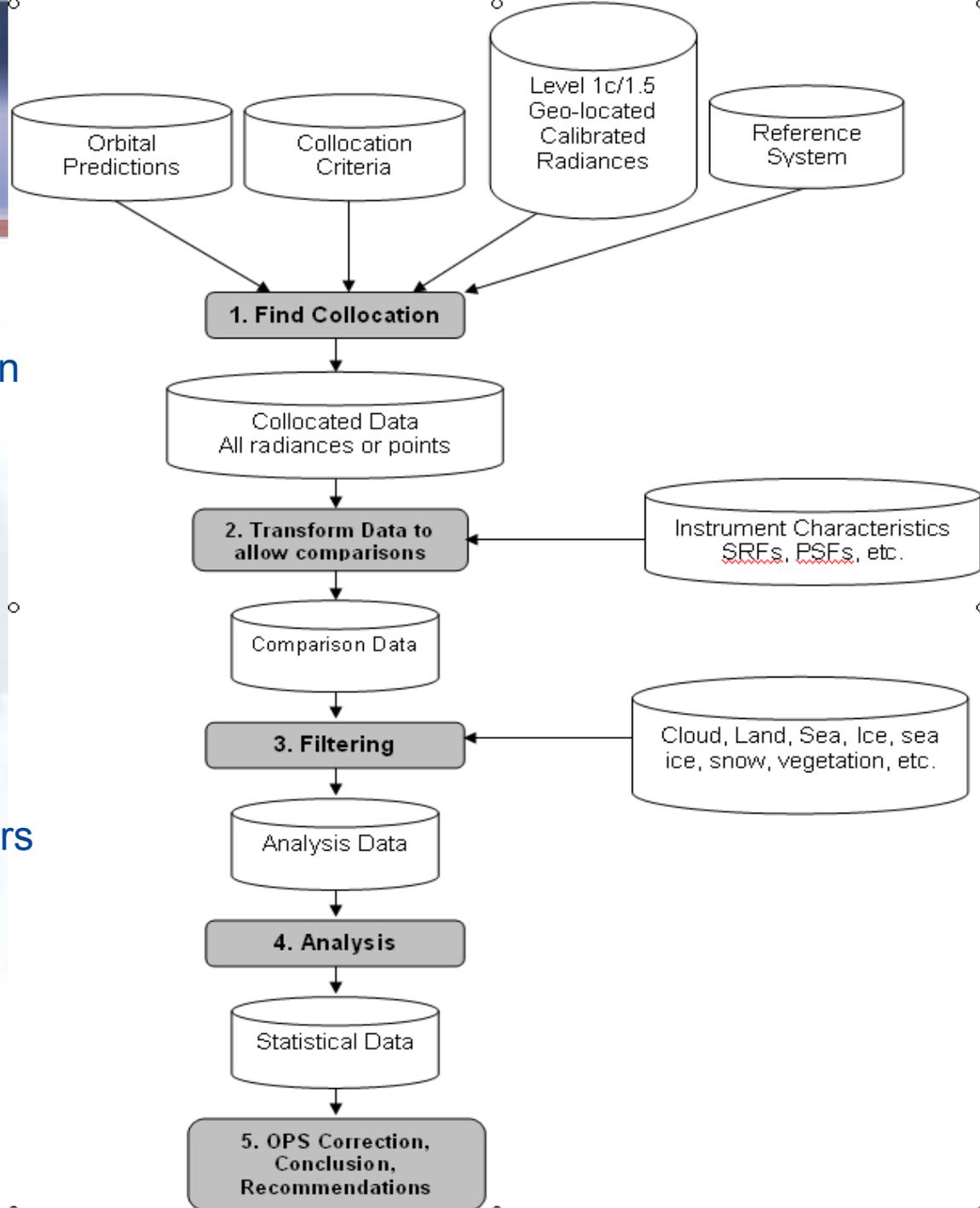
3. Filtering

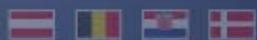
- Selecting scenes of interest
- Reducing noise & rejecting outliers

4. Analysis

- Comparing observations
- Calculating biases and errors

5. Developing corrections





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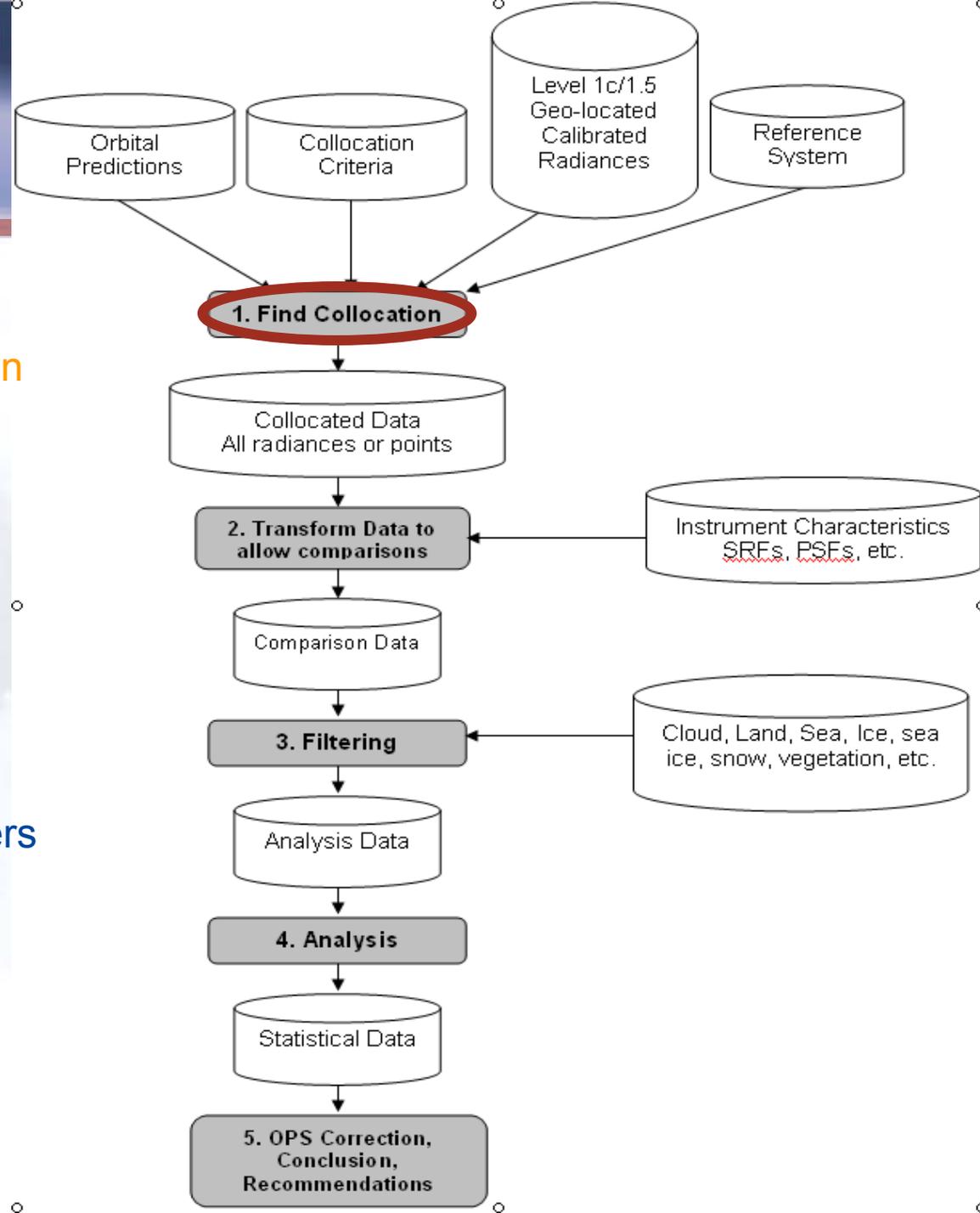
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Collocation Criteria

