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# Suomi-National Polar Orbiting Partnership (NPP) Calibration and Validation

The Suomi NPP (SNPP) satellite was launched successfully on October 28, 2011 and is a pathfinder for the future US Joint Polar Satellite System (JPSS) operational satellite series. The primary objectives of the SNPP mission are to continue the Earth system observations initiated by the Earth Observing System Terra, Aqua, and Aura missions and to prepare the operational forecasting community with pre-operational risk reduction, demonstration, and validation for selected JPSS instruments and ground processing data systems. The SNPP satellite is now flying with the following five instruments: (1) Visible/Infrared Imager/Radiometer Suite (VIIRS) has multiband imaging capabilities to support the acquisition of highresolution atmospheric imagery and generation of a variety of applied products including visible and infrared imaging of hurricanes and detection of fires, smoke, and atmospheric aerosols. (2) Cross-track Infrared Sounder (CrIS) is the first in a series of advanced operational sounders that provide more accurate, detailed atmospheric temperature and moisture observations for weather and climate applications. (3) Advanced Technology Microwave Sounder (ATMS) operates in conjunction with the CrIS to profile atmospheric temperature and moisture. The higher (spatial, temporal and spectral) resolution and more accurate sounding data of CrIS and ATMS support continuing advances in data assimilation systems and NWP models to improve short- to medium-range weather prediction. (4) Ozone Mapping and Profiler Suite (OMPS) measures the concentration of ozone in the atmosphere, providing information on how ozone concentration varies with altitude. Data from OMPS continue three decades of measurements of this important climate variable. The OMPS measurements also fulfill the U.S. treaty obligation to monitor global ozone concentrations with no gaps in coverage. (5) Cloud and Earth Radiant Energy System (CERES) seeks to develop and improve weather and models prediction, and to provide measurements of the space and time distribution of the Earth's Radiation Budget components. The observations from CERES are essential to understanding the effect of clouds on the earth's energy balance (energy coming in from the sun and radiating out from the earth), which is one of the largest sources of uncertainty in our modeling of the climate.

The SNPP instruments are now undergoing a period of intensive calval and the instrument on-orbit performances are stable and the post-launch results all meet or exceed the specifications (Figure 1 and Table 1). NOAA is in charge of calibration of four instruments: ATMS, CrIS, VIIRS and OMPS. The CrIS. ATMS and VIIRS Sensor Data Record (SDR) products have reached the provisional level at which order the data from users can NOAA (http://www.class.ngdc.noaa.gov/saa/products/welcome;jsessi onid=CAA653564B301391746505E0E3E6EBB0) and perform in-depth scientific research. Also, ATMS data have been operationally assimilated into global and regional forecast models, and a suite of Environmental Data Record (EDR) products is generated by the NPP ground system and NOAA processing system. The OMPS instrument performance is excellent and the provisional status of OMPS SDR products from the SNPP Interface Data Processing Segment (IDPS) is expected in spring 2013.



**Figure 1**. Top: ATMS Noise Equivalent Differential Temperature (NEDT) in comparison with AMSU-A/MHS. The ATMS channel number is indicated on the x-axis and the AMSU channel number is indicated in the figure in blue (Weng *et al.*, 2012). Bottom: CrIS Noise Equivalent Differential Radiance (NEDN) as a function of wave-number and Field of View (FOV).