Simultaneous near-Nadir Overpasses

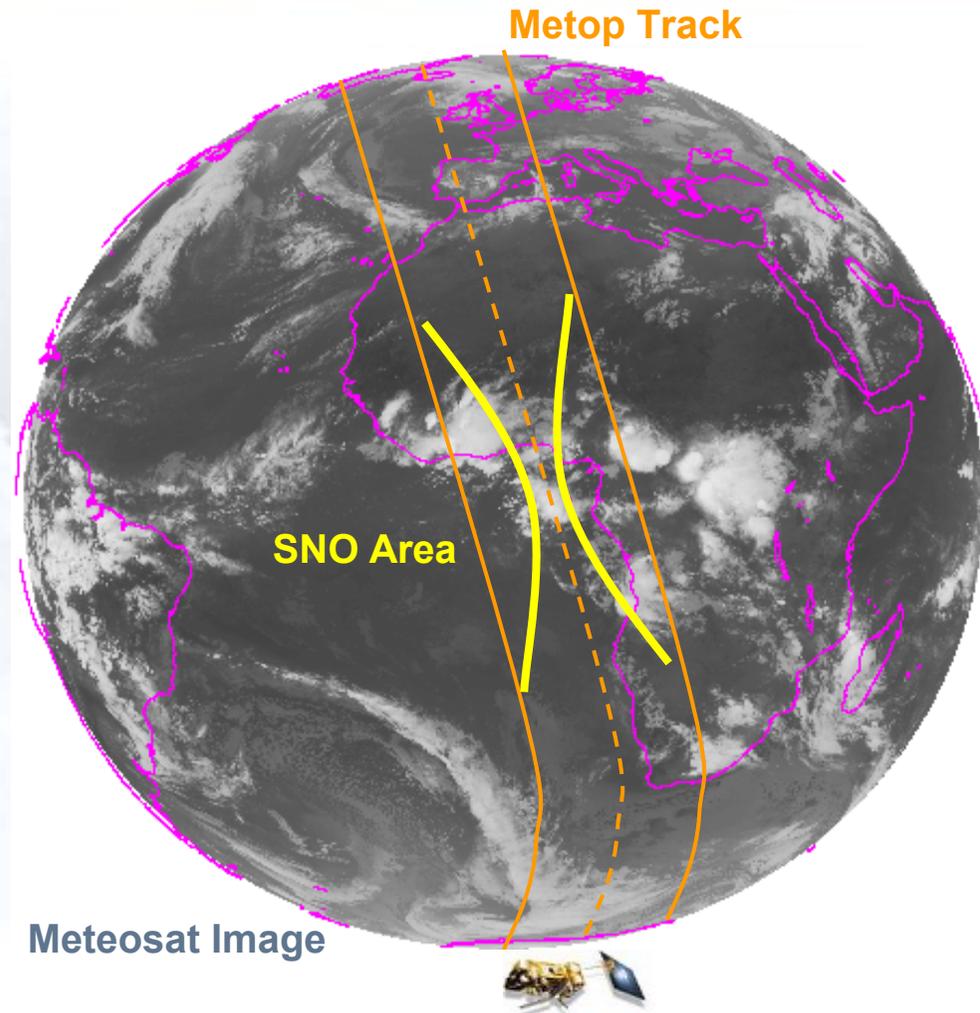
of Meteosat and Metop

- Only night-time data
- $\Delta Lat < 35^\circ$, $\Delta Lon < 35^\circ$ of SSP
- $\Delta t < 15$ mins (=scan period)
- $\Delta \theta < 1\%$ (Atmospheric path diff.)
- 3x3 MSG pixels / HIRS/4 iFoV

Restricts collocations to Tropics

~1 orbit/day

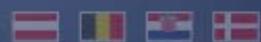
~200 good collocations?





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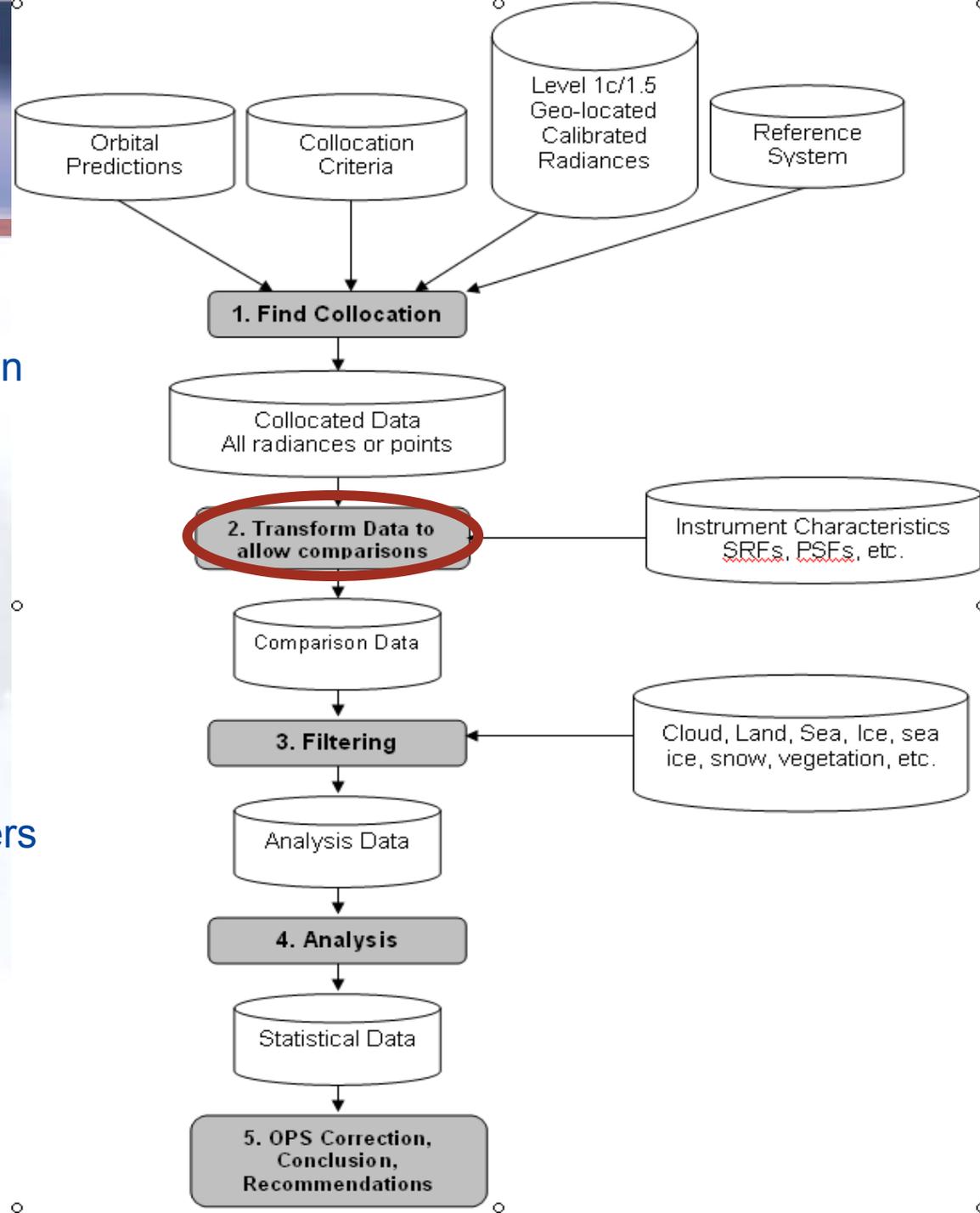
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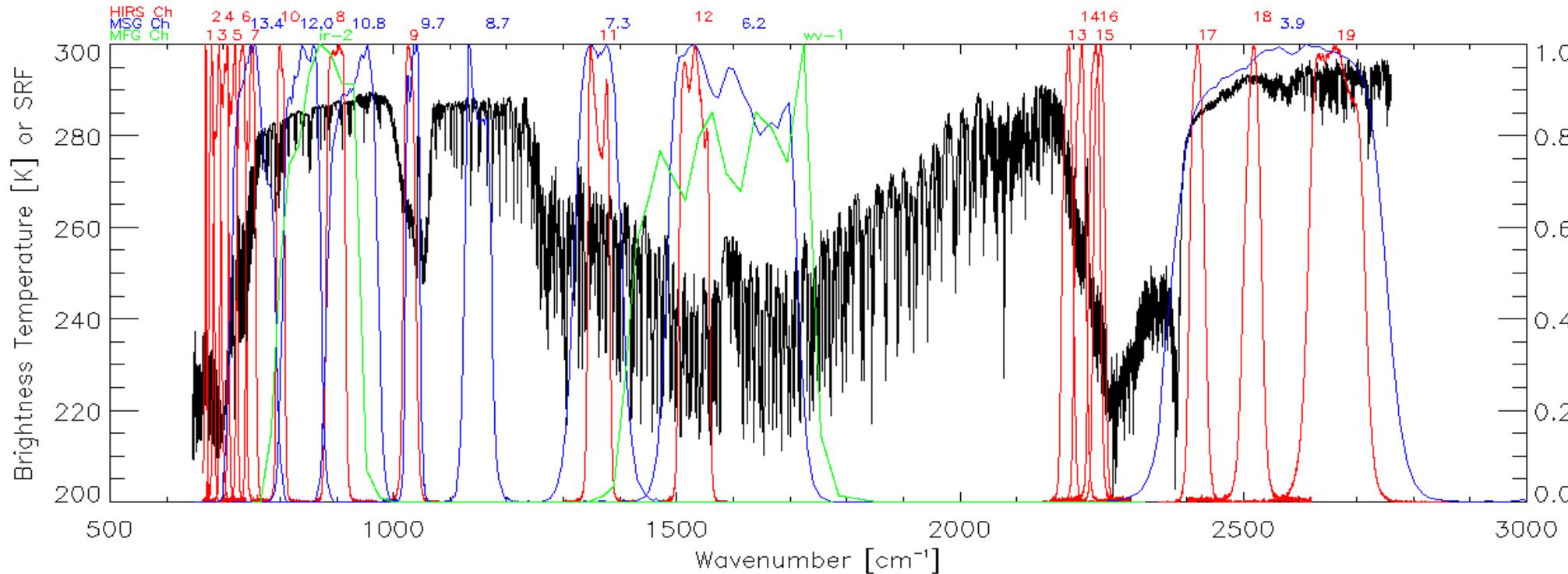
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IASI T_b Spectrum + HIRS SRFs + MSG SRFs + MTP SRFs