			Specification							Prelunch	On Orbit		
		Band No.	Driving EDR(s)	Spectral Range (um)	Horiz Sample (track Nadir	interval (km) x Scan) End of Scan	Band Gain	Ltyp or Ttyp (Spec)	Lmax or Tmax	Spec SNR or NEdT (K)	Measured SNR or NEdT (K)	Measured SNR or NEdT (K)	Uncertainty
			Ocean Color				High	44.9	135	352	616.8	583	5
		M1	Aerosol	0.402 - 0.422	0.742 - 0.259	1.60 x 1.58	Low	155	615	316	1092	1009	35
	VisNIR	M2	Ocean Color Aerosol	0.436 - 0.454	0.742 - 0.259	1.60 × 1.58	High	40	127	380	622.4	568	4
							Low	146	687	409	1118	992	17
		MR	Ocean Color	0.478 - 0.498	0.742 - 0.259	1.60 × 1.58	High	32	107	416	690	619	8
		ma	Aerosol				Low	123	702	414	1111	995	7
		MA	Ocean Color	0.545 -0.565	0.742 - 0.259	1.60 × 1.58	High	21	78	362	581.1	528	6
			Aerosol				Low	90	667	315	963.2	851	5
ър Б		11	Imagery EDR	0.600 - 0.680	0.371 - 0.387	0.80 x 0.789	Single	22	718	119	240.7	214	1
2		MS	Ocean Color Aerosol	0.662 - 0.682	0.742 - 0.259	1.60 x 1.58	High	10	59	242	366.6	328	7
ų,		ma					Low	68	651	360	827.9	652	21
2		M6	Atmosph. Correct.	0.739 - 0.754	0.742 - 0.776	1.60 x 1.58	Single	9.6	41	199	415.2	361	6
8		12	NDVI	0.846 - 0.885	0.371 - 0.387	0.80 x 0.789	Single	25	349	150	304.1	257	6
		M7	Ocean Color	lor 0.846 - 0.885	0.742 - 0.259	1.60 × 1.58	High	6.4	29	215	519.8	446	11
			Aerosol				Low	33.4	349	340	845.6	633	2
	S/WMIR	M8	<b>Cloud Particle Size</b>	1.230 - 1.250	0.742 x 0.776	1.60 x 1.58	Single	5.4	165	74	273	227	6
		M9	Cirrius/Cloud Cover	1.371 - 1.386	0.742 x 0.776	1.60 x 1.58	Single	6	77.1	83	253	229	2
		13	Binary Snow Map	1.580 - 1.640	0.371 × 0.387	0.80 x 0.789	Single	7.3	72.5	6	172	149	0
		M10	Snow Fraction	1.580 - 1.640	0.742 x 0.776	1.60 × 1.58	Single	7.3	71.2	342	714	568	18
		M11	Clouds	2.225 - 2.275	0.742 x 0.776	1.60 x 1.58	Single	0.12	31.8	10	25	22	0.1
		- 14	Imagery Clouds	3.550 - 3.930	0.371 x 0.387	0.80 x 0.789	Single	270	353	2.5	0.4	0.4	0
		M12	SST	3.660 - 3.840	0.742 x 0.776	1.60 x 1.58	Single	270	353	0.396	0.13	0.13	0
ą.		M13	SST	3 973 - 4 128	0.742 x 0.259	1.60 x 1.58	High	300	343	0.107	0.04	0.04	0.001
ā			Fires		0.102 × 0.255		Low	380	634	0.423			
.e													
niss		M14	Cloud Top Properties	8.400 - 8.700	0.742 x 0.776	1.60 x 1.58	Single	270	336	0.091	0.06	0.055	0.005
5	LWIR	M15	SST	10.263 - 11.263	0.742 x 0.776	1.60 x 1.58	Single	300	343	0.07	0.03	0.03	0
		15	Cloud Imagery	10.500 - 12.400	0.371 × 0.387	0.80 × 0.789	Single	210	340	1.5	0.4	0.4	0
		M16	SST	11.538 - 12.488	0.742 x 0.776	1.60 x 1.58	Single	300	340	0.072	0.04	0.03	0

Table 1. VIIRS performance met the specification. Signal to noise ratio is used for the reflective spectral band and NEDT is used for the thermal emissive band. The on-orbit performance and uncertainty are averaged from AeroSpace,, NASA, and NOAA/STAR teams.

During the intensive calval, the SDR teams have developed many innovative techniques for characterizing the instrument performance and improving the bias corrections. Numerous SDR processing bugs are fixed and the data quality flags are corrected and monitored at NOAA's instrument long-term monitoring system. The critical SNPP calval tasks have been completed.

(By Dr. F. Weng, [NOAA])

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# Metop-B NOAA Instruments On-Orbit Performance Verification and Cal/Val Test

The Meteorological Operational (METOP)-B spacecraft was launched on September 17, 2012, and the on-board NOAA instruments were activated within a month after the launch. As part of the Initial Joint Polar System (IJPS), the National Environmental Satellite, Data, and Information Service (NESDIS) of the National Oceanic and Atmospheric Administration (NOAA) supports NOAA instrument operation through its Polar-orbiting Operational Environmental Satellites (POES) program. With the collaboration of EUMETSAT, the post-launch tests are performed for on-orbit verification (OV), and calibration and validation (Cal/Val). MetOp-B NOAA instruments (AMSU, AVHRR, and HIRS)