IASI T_b Spectrum – Covers all HIRS IR channels

HIRS SRFs

MTP SRFs – WV Channel ~ HIRS Ch12, IR Channel ~ HIRS Ch8

MSG SRFs – 7.3 & 8.7 μ m Channels not covered by HIRS

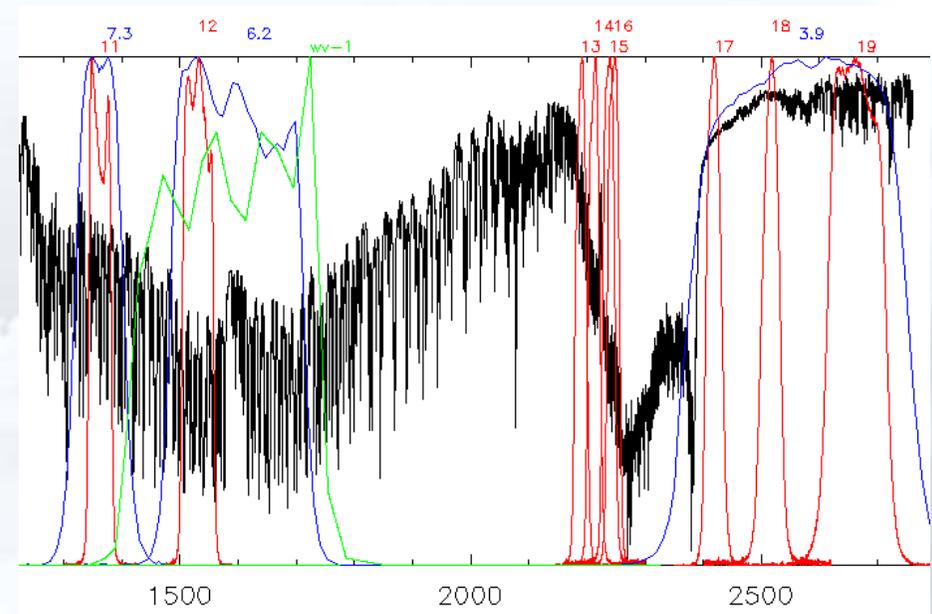
Single Ch for 10.8/12.0 μ m

3.9 μ m Ch covered by HIRS Ch17+18+19



Accounting for SRF Differences

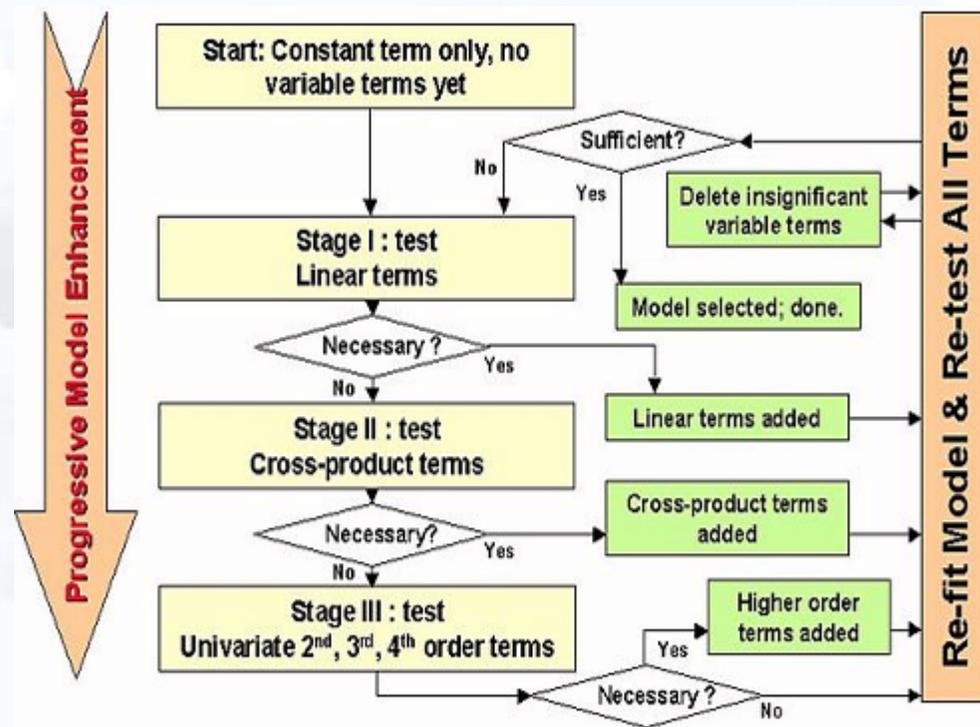
- Meteosat and HIRS have different SRFs
 - Would introduce errors into direct comparisons of radiance
- Need to 'correct' HIRS radiances
 - to account for spectral differences
- And/or combine HIRS channels
 - with different weights
- Use Radiative Transfer Model (RTM)
 - to generate synthetic radiances
 - for Meteosat & HIRS
- Calculate coefficients by regression
 - and uncertainty introduced
 - compare this uncertainty with variability





Stepwise Regression to Select Channels

- Attempted Stepwise Regression
 - to select channels match-ups
 - and estimate relative weights of each HIRS channel to simulate each Meteosat channel
 - Completely empirically
 - Results are obviously nonsense!
 - e.g. MSG 3.9 μ m channel fitted HIRS Ch18,13,5 & 11 (not 17&19)
 - Some HIRS channels can be given negative weights
- However, stepwise regression may be a useful tool to analyse results
 - e.g. dependence of bias on scan angle, latitude, time of day, phase of moon, etc.





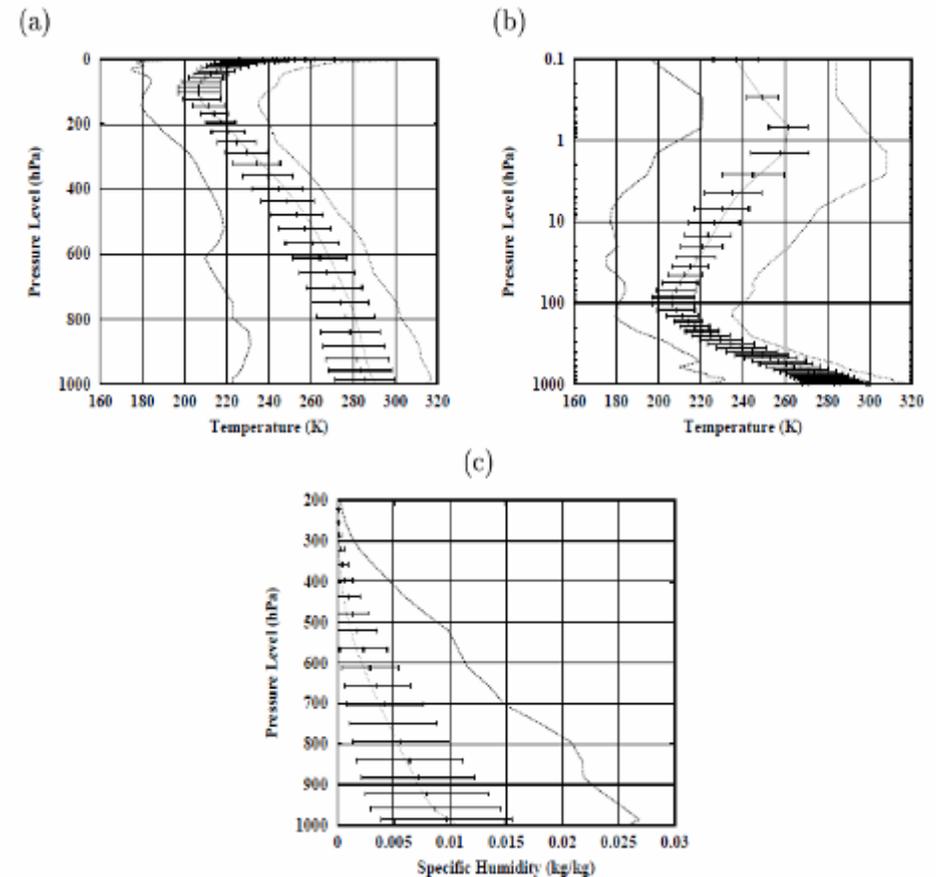
Selecting Channels for Comparison 'Manually'

MTP MVIRI	x	WV	x	x	x	IR	x	x
HIRS	x	Ch12	x	x	x	Ch8	x	x
MSG SEVIRI	3.9 μ m	6.2 μ m	7.3 μ m	8.7 μ m	9.7 μ m	10.8 μ m	12.0 μ m	13.4 μ m
HIRS	Ch17 Ch18 Ch19	Ch12	Ch11	N/A	Ch9	Ch8	Ch8	Ch7



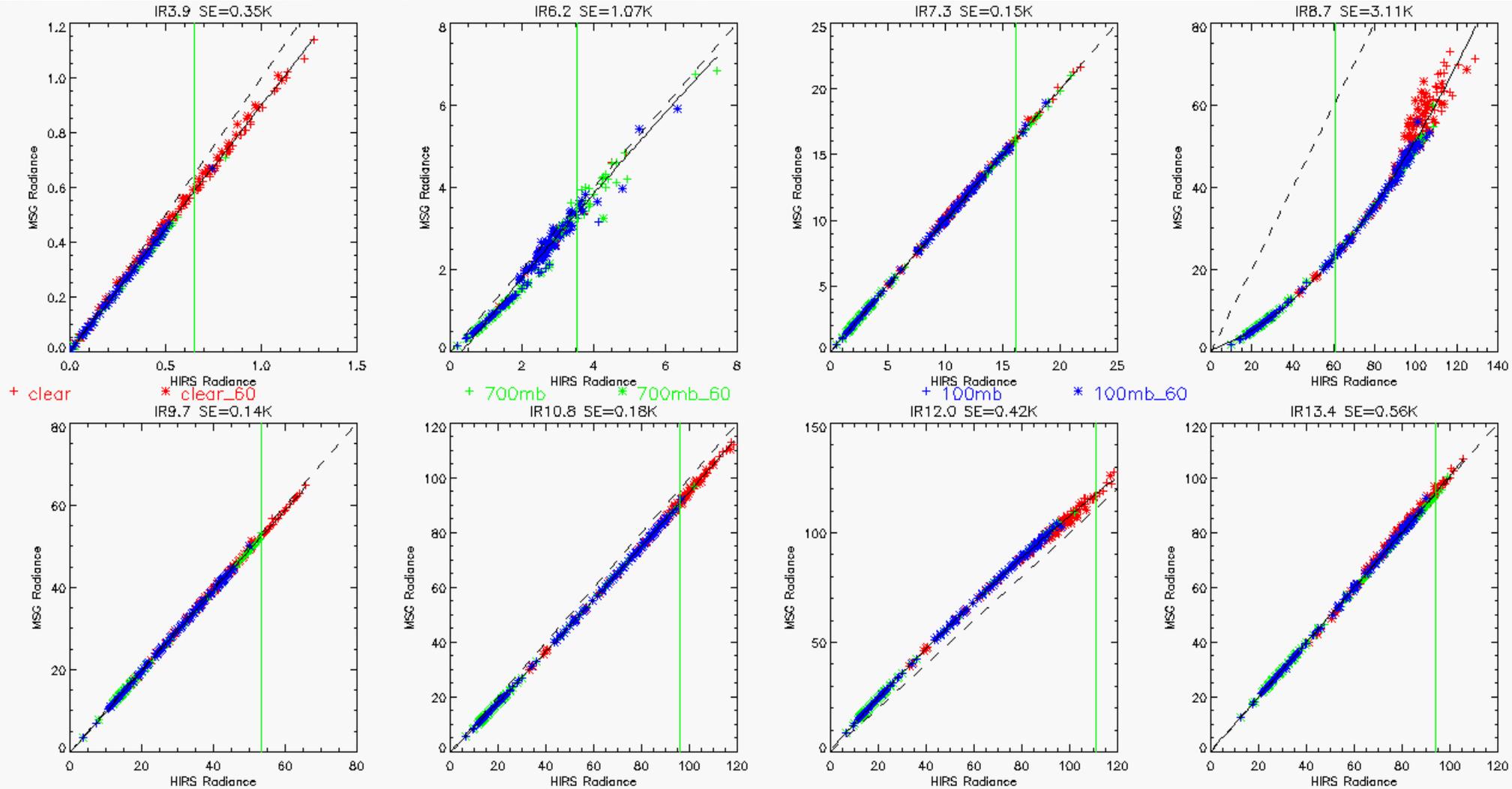
Training Dataset to Calculate Correction Coeff.s

- RTTOV-9 Radiative Transfer Model
- Diverse 52 profiles at 60 levels
 - From ECMWF (Chevallier'01)
 - Temperature, Water Vapour and Ozone
 - Covers global range
 - Represents natural variability
- Duplicate profile set:
 - 1 set for clear sky
 - 1 set with mid-level cloud (700hPa)
 - 1 set with high cloud (100hPa)
- Run RTM twice at incidence angles:
 - Zenith
 - 60°