on-orbit verifications (OV) started on September 24, 2012 and the tests in Table 1 have been completed, including nine tests for AMSU, 12 for AVHRR and 12 for HIRS. In phase I, the tests focus on the instrument performance and response verification and were reported in daily meetings. The instrument performance is as expected and the post-launch noise performance meets the specifications, as shown in Figure 1. The phase II Cal/Val tests were performed to enhance the calibration accuracy and data quality. The results were presented and discussed in weekly meetings. NOAA/NESDIS/STAR hosted a review meeting on November 28, 2012, with participants from NOAA, NASA, and EUMETSAT, and the Cal/Val teams and product groups presented their test results. The instrument performance verifications from independent Cal/Val tests and data quality assessments from a variety of products are crucial for the enhancement of the quality of the data and products. The NOAA/STAR product groups have extended the Community Radiative Transfer Model (CRTM) and other product algorithms to MetOp-B NOAA instrument data and established the MetOp-B monitoring system to verify product consistency. The high sensitivity of the selected products to the radiometric calibration and geo-location correction facilitates feedback to the Cal/Val teams. The collaboration of the Cal/Val activities between NOAA and EUMETSAT is very important for Level 1B data exchange and data processing comparisons.

A MetOp-A and MetOp-B inter-comparison with correction of the Bidirectional Reflectance Distribution Function (BRDF) effect has been performed for AVHRR and HIRS visible and near-infrared channels. These two satellites are in the same orbit, one-half orbit time (~50 minutes) apart. Calibration updates for the AVHRR visible and near-infrared channels have been performed and are ready for delivery. To verify the accuracy of the brightness temperature measurements, a MetOp-A and MetOp-B inter-comparison is performed for AVHRR and HIRS infrared channels using the double difference method based on CRTM modeling of radiances. Further tests are also planned to enhance calibration accuracy and data quality, such as AVHRR/IASI and HIRS/IASI intercomparisons for bias investigations.

(By Dr. T. Chang [NOAA]. The tests are performed by NOAA/NESDIS/STAR Cal/Val team, Drs. Fuzhong Weng, Xianqian Wu, Changyong Cao, Tsan Mo, Tiejun Chang, Chengli Qi, and Ding Liang with contributions from NOAA/NESDIS/STAR product groups and collaboration with EUMETSAT) Table 1. On-Orbit (OV) tests for NOAA instruments on MetOp-B

AMSU	HIRS	AVHRR			
A/C Conv. Evaluation	BB temperature measurement	General evaluation of imagery			
Space/Warm View Interference	Dark current restore	Instrument stability and trending			
Instrument Trending	IR channel instrument noise	Clamp stability			
Scanner Accuracy &	VIS channel noise and	IR channel noise and			
Stability	dynamic range	dynamic range			
Optimal Space view position	Calibration slope	VIS channel instrument noise			
Noise measurement (NEΔT)	Calibration intercept	IR calibration slope			
Inter-Satellite Comparison	Assessment by CRTM	Image striping			
Blackbody PRT Temp accuracy	Visible channel assessment	Geo-location verification			
Earth Scene Bias Characterization	Geo-location evaluation	VIS channels calibration			
	Instrument temperature	VIS channels consistency			
	Coherent noise	Stray light			
	Stray Light	IR Radiances Assessment			



Figure 1. Metop-B NOAA instrument noise performance. Top: AMSU noise equivalent differential temperature (NEDT). Middle: HIRS noise equivalent differential radiance (NEDN). Bottom: AVHRR visible channel Signal to Noise Ratio (SNR) and IR channel NEDT.

# Using Variograms to Quantify the Radiometric Stability of Meteosat-7/MVIRI and Metop-A/HIRS by Inter-comparison with Metop-A/IASI

Fundamental Climate Data Records (FCDRs) are long-term data records of calibrated and quality-controlled sensor data designed to allow the generation of homogeneous products that are accurate and stable enough for climate monitoring. The generation of FCDRs from multiple instruments relies on their accurate inter-calibration. Where the calibration is transferred backwards or forwards in time by a single instrument, the long-term radiometric stability of that instrument becomes a direct contribution to the uncertainty in the FCDR.

It is difficult to quantify the long-term stability of an instrument's calibration, based on a time series of comparisons with a reference, because changes to the reference must be accounted for. If the reference is another instrument, its long-term radiometric stability must also be accounted for, as well as any orbital changes, such as drift in equator crossing time, which can alias diurnal calibration variations. If the reference is a Numerical Weather Prediction (NWP) model, we need to account for not only changes to the model itself, but also all the observations it uses and its assimilation system. This limits the application of NWP as a long-term calibration reference, although some of these shortcomings can be addressed by using NWP models to generate reanalysis datasets.