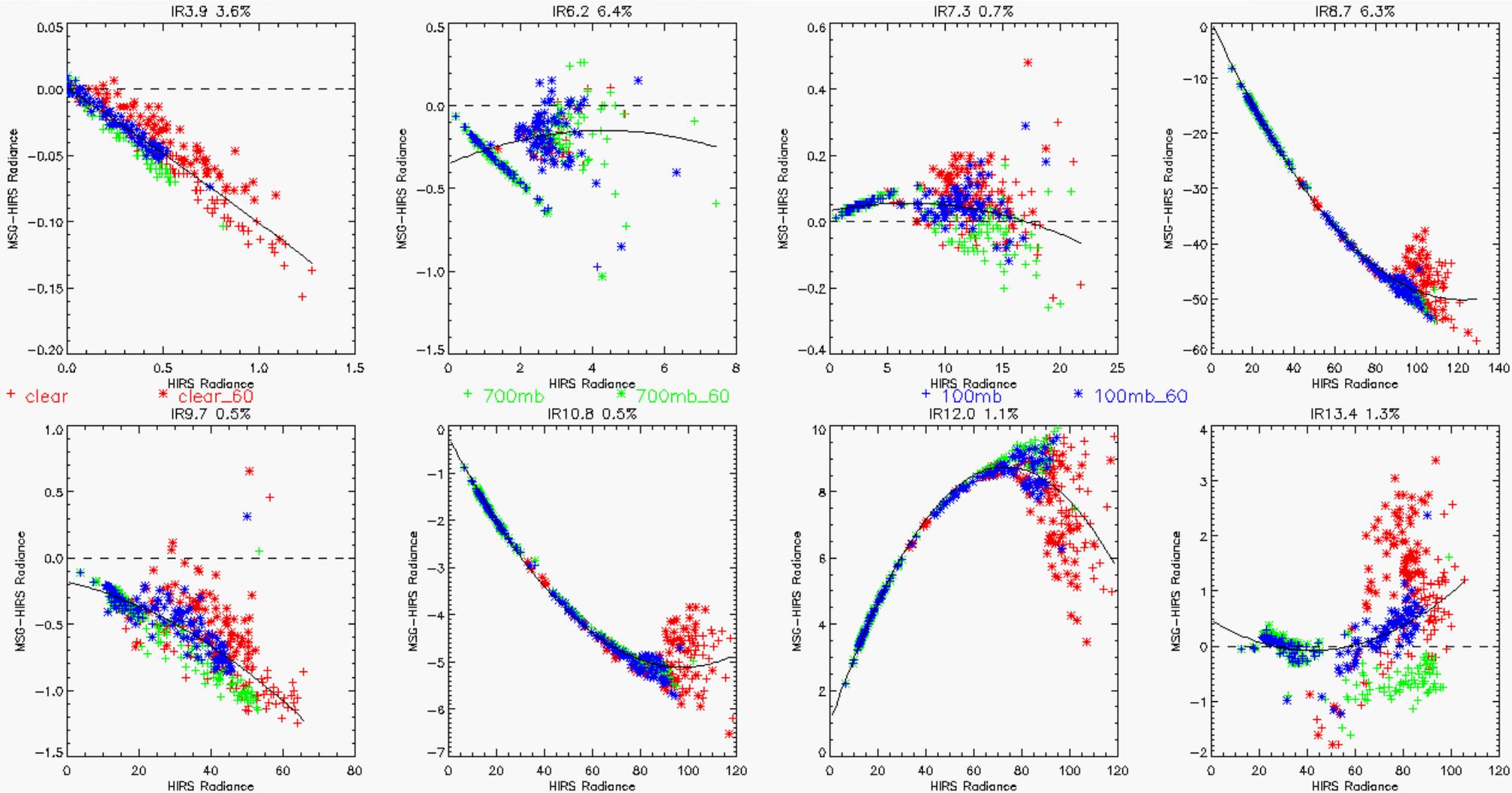


Quadratic Regression





Quadratic Regression - residuals





Regression Results

- Quadratic Regression gives better fit for IR10.8 and IR12.0
- IR6.2 show large scatter in clear sky (also IR3.9 in cloud)
 - IR6.2: Systematic difference between nadir and 60° views (WFs)
- IR8.7 doesn't match any HIRS channel – nonsense results
- Largest scatter in clear sky cases (most spectral information)
- Could improve fit by excluding arctic data
- Should validate using independent test dataset
- Should calc uncertainty at L_{ref} using coefficients full covariance
- Noise < Model Error < \sim Variability on single collocation
 - But, correlation in model errors between collocated pixels...



Compare Model Error with Variability

- Variability for 8 IR channels of MSG

- $RMSD_t(\Delta t=15\text{min})$

- $RMSD_x(\Delta x=10\text{km})$

- $\approx RMSD_y(\Delta y=10\text{km})$

- Reduced by $\sqrt{n_{col}}$ e.g. $n_{col}=100$

- Model error \gg Variability for

- IR6.2 (different weighting functions)

- IR8.7 (no HIRS equivalent)

- Model error \sim Variability

- for other SEVIRI channels

- Expect increased noise on inter-calibration results by $\sim\sqrt{2}$

MSG SEVIRI Channel [μm]	Temporal Variability $RMSD_t$ ($\Delta t=15\text{min}$) $/\sqrt{100}$ [K]	Spatial Variability $RMSD_x$ ($\Delta x=10\text{km}$) $/\sqrt{100}$ [K]	MSG-HIRS Modelling Error [K]
3.9	0.30	0.25	0.35
6.2	0.08	0.12	1.07
7.3	0.17	0.22	0.15
8.7	0.32	0.40	3.11
9.7	0.19	0.30	0.14
10.8	0.35	0.40	0.18
12.0	0.36	0.40	0.42
13.4	0.25	0.30	0.56

Temporal and Spatial Variability of Meteosat brightness temperatures on scales of 15 min and 10 km, respectively, compared with MSG-HIRS modelling error.



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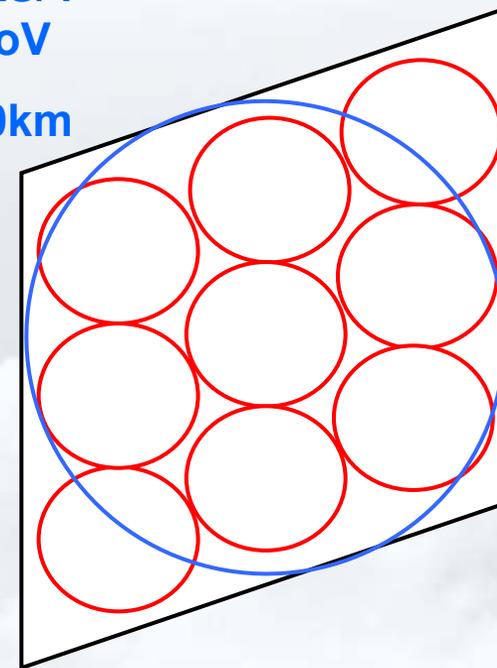
Spatial Averaging

Average Meteosat pixels
within each HIRS iFoV

Estimate uncertainty
due to spatial variability
as Standard Deviation of
Meteosat pixels