The Metop-A satellite has operated since 2006 in a stabilised sun-synchronous polar orbit where the local 21:30 equator crossing time is held constant. Metop-A carries the Infrared Atmospheric Sounding Interferometer (IASI), which has been shown to have excellent radiometric stability (EUMETSAT Tech Report, 2011) and can provide a good inter-calibration reference against which the stability of other instruments can be assessed.

Metop-A also carries a High-resolution Infrared Sounder (HIRS). Different generations of these instruments have been operated on various polar platforms since 1978, which makes them interesting potential reference instruments for the intercalibration of the infrared channels of geostationary imagers, such as Meteosat. The big advantage of both HIRS and IASI being operated on Metop-A is that it is easy to generate a very large dataset of collocations from their observations.

In this analysis the stability of observations from the HIRS onboard Metop-A, and Meteosat Visible and InfraRed Imager (MVIRI) on-board Meteosat-7, is evaluated against reference observations from the IASI instrument on-board Metop-A. The analysis takes the 2008-2012 time series of biases evaluated for standard scene radiances from the intercomparison of these instruments as described in (Hewison, 2008). The analysis focuses on the "infrared" and "water vapour" channels of MVIRI, which correspond to Channel 8 (~6.5 µm) and Channel 12 (~11.5 µm) of HIRS respectively.

We introduce the concept of the temporal variogram,  $2\gamma_t (\Delta t)$ , which is calculated between brightness temperatures biases,  $\Delta T_b$ , sampled at different intervals,  $\Delta t$ , from an extended time series,  $\Delta T_b(t)$ , following the method outlined in (Hewison, 2013) and (Hewison, 2009):

$$2\hat{\gamma}_{t}(\Delta t) = \frac{1}{n_{i}} \sum_{i} \left[ \Delta T_{b} \left( t_{i} + \Delta t \right) - \Delta T_{b} \left( t_{i} \right) \right]^{2} \quad (1)$$

Figure 1 shows the temporal variograms evaluated for two channels of Metop-A/HIRS using Metop-A/IASI as a reference over periods from 1d to 1000d. These channels were chosen as they are most representative of the "water vapour" and "infrared" channels of Meteosat/MVIRI. Their variograms characteristically increase with time rapidly for periods up to 29 d, which corresponds to the averaging period used to generate the prototype inter-calibration products. Beyond this limit, the variograms of the water vapour channel increase more slowly, reaching  $(2\gamma_t)^{1/2} = 33.8 \pm 2.2$  mK for periods of 1 year. The variograms for the infrared channel show a strong maximum for periods ~6 months, indicating an annual cycle in the time series and reach minima of 9.0±0.6 mK for periods of 1 year, with a further clearly-defined minimum at  $\Delta t=2$  yr.

These results demonstrate that radiometric calibration of Metop-A/HIRS was sufficiently stable over this period that it is unlikely to contribute significantly to the overall uncertainty of the inter-calibration of geostationary imagers compared to uncertainties in the spectral band adjustment. However, these results may not be directly transferable to HIRS on other platforms, which suffer from equator crossing time drift.



**Figure 1** – Temporal variograms  $[(2\gamma_i)^{1/2}]$  calculated as RMS differences in Standard Biases for Ch12 and Ch8 of Metop-A/HIRS calculated with reference to Metop-A/IASI. Vertical lines show periods of 29d and 1yr.

It is interesting to compare the above results with those from a similar analysis of a comparable time series of standard biases from the inter-calibration of Meteosat-7/MVIRI using Metop-A/IASI, based on the algorithm described in (Hewison *et al.*, 2013). The variograms for the water vapour and infrared channels, in Figure 2, show the same characteristic increase for periods from 1 - 29 d. In this case, the water vapour channel shows a clear annual cycle, with a maximum for periods ~6 months, but reaching a minimum of  $(2\gamma_t)^{1/2} = 65.0 \pm 4.1$  mK for  $\Delta t = 1$  yr. However, the infrared channel also shows a twice yearly oscillation, and its variogram reaches  $187\pm12$  mK for  $\Delta t=1$  vr. Both variograms are much higher, both in their nugget value (offset) and in their sill value (maximum), than those of their counterpart channels on HIRS, confirming that using HIRS as an intercalibration reference could improve FCDRs derived from Meteosat-7. The higher nugget value can be explained by uncertainties caused by collocation errors between the MVIRI and IASI observations. The high sill value indicates that the water vapour and infrared channels of MVIRI drift faster from IASI that the corresponding HIRS channels.



Figure 2 – As Figure 1, but for Water Vapour (left) and InfraRed (right) channels of Meteosat-7/MVIRI.

In conclusion, this analysis indicates that the Metop-A/HIRS may serve as stable reference for the re-calibration of the water vapour and infrared channels on-board geostationary satellites. The fact that the MVIRI channels reveal a larger drift than the HIRS channels suggests that MVIRI may not be stable enough to serve as bridge between different NOAA satellites.

(By Drs. T. J. Hewison and R. Roebeling, [EUMETSAT])

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# The Development of AMSU FCDR's and TCDR's for Hydrological Applications

This NOAA/NCDC/CDR Program project will properly characterize the AMSU and MHS sensors to generate FCDR's from the Advanced Microwave Sounding Unit (AMSU) and Microwave Humidity Sounder (MHS): channels 1, 2, 3 and 15 on AMSU-A and all five channels on AMSU-B and MHS. The FCDR's will then be used to generate TCDR's for hydrological cycle products such as precipitable water, rain rate and snow cover, etc. By project completion, an 11-year (2000 – 2010) AMSU/MHS CDR from NOAA POES satellites (NOAA-15 to -19) and EUMETSAT Metop-A satellite is anticipated. This three-year project is currently in its final year and has met many of its major milestones. Two advances are described below: geolocation correction and scan bias correction for AMSU-A window channels.

The accuracy of sensor geolocation is affected by errors in satellite attitude (pitch, roll, and yaw, or PRY), sensor mounting, and satellite clock offset, etc. Geolocation error can be a significant source of bias in satellite measurements of geographical areas with sharp T<sub>b</sub> gradients. In this project, geolocation error was quantified with the difference between ascending and descending brightness temperatures ( $\Delta T_{\rm b}$ ) along coastlines. With the existence of geolocation error  $\Delta T_{b}$  along the coastlines becomes the difference between land and ocean Tb's. This difference is quite significant for surface sensitive frequencies due to the large difference between land and water emissivity. The PRY corrections were derived by tuning satellite attitudes (PRY) until the number of coastal pixels exceeding a preset AT b threshold was minimized (Moradi et al., 2012). New geographical coordinates, scan angle, and local zenith angles were then calculated using the new attitudes. The results show that NOAA-15 AMSU-A2 sensor is mounted about 1.2 degrees negative cross-track, and about 0.5 degree negative along-track; NOAA-16 AMSU-A1 and -A2 are mounted about 0.5 degree negative along-track, and NOAA-18 AMSU-A2 is mounted more than 1 degree negative along-track. Figure 1 compares the  $\Delta T_{\rm b}$  before and after geolocation correction for NOAA-15 AMSU-A 23.8 GHz.



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Figure 1. Difference between ascending and descending brightness temperatures from NOAA-15 AMSU-A 23.8 GHz channel, (a) before correction; and (b) after correction.

AMSU-A window channels are known for their cross scan asymmetry issues (Weng et al., 2003). If not corrected, the bias will have a severe impact on the generation of geophysical products. Several approaches were used in this project to quantify the scan biases for AMSU-A channels 1, 2, 3, and 15 (respectively at 23.8, 31.4, 50.3, and 89 GHz). These include vicarious cold reference (VCR) over ocean, VCR over certain land target areas in the polar regions, vicarious hot reference (VHR) over a target area in Amazon, and Most Probable Value (MPV) over ocean. MPV is defined as narrow ranges of modeled sea surface temperature, precipitable water, and wind speed that have the highest frequency of occurrence in the data set. Since the scan bias appears to be T<sub>b</sub> dependent, different methods were employed to cover the dynamic ranges of the  $T_b$ 's. The coldest  $T_b$  for channels 1 and 2 are over ocean while for channels 3 and 15 they are over land. Consequently, VCR over ocean was used in the bias characterization for channels 1 and 2, and VCR over land for channels 3 and 15. The bias patterns appeared to be stable for the same satellite through the several years of data examined, but were quite dissimilar for the different satellites. Based on the bias characterization, a three-point approach is developed to correct the scan bias for each channel at each beam position (Yang et al., 2012). The method appears to remove the scan bias effectively for AMSU-A window channels both at brightness temperature level and at product level. Figure 2 (below) compares the Cloud Liquid Water (CLW) retrieved using the AMSU-A channels 1 and 2 T<sub>b</sub>'s before and after scan bias correction. The asymmetry in CLW caused by the scan bias in  $T_b$  was clearly removed after the bias correction especially along the limbs.