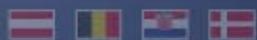
Use in weighted regression

HIRS/4
iFoV
~10km



Meteosat
pixels

3x3 MSG



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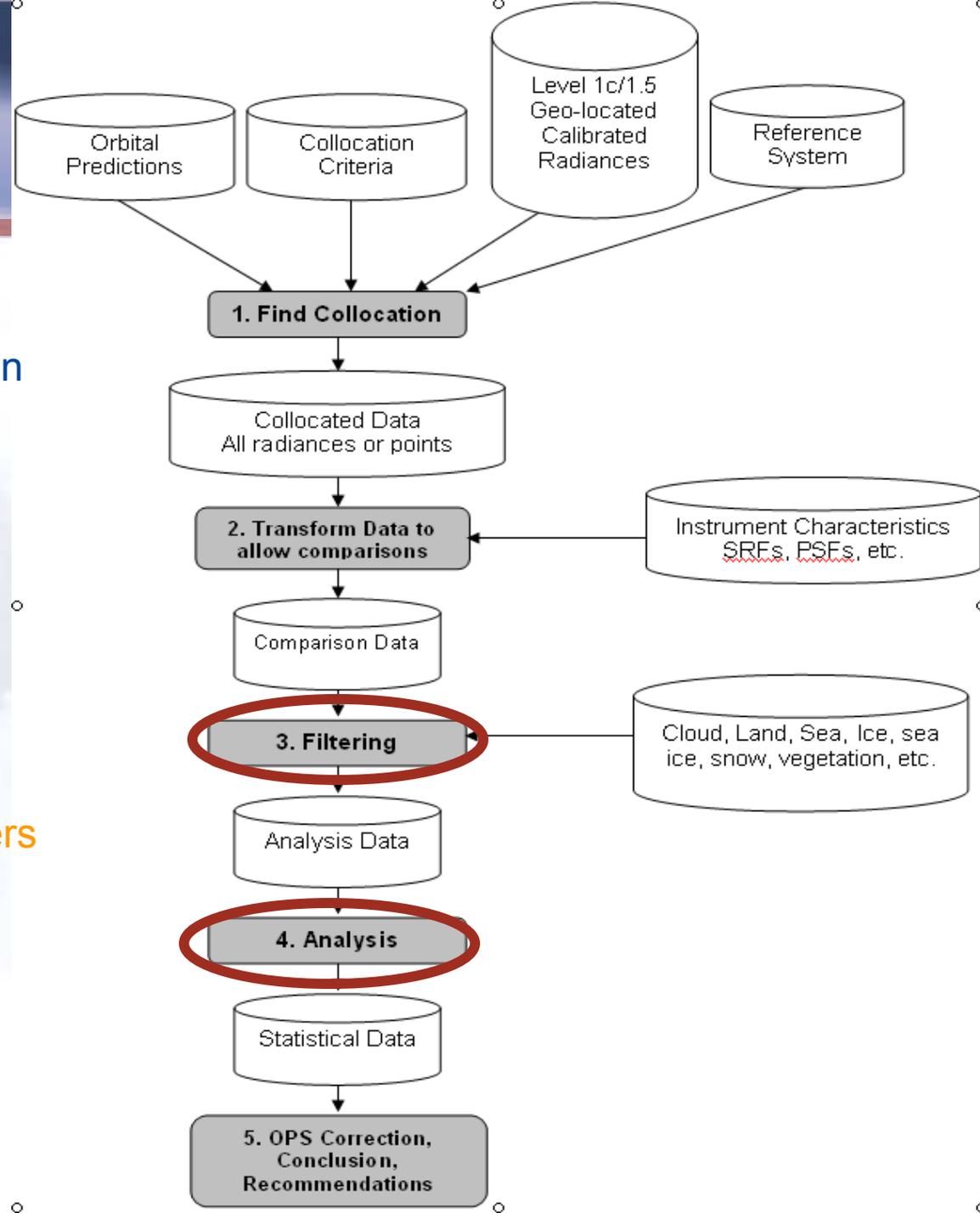
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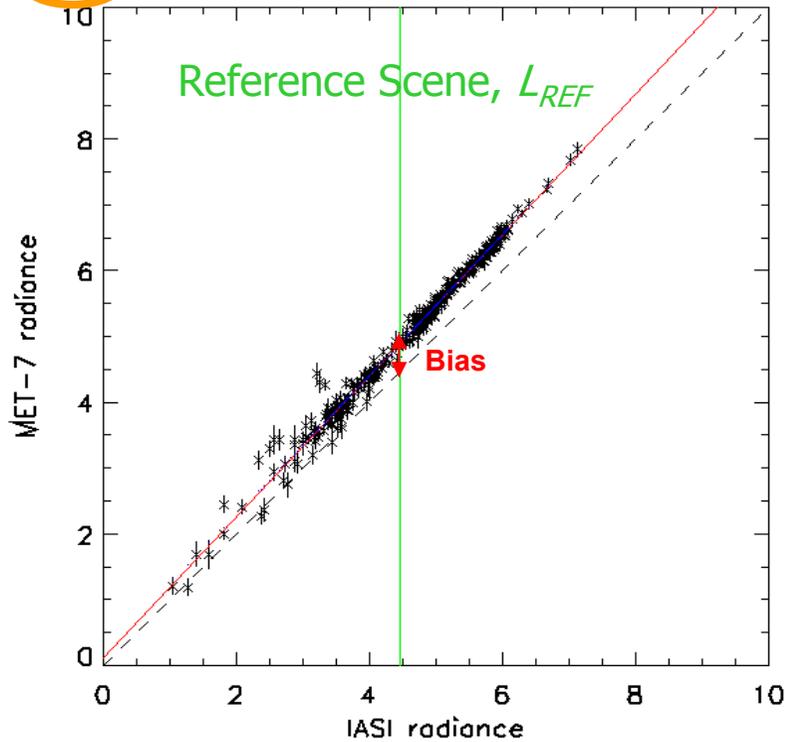
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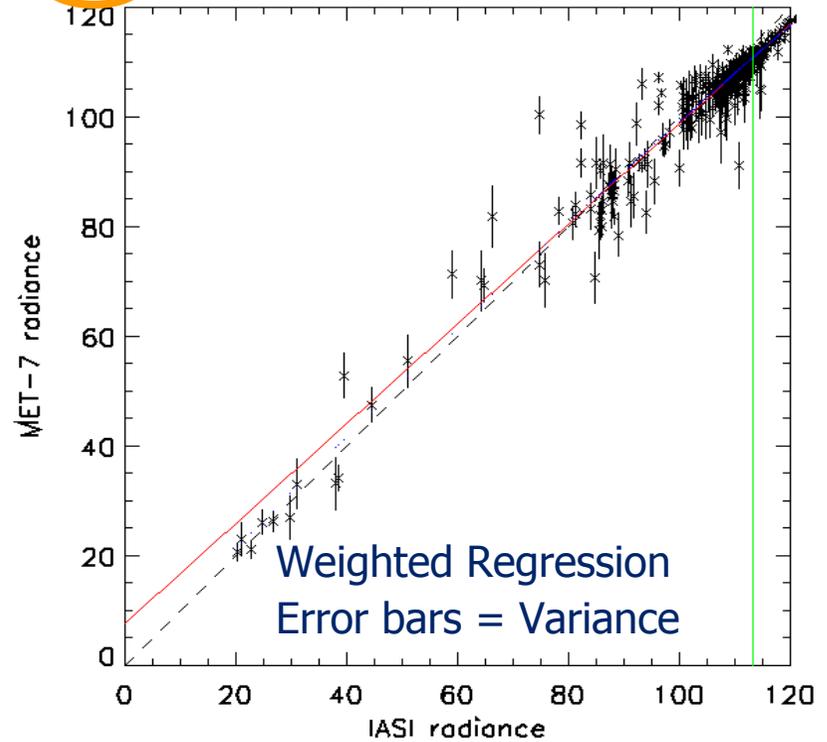
Regression

Offset $\neq 0$ Slope $\neq 1$ \Rightarrow Difference is scene-dependent

wv-1: $\sigma = 0.125 \pm 0.017$ $b = 1.0703 \pm 0.0033$



ir-2: $\sigma = 7.682 \pm 0.584$ $b = 0.9108 \pm 0.0052$

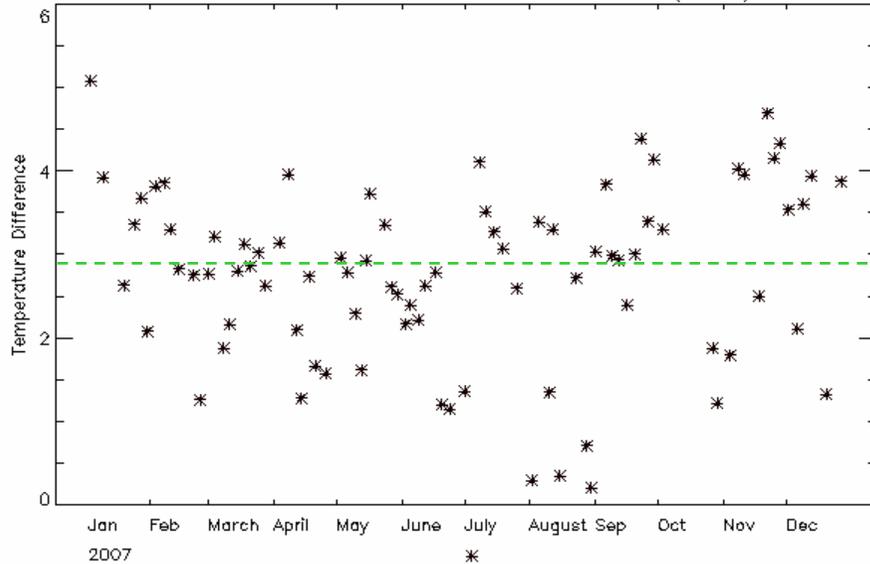


Reference Scene
defined as modal value
(typical clear sky radiance)