(by H. Meng, R. Ferraro, W. Yang, I. Moradi, and C. Divaraj, [NOAA])

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Figure 2. Cloud liquid water retrieved from AMSU-A channels 1 and 2 measurements before (a) and after (b) scan bias correction.

## News in this Quarter

## Two GSICS GEO-LEO IR Correction Products in Pre-operational Phase

On behalf of the GSICS Coordination Center (GCC) and GSICS Product Acceptance Team (GPAT), I am pleased to announce that the EUMETSAT GSICS GEO-LEO IR intercalibration correction product for Meteosat/SEVIRI and the NOAA GSICS GEO-LEO IR inter-calibration correction product for GOES Imager are now in pre-operational phase. These two products have completed the required documentation including the Algorithm Theoretical Basis Document (ATBD), uncertainty analysis and other ancillary reports. The software for these two products is running stably and reproducibly with minimal code changes expected. The software for the NOAA product has been maintained with the subversion control package. The product data availability and metadata have also been running reliably and stably at the GSICS data servers over the past years. We have received some positive feedback from product users and continue to encourage user comments. Per the GSICS Procedure for Product Acceptance (GPPA) (https://gsics.nesdis.noaa.gov/wiki/Development/GppaWorkflow) SCOPE-CM and the maturity model

(<u>http://www.agu.org/pubs/crossref/2012/2012EO440006.shtml</u>), these two products are now in pre-operational phase, on the way to operations.

Users can access to the products and the associated documents freely at the GSICS product catalog at <u>http://www.star.nesdis.noaa.gov/smcd/GCC/ProductCatalog.php</u>, which is also linked to the WMO GSICS portal website.

(by F. Yu, [GCC])

#### Current Status of Meoteosat-9 and -10

During 2012, Met9 was located at  $0^{\circ}$  and provided a Full Earth Scan (FES) service of the earth, with images every 15 minutes. It also provided a Low Rate Information Transmission (LRIT) direct service, Data Collection Platform (DCP) service, and Search and Rescue (SAR) service.

MSG3 (Met10) was launched on 5 July 2012 and handed over by ESOC to EUMETSAT on 16 July 2012. The spacecraft, located at 3.4° west, has successfully completed commissioning. MSG3-SEVIRI was successfully switched ON with a first image on 7 August 2012 and MSG3-GERB was successfully switched ON with a first image on 10 August 2012. The MSG-SAR payload entered operation in September 2012. MSG has been disseminating test Image and Product data to users since late October 2012 and was renamed Met10 in mid-December 2012. Met10 commenced an operational FES service of the earth in parallel with Met9 on 19-December 2012. During this two month parallel operation, Met10 will take over the  $0^{\circ}$  FES service as the prime spacecraft.

(By T. Hewison [EUMETSAT])

# NetCDF Formats from the EUMETSAT Data Centre

The EUMETSAT Data Centre is offering the NetCDF format as a common delivery format for Metop-A and in the near future, Metop-B level1 and 2 products. In the scope of GSICS, this is good news as the products' NetCDF formats follow the same GSICS NetCDF recommendations *i.e.* product filenames conform to the WMO file naming conventions, adopting Climate and Forecast (CF) conventions for "Coordinate Types", and using CF standard names and units where applicable.

Users are encouraged to use these product formats in future GSICS activities and provide feedback to EUMETSAT via <u>ops@eumetsat.int</u>. More information regarding these products can be found under the following URL:

http://www.eumetsat.int/Home/Main/DataAccess/EUMETSA TDataCentre/SP\_20111027152034196?l=en

(By P. Miu, [EUMETSAT])

# Just Around the Bend ...

## **GSICS-Related Meetings**

- The annual GRWG and GDWG joint meeting will be held in Williamsburg, Virginia, USA on 4-8 March 2013.
- The 5<sup>th</sup> GSICS Users' Workshop will take place in conjunction with the first NOAA Satellite Conference which will be held in College Park, Maryland, USA, April 8-12, 2013. Remote access to the users' workshop will be available via Webex.
- The first NOAA Satellite Conference will be held at the NOAA Center for Weather and Climate Prediction (NCWCP), College Park, USA April 8-12, 2013.

### **GSICS** Publications

- Gowarda, S., et al., 2012: Complementarity of ResourceSat-1 AWiFS and Landsat TM/ETM+ sensors. *Remote Sensing of Environment*, **123**, 41-56.
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