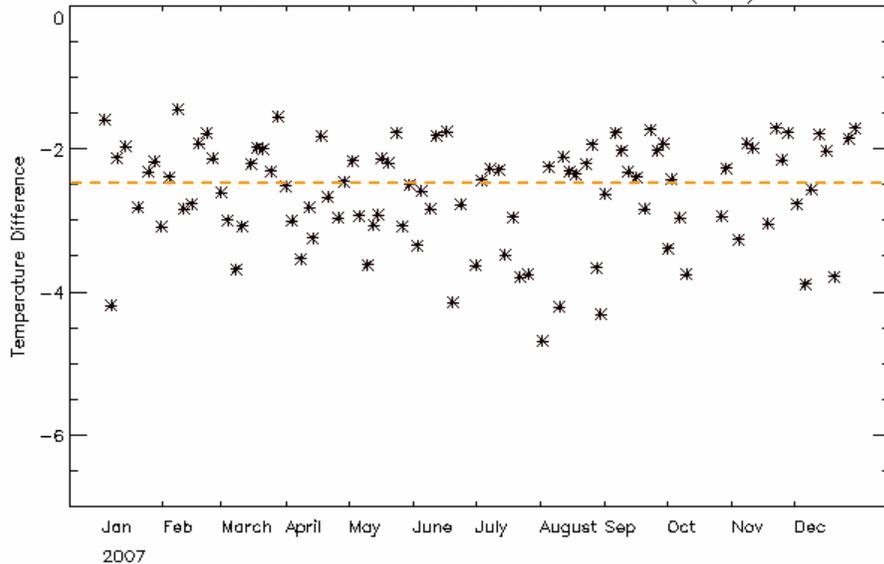


Meteosat-7 – HIRS Inter-Comparisons (not GSICs!)

METEOSAT-7 WV CHANNEL VS NOAA-16 HIRS(Ch.10)



METEOSAT-7 IR CHANNEL VS NOAA-16 HIRS(Ch.8)



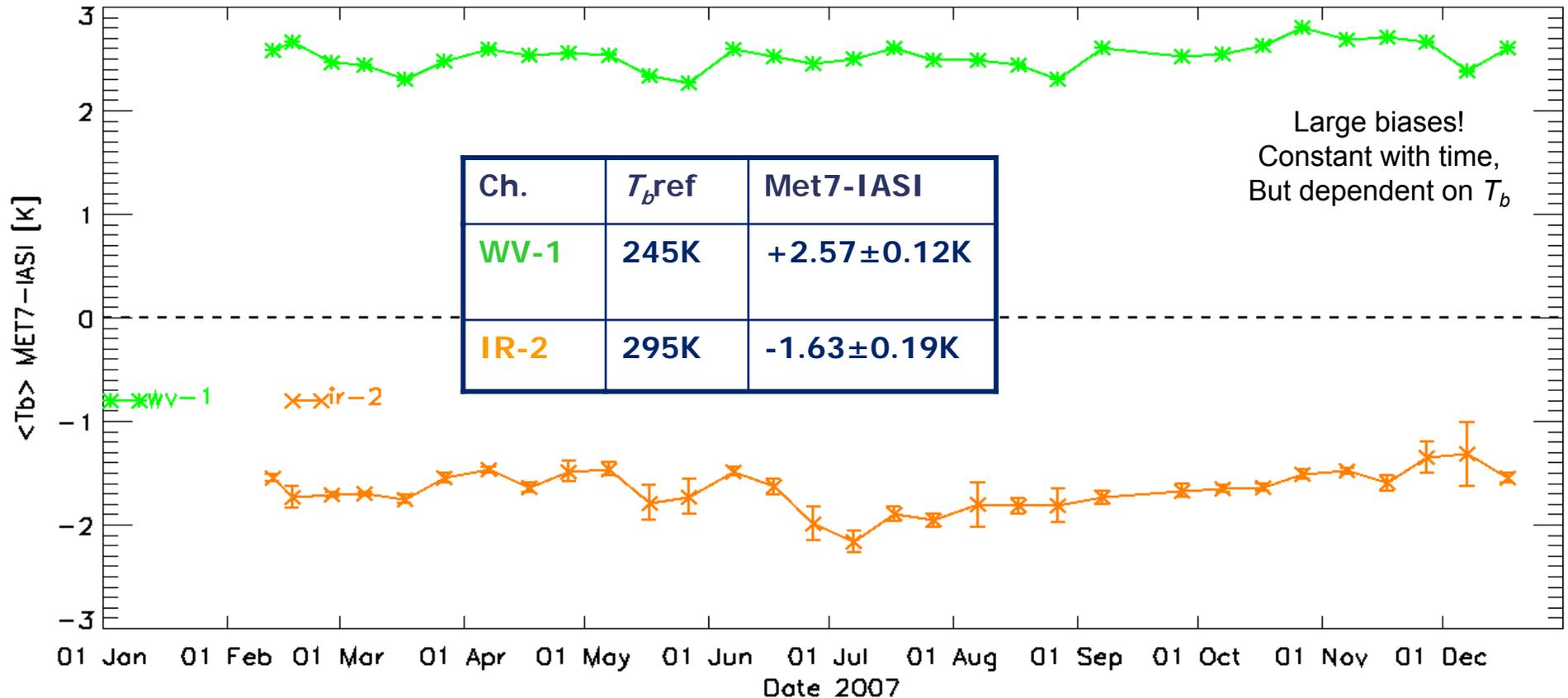
- Comparisons of Met-7 – HIRS
 - Processed operationally at EUMETSAT
 - used to check Met-7 calibration
- Needs to account for different SRFs
 - Increases uncertainty

- Noisy, but stable
- WV: $+2.8 \pm 1.0$ K
- IR : -2.5 ± 0.6 K

- Biases similar to Met-7 – IASI
- Variances much larger



MVIRI on Meteosat-7 – IASI on Metop-A



Time series of **brightness temperature differences** between Met7-IASI for typical clear-sky radiances: Each Met7 infrared channel is shown in a different color, with different symbols, following the legend. Error bars represent statistical uncertainty on each mean bias (may be very small).



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Conclusions

- Can use HIRS as inter-calibration reference for Meteosat
 - (instead of IASI)
- Need to account for spectral differences
 - Transform HIRS observations to Meteosat-space
 - Using coefficients derived from regression of modelled radiances
 - Based on RTTOV + data set of diverse profiles + cloud
 - Not possible for IR8.7
 - Noisy for IR6.2
 - Introduces error in inter-calibration ~ Variability (for ~100 collocations)
 - “Closing the triangle”: $\langle \text{MSG-IASI} \rangle \neq \langle \text{MSG-HIRS} \rangle - \langle \text{HIRS-IASI} \rangle$
- EUMETSAT plan to implement prototype in 2009



Thank you

Questions and Answers